

Stochastic Modeling in Systems Biology



Yang Cao



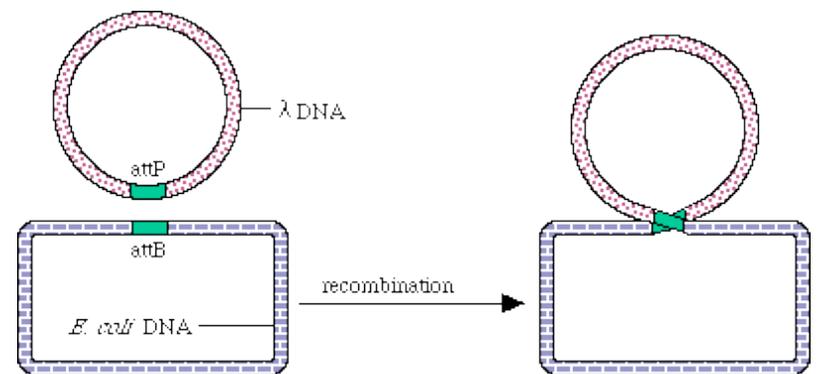
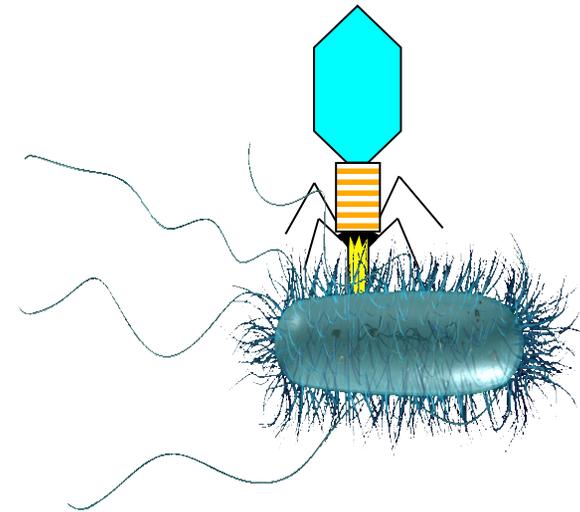
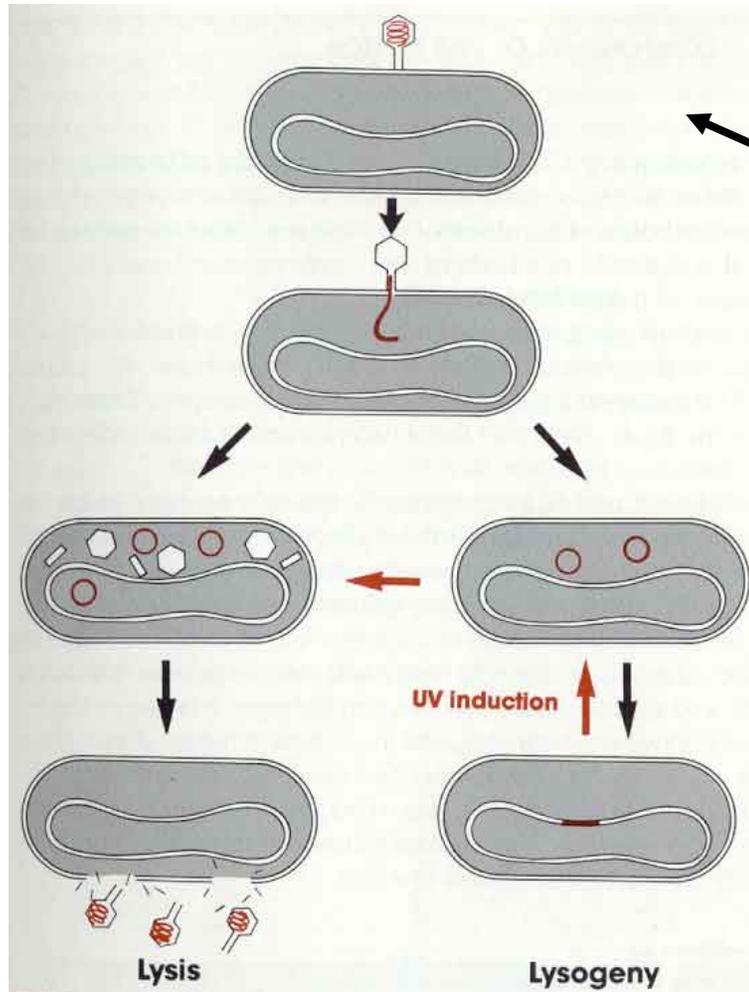
Department of Computer Science





Lambda-phage affected E. Coli

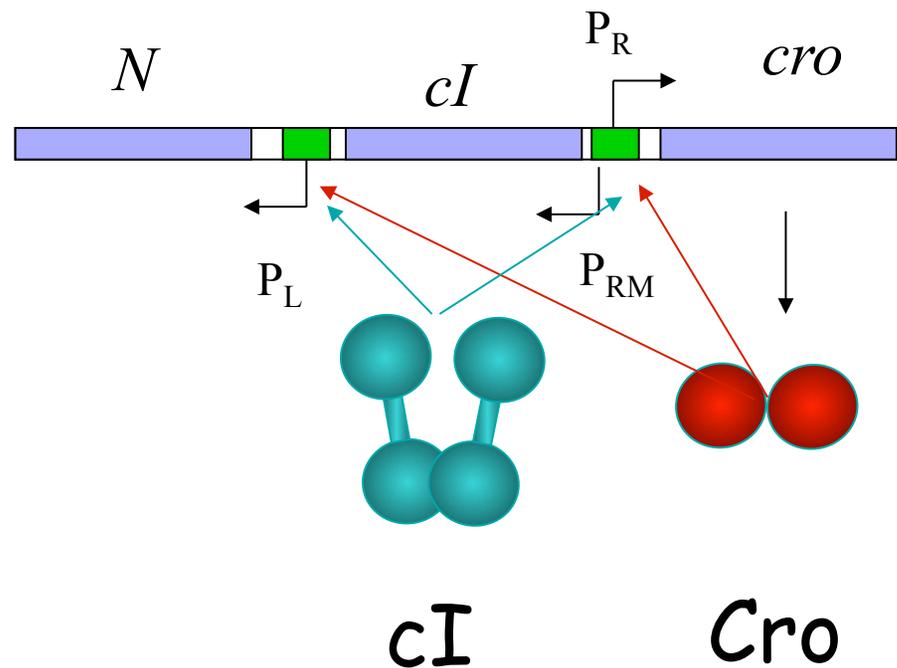
Computational Science and Engineering





Highlight the lambda phage regulation

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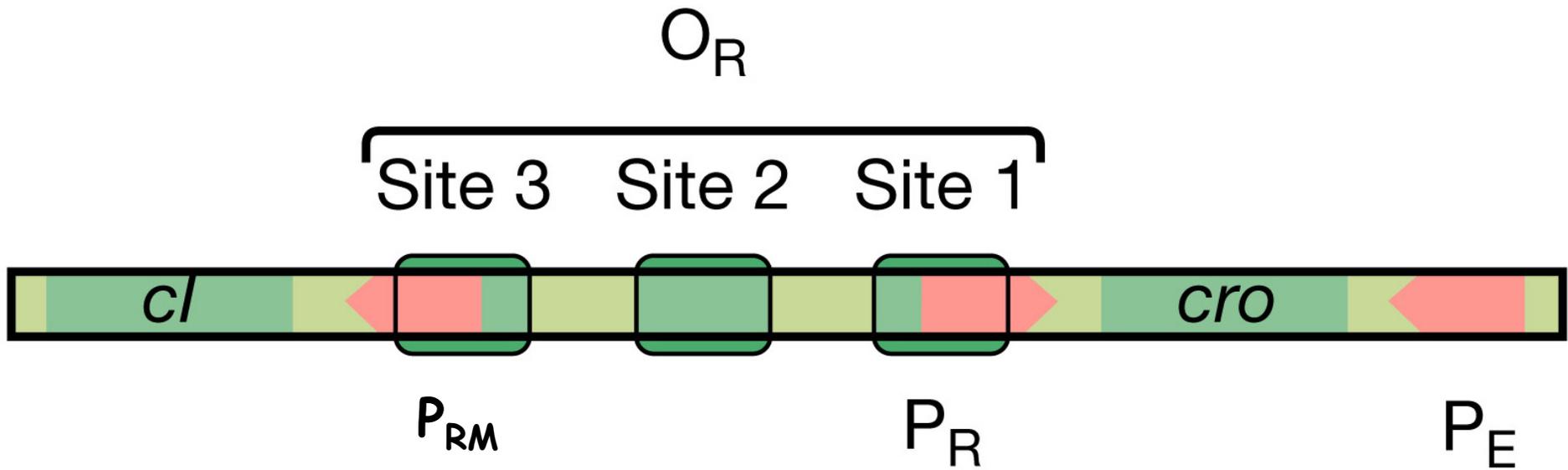
If cI wins, P_R and P_L are repressed and the cell enters lysogeny

If Cro wins, P_{RM} is repressed and the cells enters the lytic cycle

A close up on the right promoter- operator region



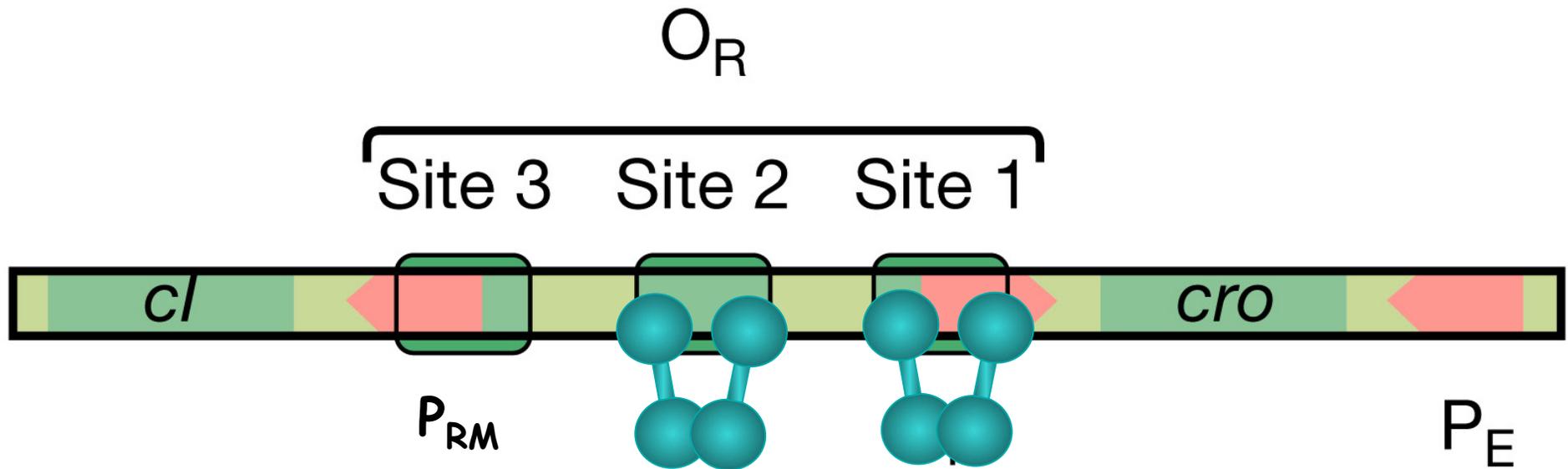
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cI must bind to OR1 to repress rightwards transcription

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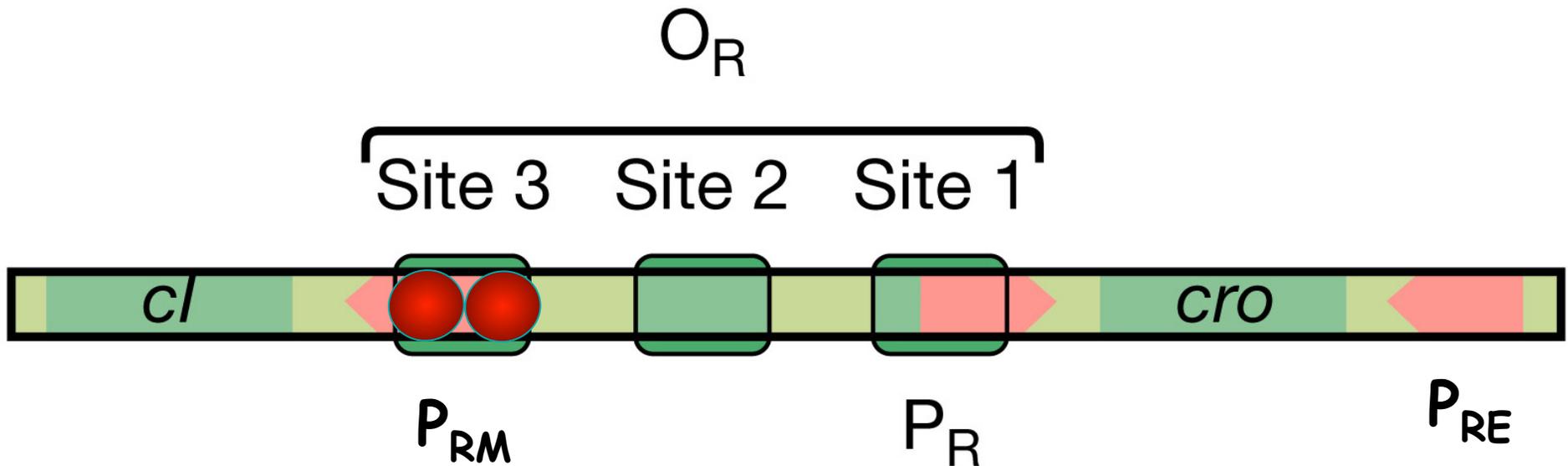


cI represses P_R - shuts off *cro*

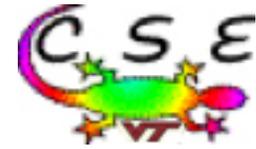
cI activates P_{RM} - expression of *cI*

Cro must bind to OR3 to repress expression of repressor by P_{RM}

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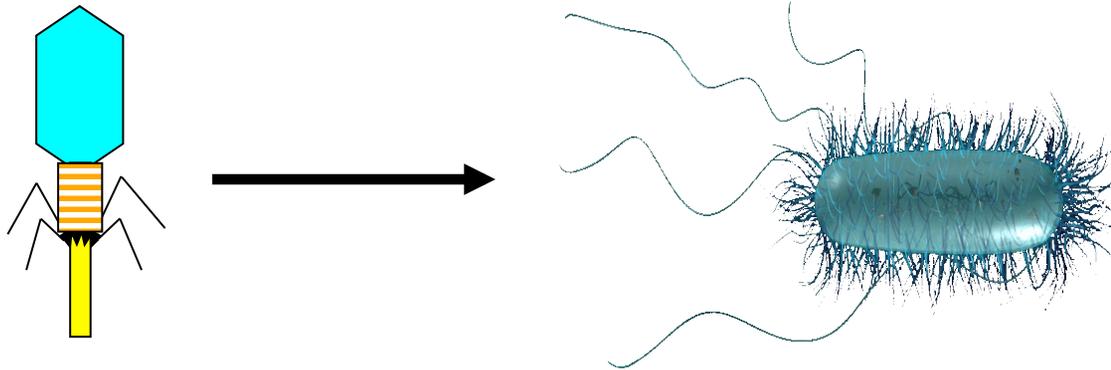


Cro represses P_{RM} - shuts off cI expression

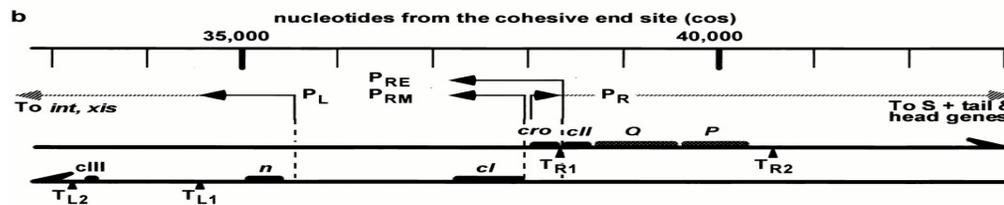
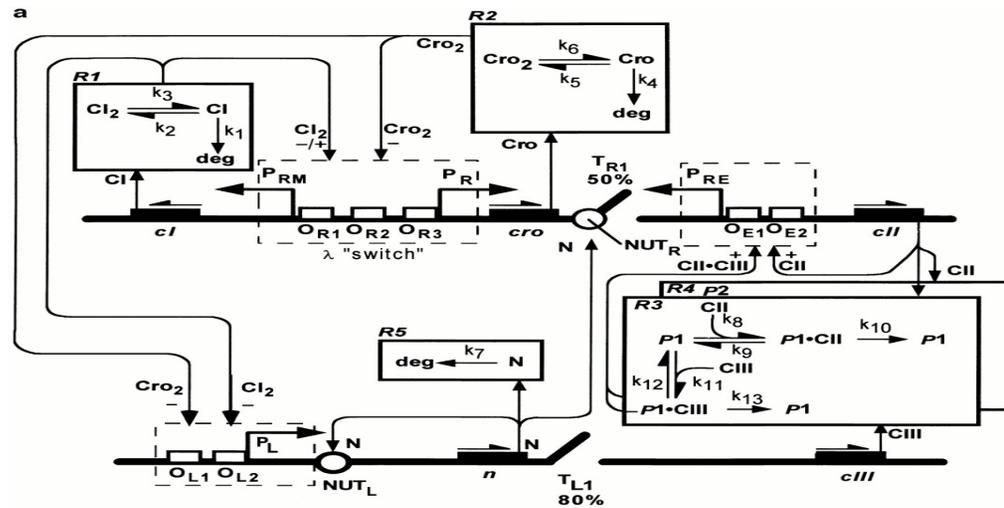


Lambda-phage affected E. Coli

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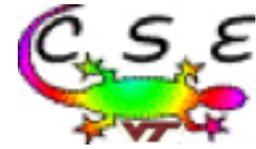
Lysis
Lysogeny



Stochastic effects play an important role in lytic/lysogenic decision network

Arkin et al. 1997, 1998

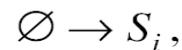
Chemical Reacting System



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A Chemically Reacting System

- Molecules of N *chemical species* S_1, \dots, S_N .
 - In a volume Ω , at temperature T .
 - Different conformations or excitation levels are considered different species if they behave differently.
- M “elemental” *reaction channels* R_1, \dots, R_M .
 - each R_j describes a *single instantaneous physical event*, which changes the population of at least one species. Thus, R_j is either



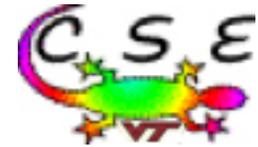
or



or



A General Question



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Question: How does this system evolve in time?

The traditional answer, for *spatially homogeneous* systems:

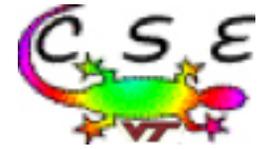
“According to the *reaction rate equation* (RRE).”

- A set of coupled, first-order ODEs.
- Derived using ad hoc, phenomenological reasoning.
- Implies the system evolves *continuously* and *deterministically*.
- Empirically accurate for large systems.
- Often not adequate for small systems.

* * *

The question deserves a more carefully considered answer.

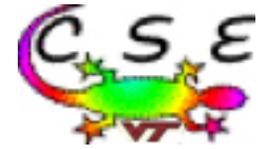
Molecular Dynamics



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Molecular Dynamics (MD)

- **The most exact way** of describing the system's evolution.
- Tracks the position and velocity of *every* molecule in the system.
- Simulates *every* collision, *non-reactive* as well as *reactive*.
- Shows changes in species populations and their spatial distributions.
- **But . . .** it's *unfeasibly slow* for nearly all realistic systems.



Some Facts about Cell (got from Mark Paul)

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Characteristic Length Scales

The radius of a single cell,

$$R_{cell} \approx 5\mu\text{m}$$

The radius of a water molecule,

$$R_{water} \approx 0.3\text{nm}$$

The volume of a single cell,

$$V_{cell} \approx \frac{1}{2}\text{pL}$$

If a cell only contained water, there would be,

$$N_{water} \approx 4 \times 10^{15} \text{ molecules}$$

Characteristic Time Scales

Mean time for cell division,

$$t_{cell} \approx 100\text{min}$$

At room temperature the equipartition of energy yields the mean velocity of a molecule to be,

$$\frac{3}{2}k_B T = \frac{1}{2}mv^2$$

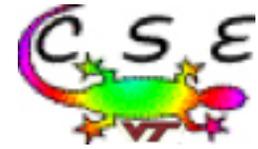
Using this, the mean time between collisions is,

$$t_c \lesssim 1\text{ps}$$

The number of collisions to occur per cell cycle is then,

$$N \approx 3 \times 10^{31}$$

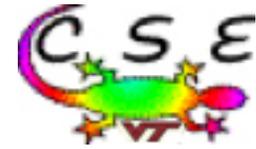
Molecular dynamics is out!



A **great simplification occurs** *if* successive *reactive* collisions tend to be separated in time by *very many non-reactive* collisions.

- The overall effect of the non-reactive collisions is to *randomize* the positions of the molecules (and also maintain thermal equilibrium).
- The non-reactive collisions merely serve to keep the system **well-stirred** or **spatially homogeneous** for the reactive collisions.
- Can describe the *state* of the system by $\mathbf{X}(t) \triangleq (X_1(t), \dots, X_N(t))$,

$X_i(t) \triangleq$ the *number* of S_i molecules at time t .



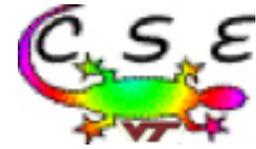
But this *well-stirred simplification*, which . . .

- ignores the non-reactive collisions,
- *truncates* the definition of the system's state,

. . . comes at a price:

$X(t)$ must be viewed as a *stochastic process*.

- In fact, *the system was never deterministic to begin with!*
Even if molecules moved according to classical mechanics . . .
 - monomolecular reactions always involve QM.
 - bimolecular reactions require collisions, whose extreme sensitivity to initial conditions renders them essentially random.
 - bimolecular reactions usually involve QM too.
- But stochastic processes can be handled.

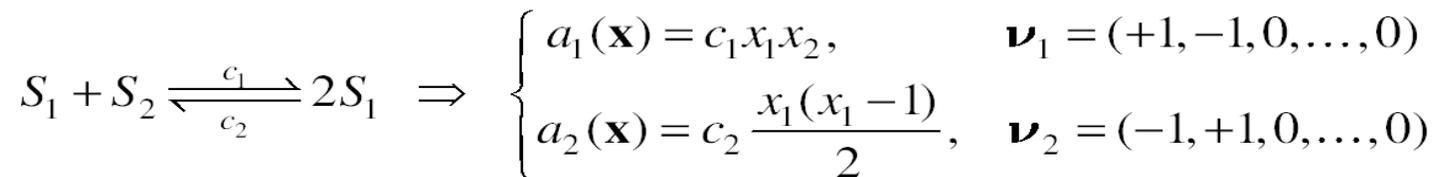


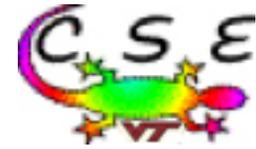
Characteristics of the System

For well-stirred systems, each R_j is completely characterized by:

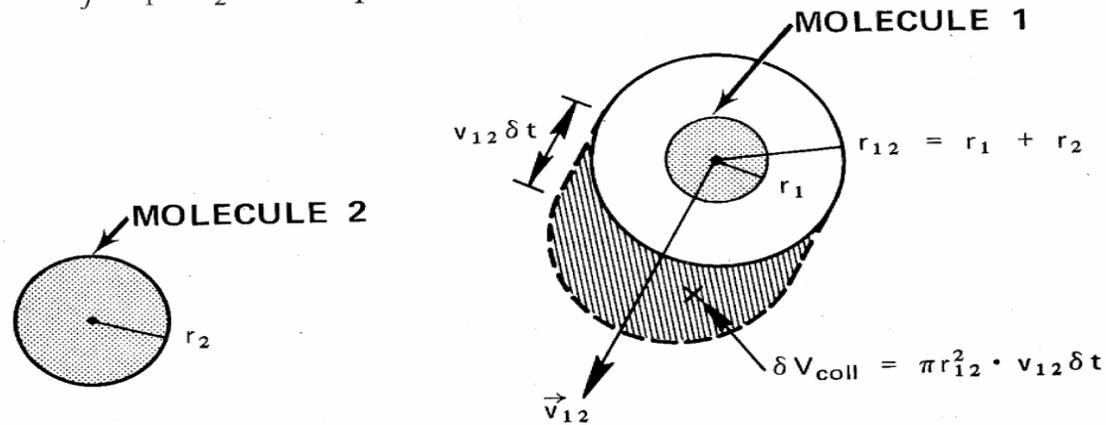
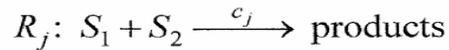
- a **propensity function** $a_j(\mathbf{x})$: Given the system in state \mathbf{x} , $a_j(\mathbf{x}) dt \triangleq$ the **probability** that one R_j event will occur in the next dt .
 - The existence and form of $a_j(\mathbf{x})$ follow from kinetic theory.
 - $a_j(\mathbf{x})$ is roughly equal to, but is **not** derived from, the RRE “rate”.
- a **state change vector** $\mathbf{v}_j \equiv (v_{1j}, \dots, v_{Nj})$: $v_{ij} \triangleq$ the **change** in the number of S_i molecules caused by one R_j event.
 - R_j induces $\mathbf{x} \rightarrow \mathbf{x} + \mathbf{v}_j$. $\{v_{ij}\} \equiv$ the “stoichiometric matrix.”

E.g.,





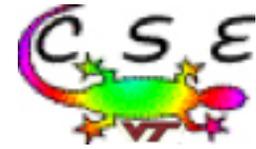
One Reasoning (but not a proof)



$$\left\{ \left(\frac{(\bar{v}_{12} dt)(\pi r_{12}^2)}{\Omega} \right) \times \exp(-E_j/k_B T) \right\} \times x_1 x_2 = \underbrace{\left(\frac{\bar{v}_{12} \pi r_{12}^2}{\Omega} \exp(-E_j/k_B T) \right)}_{c_j} x_1 x_2 dt$$

Probability that a randomly chosen S_1 - S_2 pair will react according to R_j in next dt .

$$\underbrace{\left(c_j x_1 x_2 \right)}_{a_j(\mathbf{x})} dt \triangleq a_j(\mathbf{x}) dt$$



Propensity Function vs the Reaction Rate

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• Difference

- Propensity function describes the probability while reaction rate describes the changing rate.
- Propensity functions are defined based on population of species while the reaction rates are defined based on the concentration of species

• Connection

- For simple system, they have similar format.

For reaction like $A \rightarrow B$

- Reaction rate: $k[A]$

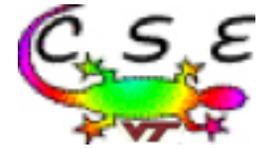
- Propensity function $c x_A$ and we have $c = k$

- For reaction like $A + B \rightarrow C$

- Reaction rate $k[A][B]$

- :

- Propensity function $c x_A x_B$ and we have $c = k / V$



Chemical Master Equation

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Two exact, rigorously derivable consequences . . .

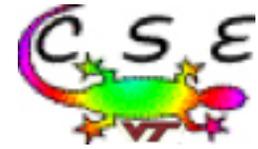
- 1. The *chemical master equation* (CME):

$$\frac{\partial P(\mathbf{x}, t | \mathbf{x}_0, t_0)}{\partial t} = \sum_{j=1}^M \left[a_j(\mathbf{x} - \boldsymbol{\nu}_j) P(\mathbf{x} - \boldsymbol{\nu}_j, t | \mathbf{x}_0, t_0) - a_j(\mathbf{x}) P(\mathbf{x}, t | \mathbf{x}_0, t_0) \right].$$

- Gives $P(\mathbf{x}, t | \mathbf{x}_0, t_0) \triangleq \text{Prob}\{\mathbf{X}(t) = \mathbf{x}, \text{ given } \mathbf{X}(t_0) = \mathbf{x}_0\}$ for $t \geq t_0$.
- The CME follows from the *probability* statement

$$P(\mathbf{x}, t + dt | \mathbf{x}_0, t_0) = P(\mathbf{x}, t | \mathbf{x}_0, t_0) \times \left[1 - \sum_{j=1}^M (a_j(\mathbf{x}) dt) \right] \\ + \sum_{j=1}^M P(\mathbf{x} - \boldsymbol{\nu}_j, t | \mathbf{x}_0, t_0) \times (a_j(\mathbf{x} - \boldsymbol{\nu}_j) dt).$$

- But it's practically always *intractable* (analytically and numerically).

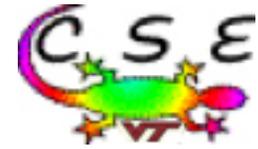


- **2.** The *stochastic simulation algorithm* (SSA):
- A procedure for constructing *sample paths* or *realizations* of $\mathbf{X}(t)$.
 - Approach: Generate the time to the *next* reaction and the index of that reaction.
 - Theoretical justification: With $p(\tau, j|\mathbf{x}, t)$ defined by
$$p(\tau, j|\mathbf{x}, t) d\tau \triangleq \text{prob, given } \mathbf{X}(t) = \mathbf{x}, \text{ that the next reaction will occur in } [t+\tau, t+\tau+d\tau), \text{ and will be an } R_j,$$

can prove that

$$p(\tau, j|\mathbf{x}, t) = a_j(\mathbf{x}) \exp(-a_0(\mathbf{x})\tau), \quad \text{where } a_0(\mathbf{x}) \triangleq \sum_{j'=1}^M a_{j'}(\mathbf{x}).$$

This implies that the *time* τ to the next reaction event is an exponential random variable with mean $1/a_0(\mathbf{x})$, and the *index* j of that reaction is an integer random variable with prob $a_j(\mathbf{x})/a_0(\mathbf{x})$.



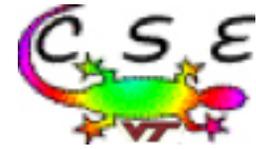
Direct Method (DM)

Computational Science and Engineering

The “Direct” Version of the SSA

1. With the system in state \mathbf{x} at time t , evaluate $a_0(\mathbf{x}) \triangleq \sum_{j'=1}^M a_{j'}(\mathbf{x})$.
2. Draw two unit-interval uniform random numbers r_1 and r_2 , and compute τ and j according to
 - $\tau = \frac{1}{a_0(\mathbf{x})} \ln \left(\frac{1}{r_1} \right)$,
 - $j =$ the *smallest integer* satisfying $\sum_{j'=1}^j a_{j'}(\mathbf{x}) > r_2 a_0(\mathbf{x})$.
3. Replace $t \leftarrow t + \tau$ and $\mathbf{x} \leftarrow \mathbf{x} + \mathbf{v}_j$.
4. Record (\mathbf{x}, t) . Return to Step 1, or else end the simulation.

(Inverse Generation Method)



First Reaction Method (FRM)

- A different but equivalent simulation method for SSA
- Generate a firing time for each reaction channel

$$\tau_j = \frac{1}{a_j(x)} \ln\left(\frac{1}{r_j}\right),$$

- Find the minimum of all the firing time and throw off all the others

$\mu =$ the index satisfying

$$\tau_\mu = \min_j \tau_j,$$

- In theory this method is equivalent to the DM
- The biggest concern is the computational cost



Next Reaction Method (NRM)

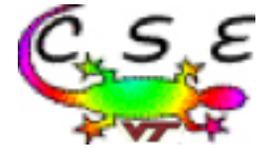
- Derived by Gibson and Bruck 2000
- Keep the randomly generated firing time if the corresponding propensity function is not changed (Use a dependent graph (DG) to achieve this goal)
- Use absolute time instead of relative time

$$\tau_\alpha = \frac{1}{a_\alpha(t)} \log \left(\frac{1}{r} \right) + t.$$

- Reuse the unapplied uniform random number

$$\tau_\alpha \leftarrow \left(a_{\alpha,old} / a_{\alpha,new} \right) (\tau_\alpha - t) + t.$$

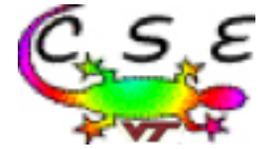
- Use a priority tree (heap array) to conduct the search
- Only need to generate one uniform random number each step
- The computational cost to maintain the data structure can be hug!



Optimized Direct Method (ODM)

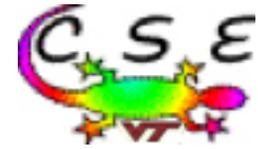
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- **Analyze the time profile of DM and NRM. Conclude that the data structure maintaining cost is very high for most problems.**
- **Sort the reaction channel so that more frequent firing reaction channels have smaller index. (Run a few pre-simulation to collect info for the problem.)**
- **If necessary, use the dependent graph (DG) to avoid recalculating propensity functions for reaction channels that are not affected by the last reaction.**
- **Efficient for multiscale problem**
- **Among all test problems we tried, ODM is faster than NRM.**



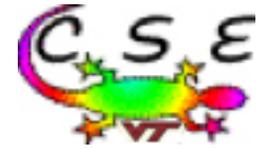
Sorted Direct Method (SDM)

- The pre-simulation procedure is troublesome for an automatic code.
- The index should be changed dynamically during the simulation
- Bubble sorting technique
If a reaction just fired, move its index one step up. After a while, the reaction index will be automatically well-sorted.
- Less (but almost the same) efficient than ODM but much easier to code and maintain.



The SSA . . .

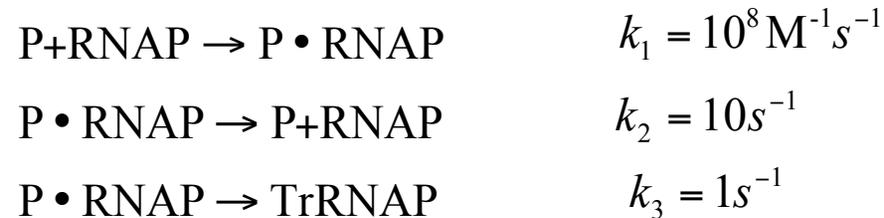
- Is *exact*.
 - Is equivalent to (but is not derived from) the CME.
 - Does *not* entail approximating “ dt ” by “ Δt ”.
 - Is *procedurally simple*, even when the CME is intractable.
-
- ***Remains too slow for most practical problems:*** Simulating *every* reaction event, *one* at a time, is just too much work if any reactant is present in very large numbers.



A Model for Prokaryotic Gene Expression

Computational Science and Engineering

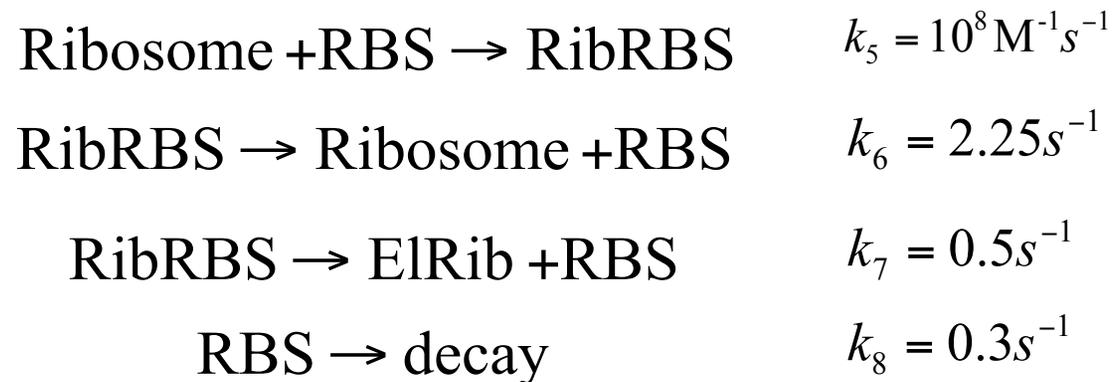
1. Transcription Initiation (the binding and initiation)



2. Elongation (RBS is available before elongation terminates)



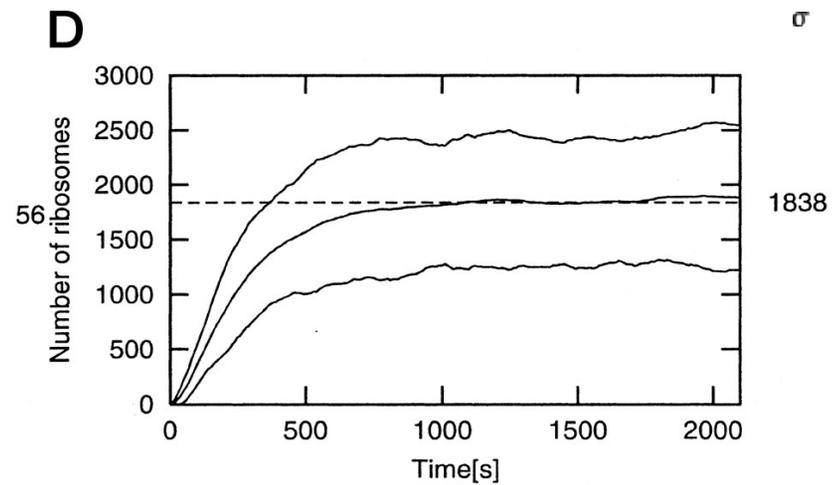
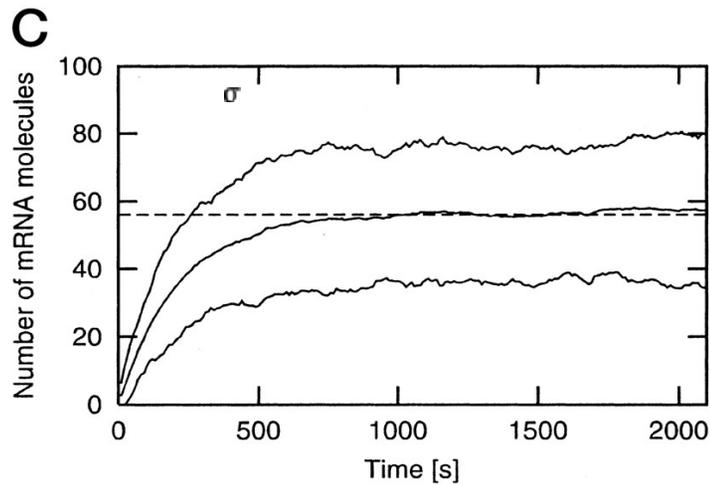
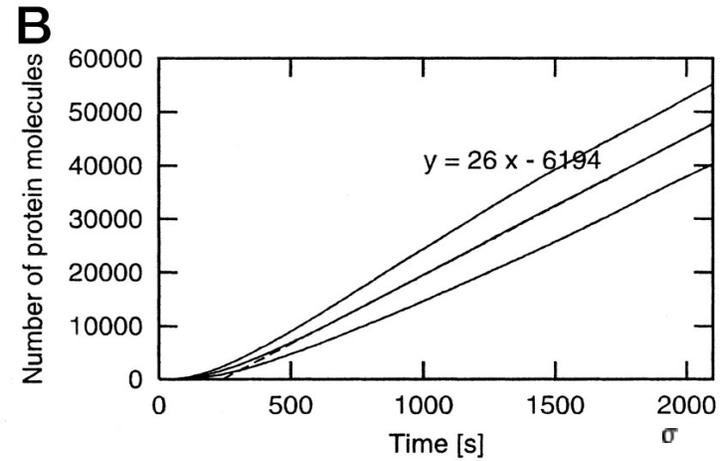
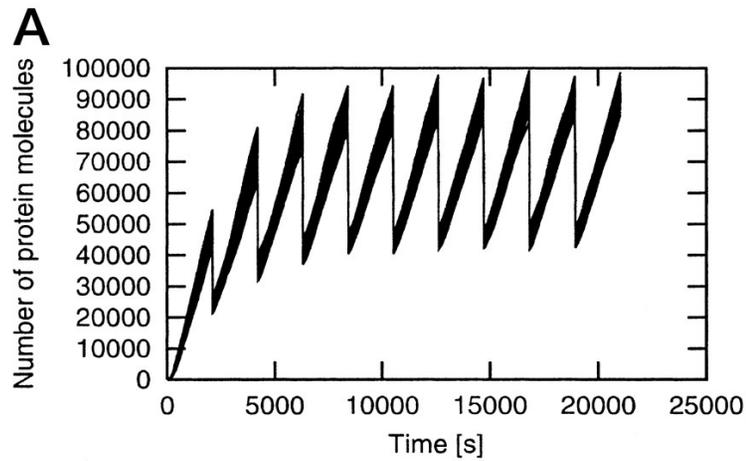
3. Translation Initiation



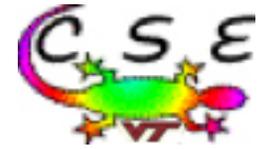
4. Elongation



Simulation Results

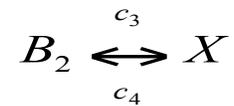
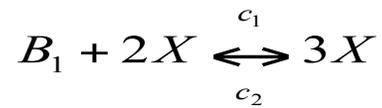


Schlögl Model and Error Measurement



Computational Science and Engineering

- Reactions:



- Propensity functions:

$$a_1(x) = \frac{c_1}{2} N_1 x(x-1),$$

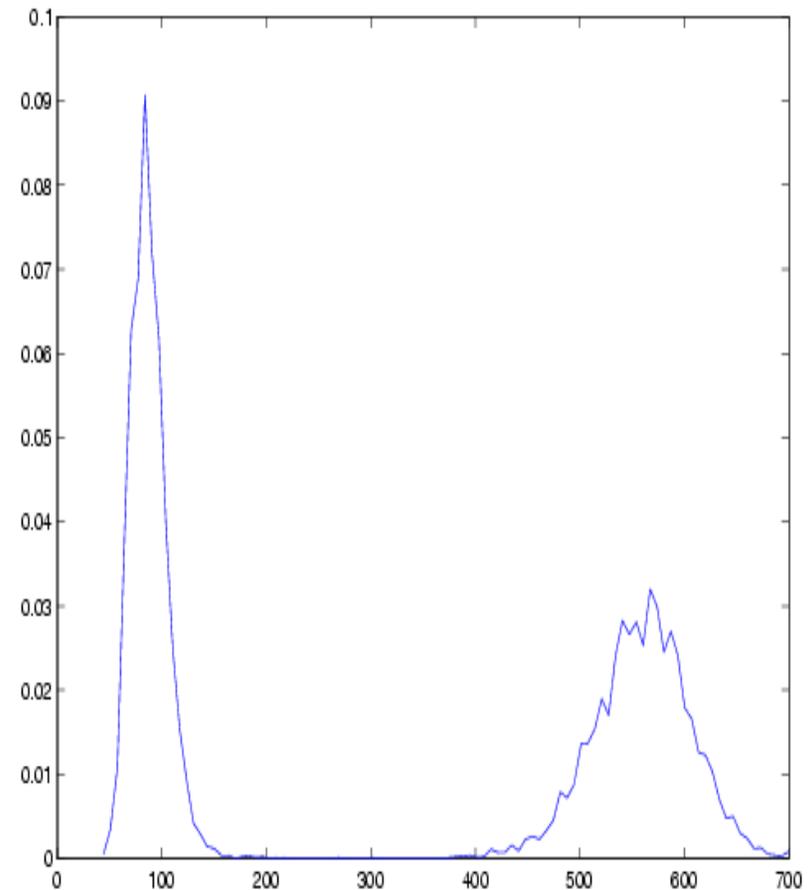
$$a_2(x) = \frac{c_2}{6} x(x-1)(x-2),$$

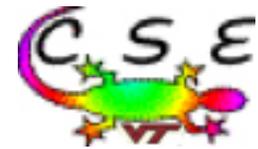
$$a_3(x) = c_3 N_2,$$

$$a_4(x) = c_4 x.$$

- Bistable distribution

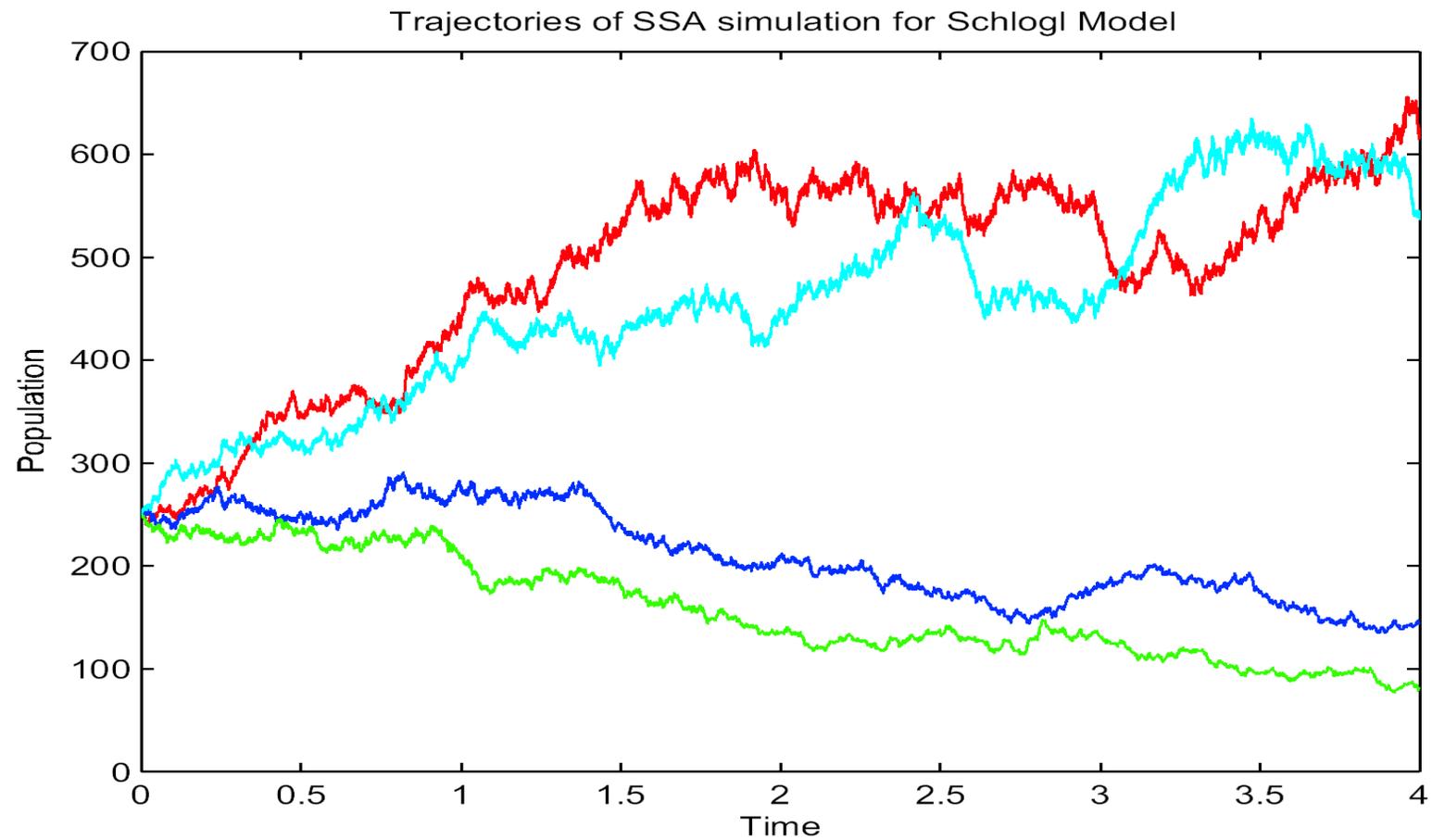
Histogram plot of the state
in Schlögl model

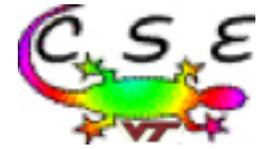




Single Simulation Results

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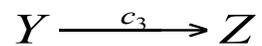
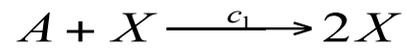




Stochastic Modeling

Computational Science and Engineering

Lotka reactions:



Lead to ODEs

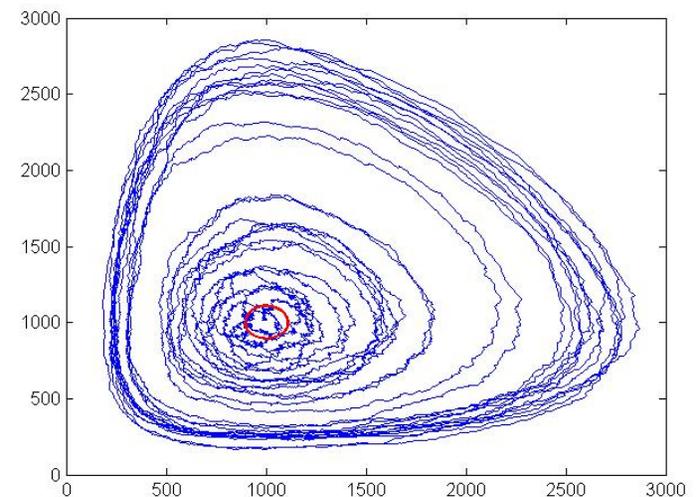
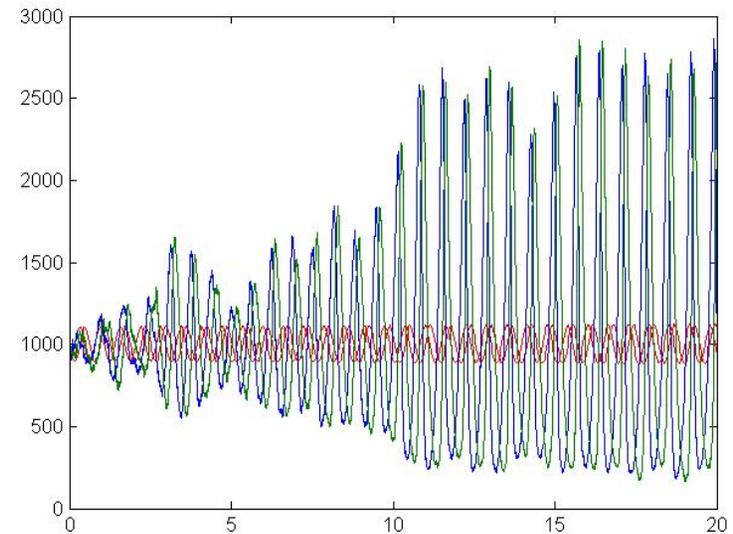
$$\begin{cases} \dot{x} = (c_1 A - c_2 y)x \\ \dot{y} = (-c_3 + c_2 x)y \end{cases}$$

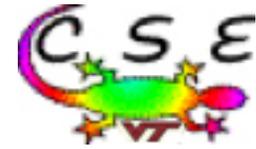
The stochastic simulation generates interesting

$$c_1 A = 10,$$

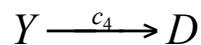
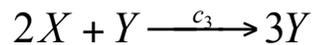
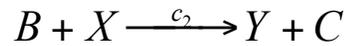
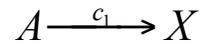
$$c_2 = 0.01,$$

$$c_3 = 10$$





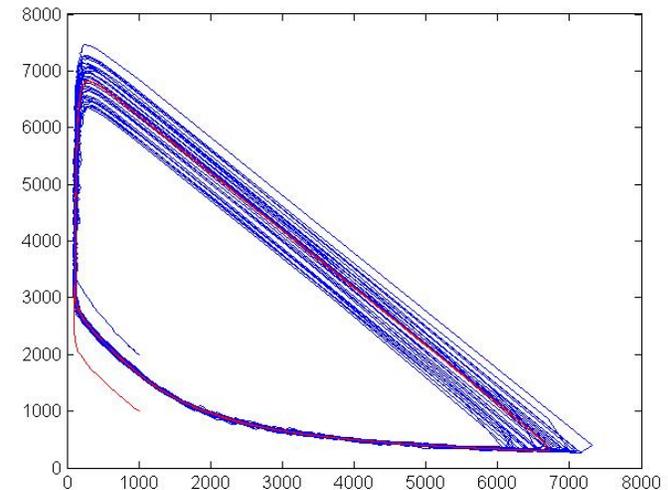
Brusselator



$$\begin{aligned} c_1 A &= 5000, \\ c_2 B &= 50, \\ c_3 &= 0.00005, \\ c_4 &= 5. \end{aligned}$$

Lead to ODEs

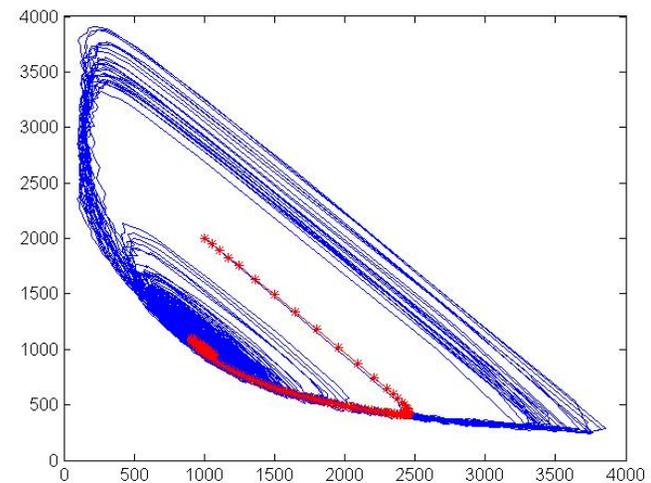
$$\begin{cases} \dot{x} = c_1 A - c_2 B y + \frac{c_3}{2} x^2 y - c_4 x \\ \dot{y} = c_2 B y - \frac{c_3}{2} x^2 y \end{cases}$$



**Bifurcation happens
around the condition:**

$$\frac{2c_2 B}{c_3} = \frac{(c_1 A)^2}{c_4^2} + \frac{2c_4}{c_3}$$

$$\begin{aligned} c_1 A &= 5000, \\ c_2 B &= 50, \\ c_3 &= 0.0001, \\ c_4 &= 5. \end{aligned}$$



J. Tyson's 1973, 1974 paper



Break the Assumption

Computational Science and Engineering

Spatially Inhomogeneous Systems

- Spatial homogeneity does *not* require that all equal-size subvolumes of Ω contain the same number of molecules!
- The CME and SSA require only that the center of a *randomly* chosen S_i molecule be found with *equal probability* at any point inside Ω .
- A system consisting of only one molecule can be “well-stirred”.

➤ **But the well-stirred assumption can't always be made.**

In that case, we must do something different; however, the traditional *reaction-diffusion equation* (RDE) is *not always* the answer:

- The RDE (like the RRE) is *continuous* and *deterministic*.
- It assumes that each $d\Omega$ contains a spatially homogeneous mixture of *infinitely* many molecules.
- Not the case in most cellular systems, where spatial inhomogeneity arises not from slow mixing but rather from compartmentalization caused by highly heterogeneous structures within the cell.