

Implementing Subprograms

In Text: Chapter 9

1

Outline

- Activation records
- Accessing locals
- Accessing nonlocals (static scoping)
 - Static chains
 - Displays
- Implementing blocks
- Accessing nonlocals with dynamic scoping

■ Chapter 9: Implementing Subprograms ■ 2

Implementing Subprograms

- The subprogram call and return operations of a language are together called its **subprogram linkage**
- **First, let's look at implementing FORTRAN 77 subprograms**

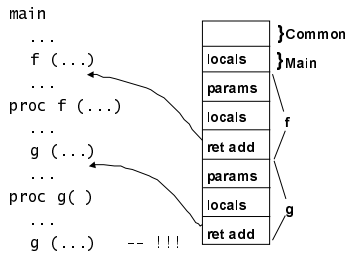
■ Chapter 9: Implementing Subprograms ■ 3

Implementing FORTRAN 77 Subprogs

- Call Semantics:
 - Save the execution status of the caller
 - Carry out the parameter-passing process
 - Pass the return address
 - Transfer control to the callee
- Return Semantics:
 - If pass-by-value-result is used, move current values of parameters to their corresponding actuals
 - If it is a function, move return value to a place the caller can get it
 - Restore the execution status of the caller
 - Transfer control back to the caller
- Required Storage:
 - Status information of the caller, parameters, return address, and functional value (if it is a function)

FORTRAN Activation Info

- can allocate all memory statically



Activation Records

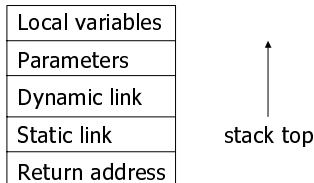
- The format, or layout, of the noncode part of an executing subprogram is called an **activation record (AR)**
- An **activation record instance (ARI)** is a concrete example of an activation record (the collection of data for a particular subprogram activation)
- FORTRAN 77 subprograms can have no more than one activation record instance at any given time
- The code of all of the program units of a FORTRAN 77 program may reside together in memory, with the data for all units stored together elsewhere
- The alternative is to store all local subprogram data with the subprogram code

Implementing Subprograms in ALGOL-like Languages

- More complicated than FORTRAN 77:
 - Parameters are often passed by two methods
 - Local variables are often dynamically allocated
 - Recursion must be supported
 - Static scoping must be supported

Activation Record Structure

- A typical activation record for an ALGOL-like language:



Activation Record Details

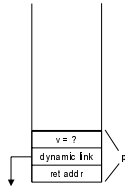
- The activation record format is static, but its size may be dynamic
- The **static link** points to the bottom of the activation record instance of an activation of the static parent (used for access to nonlocal vars)
- The **dynamic link** points to the **bottom** of an instance of the activation record of the caller
- An activation record instance is dynamically created when a subprogram is called

Example Factorial Program (1)

```

program p;
var v : int;
function fac(n: int): int;
begin
  if n <= 1 then
    fac := 1
  else
    fac := n * fac(n - 1);
  end;
begin
  v := fac(3);
  print(v);
end.

```



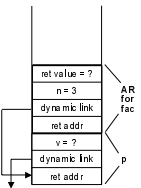
Chapter 9: Implementing Subprograms 10

Example Factorial Program (2)

```

program p;
var v : int;
function fac(n: int): int;
begin
  if n <= 1 then
    fac := 1
  else
    fac := n * fac(n - 1);
  end;
begin
  v := fac(3);
  print(v);
end.

```



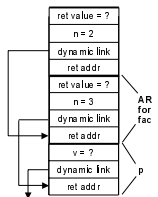
Chapter 9: Implementing Subprograms 11

Example Factorial Program (3)

```

program p;
var v : int;
function fac(n: int): int;
begin
  if n <= 1 then
    fac := 1
  else
    fac := n * fac(n - 1);
  end;
begin
  v := fac(3);
  print(v);
end.

```



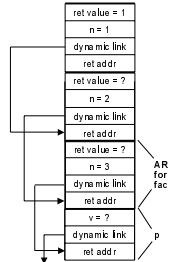
Chapter 9: Implementing Subprograms 12

Example Factorial Program (4)

```

program p;
var v : int;
function fac(n: int): int;
begin
  if n <= 1 then
    fac := 1
  else
    fac := n * fac(n - 1);
  end;
begin
  v := fac(3);
  print(v);
end.

```



Chapter 9: Implementing Subprograms

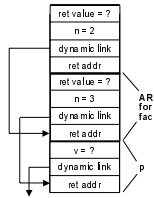
13

Example Factorial Program (5)

```

program p;
var v : int;
function fac(n: int): int;
begin
  if n <= 1 then
    fac := 1
  else
    fac := n * fac(n - 1);
  end;
begin
  v := fac(3);
  print(v);
end.

```



Chapter 9: Implementing Subprograms

14

The Dynamic Chain

- The collection of dynamic links in the stack at a given time is called the **dynamic chain**, or **call chain**
- Local variables can be accessed by their offset from the beginning of the activation record. This offset is called the **local_offset**
- The local_offset of a local variable can be determined by the compiler:
 - Assuming all stack positions are the same size, the first local variable declared has an offset of three plus the number of parameters
- The activation record used in the previous example supports recursion

Chapter 9: Implementing Subprograms

15

Accessing Nonlocal References

- Two situations:
 - Static scoping
 - Static chains
 - Displays
 - Dynamic scoping

■ Chapter 9: Implementing Subprograms ■ 16

Nonlocal Refs: Static Scoping

- All accessible nonlocal variables reside in some ARI on the stack
- The process of locating a nonlocal reference:
 - Find the correct ARI
 - Determine the correct offset within that ARI
 - Finding the offset is easy! It is statically determined
 - Finding the correct ARI:
 - Static semantic rules guarantee that all nonlocal variables that can be referenced have been allocated in some ARI that is on the stack when the reference is made

■ Chapter 9: Implementing Subprograms ■ 17

Technique 1: Static Chains

- A **static chain** is a chain of **static links** that connects certain ARIs
- The static link in an ARI for subprogram A points to one of the ARIs of A's **static parent**
- The static chain from an ARI connects it to all of its static ancestors
- To find the declaration for a reference to a nonlocal variable:
 - The compiler can easily determine how many levels of scope separate the current subprogram from the definition
 - Just walk the static chain the correct number of steps
- **Static_depth** is an integer associated with a static scope whose value is the depth of nesting of that scope

■ Chapter 9: Implementing Subprograms ■ 18

Static Depth and Chain Offset

```

main ----- static_depth = 0
├── A ----- static_depth = 1
│   ├── B ----- static_depth = 2
│   └── C ----- static_depth = 1

```

- The **chain_offset** or **nesting_depth** of a nonlocal reference is the difference between the `static_depth` of the reference and that of the scope where it is declared
- A reference can be represented by the pair: (chain_offset, local_offset)

■ Chapter 9: Implementing Subprograms ■

19

Static Chain Example (1)

```

program MAIN_2;
var X : integer;
procedure BIGSUB;
var A, B, C : integer;
procedure SUB1;
var A, D : integer;
begin { SUB1 }
  A := B + C; <-----1
end; { SUB1 }
procedure SUB2(X : integer);
var B, E : integer;
procedure SUB3;
var C, E : integer;
begin { SUB3 }
  SUB1;
  E := B + A; <-----2
end; { SUB3 }
begin { SUB2 }
  SUB3;
  A := D + E; <-----3
end; { SUB2 }
begin { BIGSUB }
  SUB2(7);
end; { BIGSUB }
begin
  BIGSUB;
end. { MAIN_2 }

```

Call sequence for MAIN_2:

- MAIN_2 calls BIGSUB
- BIGSUB calls SUB2
- SUB2 calls SUB3
- SUB3 calls SUB1

■ Chapter 9: Implementing Subprograms ■

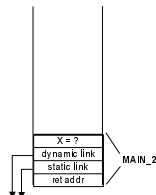
20

Static Chain Example (2)

```

program MAIN_2;
var X : integer;
procedure BIGSUB;
var A, B, C : integer;
procedure SUB1;
var A, D : integer;
begin { SUB1 }
  A := B + C; <-----1
end; { SUB1 }
procedure SUB2(X : integer);
var B, E : integer;
procedure SUB3;
var C, E : integer;
begin { SUB3 }
  SUB1;
  E := B + A; <-----2
end; { SUB3 }
begin { SUB2 }
  SUB3;
  A := D + E; <-----3
end; { SUB2 }
begin { BIGSUB }
  SUB2(7);
end; { BIGSUB }
begin
  BIGSUB;
end. { MAIN_2 }

```



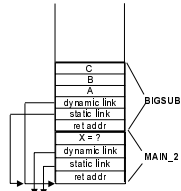
■ Chapter 9: Implementing Subprograms ■

21

Static Chain Example (3)

```

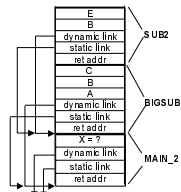
program MAIN_2;
  var X : integer;
  procedure BIGSUB;
    var A, B, C : integer;
    procedure SUB1;
      var A, D : integer;
      begin { SUB1 }
        A := B + C; <-----1
      end; { SUB1 }
    procedure SUB2(X : integer);
      var B, E : integer;
      procedure SUB3;
        var C, E : integer;
        begin { SUB3 }
          SUB1;
          E := B + A; <-----2
        end; { SUB3 }
      begin { SUB2 }
        SUB3;
        A := D + E; <-----3
      end; { SUB2 }
    begin { BIGSUB }
      SUB2(7);
    end; { BIGSUB }
  begin
    BIGSUB;
  end; { MAIN_2 }
  
```



Static Chain Example (4)

```

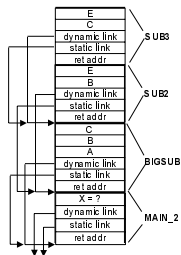
program MAIN_2;
  var X : integer;
  procedure BIGSUB;
    var A, B, C : integer;
    procedure SUB1;
      var A, D : integer;
      begin { SUB1 }
        A := B + C; <-----1
      end; { SUB1 }
    procedure SUB2(X : integer);
      var B, E : integer;
      procedure SUB3;
        var C, E : integer;
        begin { SUB3 }
          SUB1;
          E := B + A; <-----2
        end; { SUB3 }
      begin { SUB2 }
        SUB3;
        A := D + E; <-----3
      end; { SUB2 }
    begin { BIGSUB }
      SUB2(7);
    end; { BIGSUB }
  begin
    BIGSUB;
  end; { MAIN_2 }
  
```



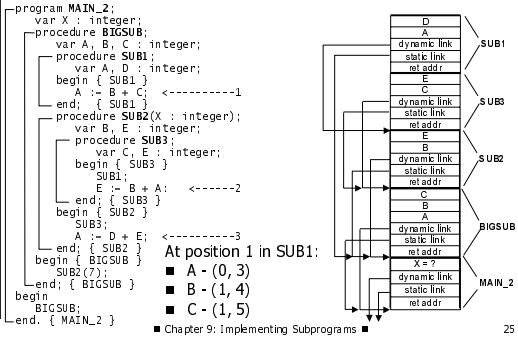
Static Chain Example (5)

```

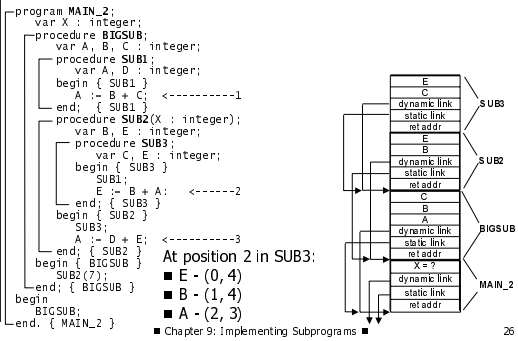
program MAIN_2;
  var X : integer;
  procedure BIGSUB;
    var A, B, C : integer;
    procedure SUB1;
      var A, D : integer;
      begin { SUB1 }
        A := B + C; <-----1
      end; { SUB1 }
    procedure SUB2(X : integer);
      var B, E : integer;
      procedure SUB3;
        var C, E : integer;
        begin { SUB3 }
          SUB1;
          E := B + A; <-----2
        end; { SUB3 }
      begin { SUB2 }
        SUB3;
        A := D + E; <-----3
      end; { SUB2 }
    begin { BIGSUB }
      SUB2(7);
    end; { BIGSUB }
  begin
    BIGSUB;
  end; { MAIN_2 }
  
```



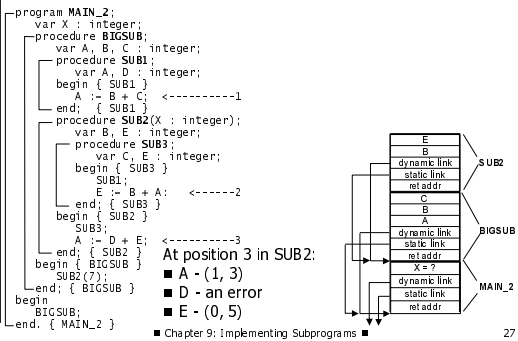
Static Chain Example (6)



Static Chain Example (7)



Static Chain Example (8)



Static Chain Maintenance

- At the call (assume there are no parameters that are subprograms and no pass-by-name parameters):
 - The activation record instance must be built
 - The dynamic link is just the old frame pointer
 - The static link must point to the most recent ARI of the static parent (in most situations)
- Best method:
 - If A calls B, then B's static link should be set to the ARI that is $(\text{static_depth}(A) - \text{static_depth}(B) + 1)$ links along the static chain starting at A
 - Amounts to treating subprogram calls and definitions like variable references and definitions, and then using the `chain_offset`
 - This info can be computed statically by the compiler

■ Chapter 9: Implementing Subprograms ■

28

Evaluation of Static Chains

- Problems:
 - A nonlocal reference is slower if the number of scopes between the reference and the declaration of the referenced variable is large
 - Time-critical code is difficult, because the costs of nonlocal references are not equal, and can change with code upgrades

■ Chapter 9: Implementing Subprograms ■

29

Technique 2 - Displays

- The **idea**: Put the static links in a separate stack called a **display**
- The entries in the display are pointers to the ARIs that have the variables in the referencing environment
- Represent references as $(\text{display_offset}, \text{local_offset})$
- Where `display_offset` is the same as `chain_offset`
- Advantage: constant-time nonlocal access

■ Chapter 9: Implementing Subprograms ■

30

Mechanics of Display References

- Use the `display_offset` to get the pointer into the display to the ARI with the variable
- Use the `local_offset` to get to the variable within the ARI
- Display maintenance (assuming no parameters that are subprograms and no pass-by-name parameters):
 - `Display_offset` depends only on the `static_depth` of the procedure whose ARI is being built: It is exactly the `static_depth` of the procedure
 - There are $k+1$ entries in the display, where k is the static depth of the currently executing unit ($k=0$ is for the main program)
 - For a call to procedure P with a `static_depth` of k :
 - Save a copy of the display pointer at position k in new ARI
 - Put the link to the new ARI for P at position k in the display
 - On return, move the saved display pointer from the ARI back into the display at position k

■ Chapter 9: Implementing Subprograms ■

31

Static Chain vs. Display

- References to locals
 - Not much difference
- References to nonlocals
 - If it is one level away, they are equal
 - If it is farther away, the display is faster
 - Display is better for time-critical code, because all nonlocal references cost the same
- Procedure calls
 - Speed is about the same
 - Display uses more memory
- Procedure returns
 - Both have fixed time, but the static chain is slightly faster
- Overall: Static chain is better, unless the display can be kept in registers

■ Chapter 9: Implementing Subprograms ■

32

Implementing Blocks

- Two Methods:
 - Treat blocks as parameterless subprograms and give them activation records
 - Allocate locals on top of the ARI of the subprogram
 - Must use a different method to access locals (e.g., frame pointer)

■ Chapter 9: Implementing Subprograms ■

33

Implementing Dynamic Scoping

- Deep Access
 - Nonlocal references are found by searching the activation record instances on the dynamic chain
 - Length of chain cannot be statically determined
 - Every activation record instance must have variable names
- Shallow Access
 - Put locals in a central place
 - Methods:
 - One stack for each variable name
 - Central table with an entry for each variable name

■ Chapter 9: Implementing Subprograms ■

34

Subprograms as Parameters

- For deep binding:
 - Static chain
 - Compiler simply passes the link to the static parent of the parameter, along with the parameter
 - Display
 - All pointers to static ancestors must be saved, because none are necessarily in the environment of the parameter
 - In many implementations, the whole display is saved for calls that pass subprogram parameters

■ Chapter 9: Implementing Subprograms ■

35
