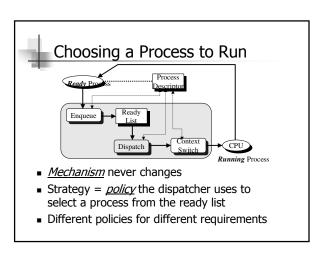


- Involuntary CPU sharing timer interrupts
 - <u>Time quantum</u> determined by interval timer – usually fixed size for every process using the system
 - Sometimes called the *time slice length*





Policy Considerations

- Policy can control/influence:
 - CPU utilization
 - Average time a process waits for service
 - Average amount of time to complete a job
- Could strive for any of:
 - Equitability
 - Favor very short or long jobs
 - Meet priority requirements
 - Meet deadlines



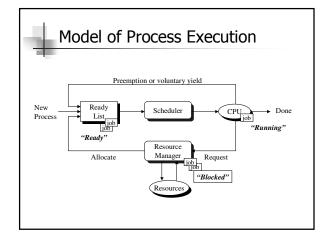
Optimal Scheduling

- Suppose the scheduler knows each process p_i 's <u>service time</u>, $\tau(p_i)$ -- or it can estimate each $\tau(p_i)$:
- Policy can optimize on any criteria, e.g.,
 - CPU utilization
 - Waiting time
 - Deadline
- To find an optimal schedule:
 - Have a finite, fixed # of p_i
 - Know $\tau(p_i)$ for each p_i
 - Enumerate all schedules, then choose the best



However ...

- The τ(p_i) are almost certainly just estimates
- General algorithm to choose optimal schedule is O(n²)
- Other processes may arrive while these processes are being serviced
- Usually, optimal schedule is only a <u>theoretical benchmark</u> – scheduling policies try to <u>approximate</u> an optimal schedule





Selection Strategies

- Motivation
 - To "optimize" some aspect of system behavior
- Considerations
 - Priority of process
 - External : assigned
 - Internal : aging
 - Fairness : no starvation
 - Overall Resource Utilization

...



Selection Strategies...

- Considerations...
 - Turnaround time
 - Average time / job
 - Throughput
 - Jobs / time unit
 - Response time
 - System availability
 - Deadlines

Talking About Scheduling ...

- Let $P = \{p_i \mid 0 \le i < n\} = \text{set of processes}$
- Let S(p_i) ∈ {running, ready, blocked}
- Let $\tau(p_i)$ = Time process needs to be in running state (the <u>service time</u>)
- Let W(p_i) = Time p_i is in ready state before <u>first</u> transition to running (<u>wait time</u>)
- Let $T_{TRnd}(p_i)$ = Time from p_i first enter ready to last exit ready ($\underline{turnaround\ time}$)
- Batch <u>Throughput rate</u> = inverse of avg T_{TRnd}
- Timesharing response time = W(p_i)



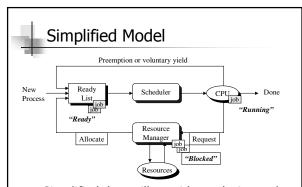
Definition & Terms

- Time Quantum
 - Amount of time between timer interrupts
 - Also called Time Slice
- Service Time τ (P_i)
 - Amount of time process needs to be in Running state (acquired CPU) before it is completed
- Wait Time W (P_i)
 - Time a process spends waiting in the Ready state before its *first* transition to the Running state



Definition & Terms...

- Turnaround Time T (P_i)
 - Amount of time between moment process first enters Ready state and the moment the process exits Running state for the last time (completed)
- Service time, Wait time & Turnaround time are measurable metrics used to compare scheduling algorithms



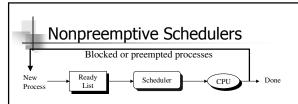
- Simplified, but still provide analysis result
- Easy to analyze performance



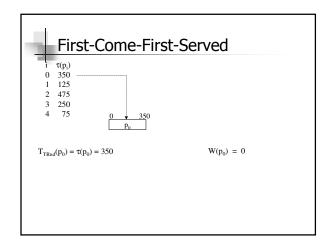
Classes of Scheduling Algorithms

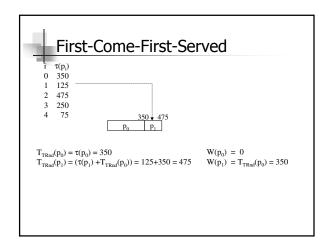
- 2 major classes
 - Non-preemptive
 - Run to completion
 - Preemptive
 - Process with highest priority always gets CPU

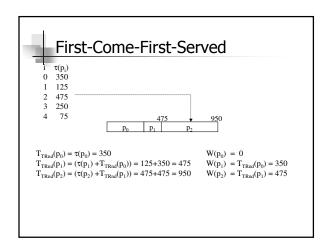
Recall: Several ways to establish priority

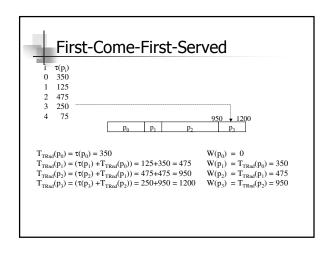


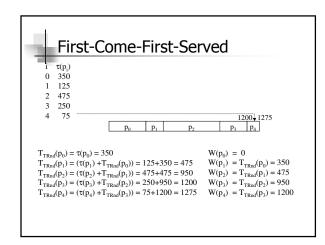
- Try to use the simplified scheduling model
- Only consider <u>running</u> and <u>ready</u> states
- Ignores time in <u>blocked</u> state:
 - "New process created when it enters ready state"
 - "Process is destroyed when it enters blocked state"
 - Really just looking at "small phases" of a process

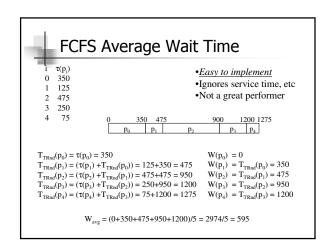


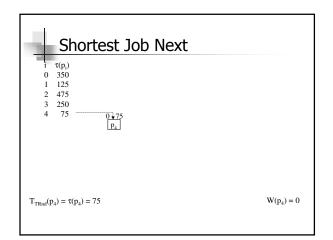


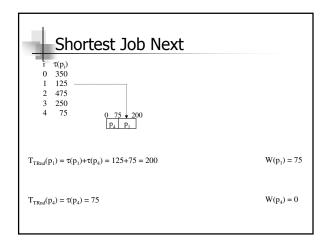


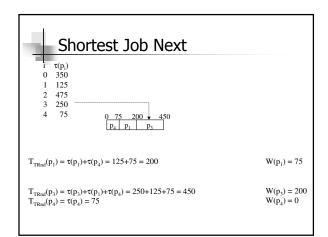


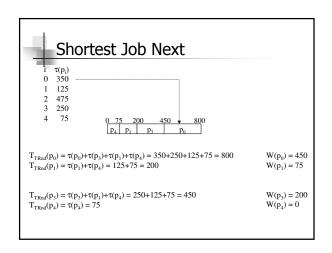


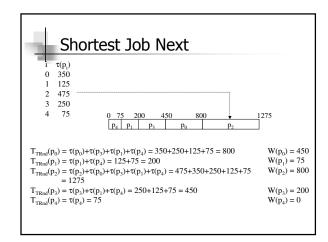


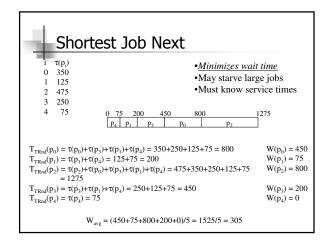


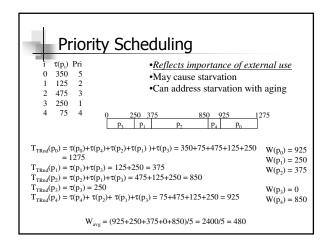


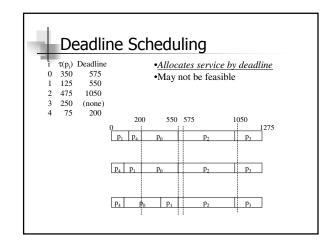


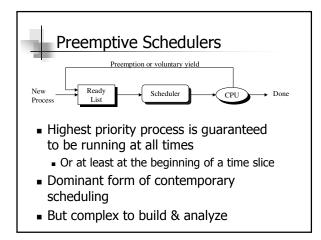


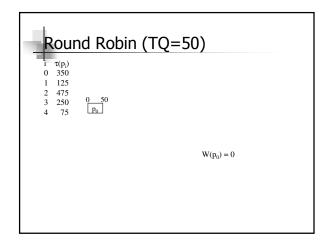








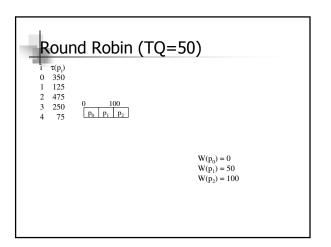


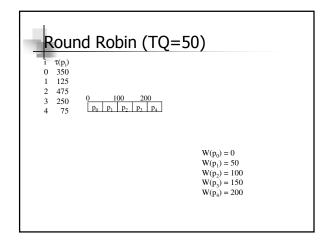


```
Round Robin (TQ=50)

1 \tau(p_i)
0 350
1 125
2 475
3 250 0 100
4 75 p_0 p_1

W(p_0) = 0
W(p_1) = 50
```

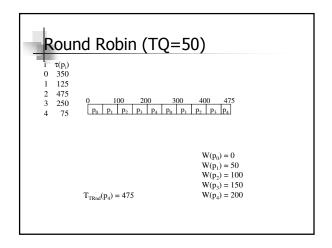




```
Round Robin (TQ=50)

1 \tau(p_i)
0 350
1 125
2 475
3 250
4 75

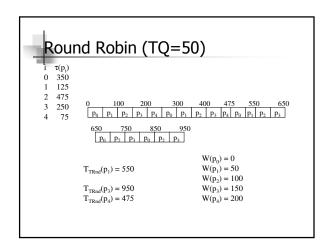
W(p_0) = 0
W(p_1) = 50
W(p_1) = 50
W(p_2) = 100
W(p_3) = 150
W(p_4) = 200
```

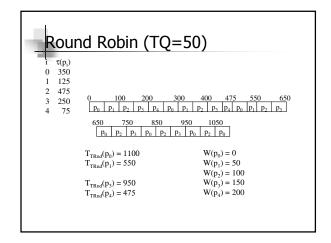


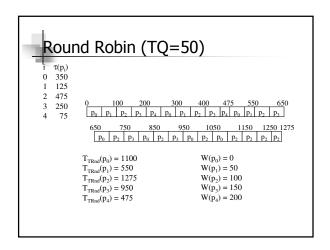
```
Round Robin (TQ=50)

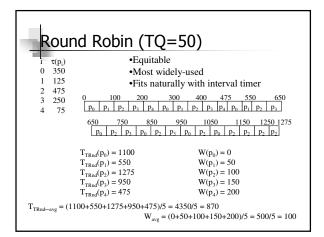
1 \tau(p_1)
0 350
1 125
2 475
3 250
4 75

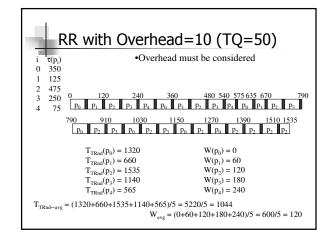
\tau(p_1)
0 100 200 300 400 475 550
\tau(p_0)
\tau(p_1)
\tau(p_2)
\tau(p_1)
\tau(p_2)
\tau(p_1)
\tau(p_2)
\tau(p_2)
\tau(p_3)
\tau(p_4)
```

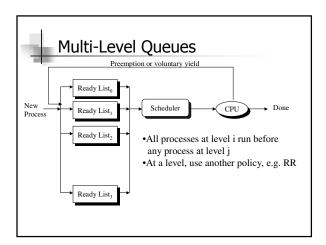












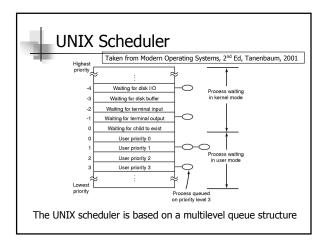
Contemporary Scheduling

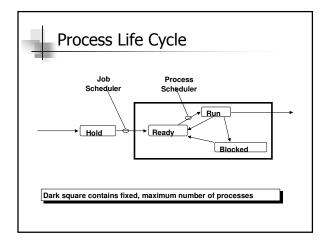
- Involuntary CPU sharing -- timer interrupts
 - <u>Time quantum</u> determined by interval timer -usually fixed for every process using the system
 - Sometimes called the *time slice length*
- Priority-based process (job) selection
 - Select the highest priority process
 - Priority reflects policy
- With *preemption*
- Usually a variant of *Multi-Level Queues*



BSD 4.4 Scheduling

- Involuntary CPU Sharing
- Preemptive algorithms
- 32 Multi-Level Queues
 - Queues 0-7 are reserved for system functions
 - Queues 8-31 are for user space functions
 - nice influences (but does not dictate) queue level







Job and Process Scheduler

Job Scheduler

- · Controls when jobs will be allowed to contend the CPU
- Most popular techniques

FIFO First in, first out

SJF Shortest job first

Process Scheduler

- Controls when individual jobs (processes) will actually get the CPU
- Only interesting in multi-programming
- Most popular technique is Round Robin
 - Give each process one time slice in turn until complete



Turnaround and Weighted Turnaround Time

Let: N be number of jobs

A_i be arrival time of i-th job

F_i be finish time of i-th job

Turnaround time for ith job:

 $T_i = F_i - A_i$

Average turnaround time for ith job:

 $T = \Sigma T_i / N$

Weighted turnaround time for ith job:

 $WT_i = (F_i - A_i) / (Service-time)_i$

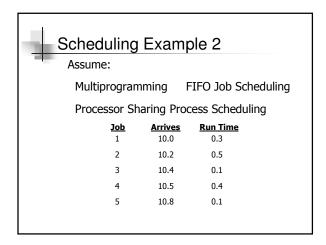
Average Weighted Turnaround time:

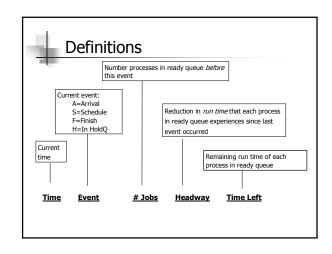
 $WT = \Sigma WT_i / N$



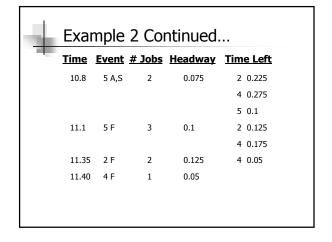
Processor Sharing (PS) "Theoretical" Scheduling Algorithm

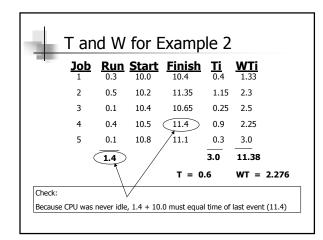
- Limit of RR as time quantum goes to zero.
- Like giving each CPU cycle to a different process, in round robin fashion.
- N processes scheduled by PS
 - Each job runs on dedicated *N*-fold slower CPU.
 - Thus, READY = RUNNING.
- CPU Time "shared" equally among processes

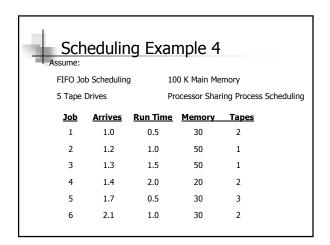




Exa	ample	e 2 Co	ontinue	ed.	
Time	Event	# Jobs	<u>Headway</u>	Time	Left
10.0	1 A,S			1	0.3
10.2	2 A,S	1	0.2	1	0.1
				2	0.5
10.4	1 F	2	0.1	2	0.4
	3 A,S			3	0.1
10.5	4 A,S	2	0.05	2	0.35
				3	0.05
				4	0.4
10.65	3 F	3	0.05	2	0.3
				4	0.35







Exa	ampl	e 4 C	Contir	nue	d	
Time	Event	# Jobs	HWay	MM	Tapes	Time Left
1.0	1 A,S			70	3	1 0.5
1.2	2 A,S	1	0.2	20	2	1 0.3
						2 1.0
1.3	3 A,H	2	0.05	20	2	1 0.25
						2 0.95
1.4	4 A,S	2	0.05	0	0	1 0.2
						2 0.9
						4 2.0
1.7	5 A,H	3	0.1	0	0	1 0.1
						2 0.8
						4 1.9
2.0	1 F	3	0.1	30	2	2 0.7
						4 1.8

Į E	Example 4 Continued								
<u>Tir</u>	ne	Event	# Jobs	<u>HWa</u> y	<u> MM</u>	Tapes	Time Left		
2.	1	6 A,S	2	0.05	0	0	2 0.65		
							4 1.75		
							6 1.0		
4.	05	2 F	3	0.65	50	1	4 1.1		
		3 S			0	0	6 0.35		
							3 1.5		
5.	1	6 F	3	0.35	30	2	4 0.75		
							3 1.15		
6.	6	4 F	2	0.75	50	4	3 0.4		
		5 S			20	1	5 0.5		
7.	4	3 F	2	0.4	70	2	5 0.1		
7.	5	5 F	1	0.1	100	5			

