

B. Methods for solving a single IVP

1. Taylor series methods

- Idea: approximate $x(t_{k+1})$ a truncated Taylor series for x , expanded about t_k .
- Examples

– Euler's method:

$$x_{k+1} = x_k + hf(t_k, x_k)$$

– Higher order methods

$$x_{k+1} = x_k + hf(t_k, x_k) + \frac{h^2}{2}f'(t_k, x_k) + \cdots + \frac{h^p}{p!}f^{(p-1)}(t_k, x_k)$$

2. Runge-Kutta methods

- Idea: get better approximation to $x(t + h)$ by evaluating f at more places, rather than by differentiating f .
- Examples

– RK method of order 2

$$x_{k+1} = x_k + \frac{h}{2} [f(t_k, x_k) + f(t_{k+1}, x_k + hf(t_k, x_k))]$$

– RK method of order 4

$$\begin{aligned} K_1 &= hf(t_k, x_k), \\ K_2 &= hf\left(t_k + \frac{h}{2}, x_k + \frac{1}{2}K_1\right), \\ K_3 &= hf\left(t_k + \frac{h}{2}, x_k + \frac{1}{2}K_2\right), \\ K_4 &= hf(t_{k+1}, x_k + K_3), \\ x_{k+1} &= x_k + \frac{1}{6}(K_1 + 2K_2 + 2K_3 + K_4) \end{aligned}$$

3. Multistep methods

- Idea: use information from t_0, \dots, t_k to compute x_{k+1} .
- Examples
 - An “explicit” m -step formula:

$$x_{k+1} = \sum_{j=k+1-m}^k \alpha_j x_j + \sum_{j=k+1-m}^k \beta_j f(t_j, x_j),$$

where the α_j and β_j are chosen to minimize the local error.

- An Adams-Bashforth m -step formula:

$$x_{k+1} = x_k + h \left(\sum_{j=k+1-m}^k \beta_j f(t_j, x_j) \right).$$

- A 3-step Adams-Bashforth formula:

$$x_{k+1} = x_k + \frac{h}{12} (23f(t_k, x_k) - 16f(t_{k-1}, x_{k-1}) + 5f(t_{k-2}, x_{k-2})).$$

4. Implicit methods

- Idea: x_{k+1} is defined implicitly at each step
- Examples:
 - Backward Euler.

$$x_{k+1} = x_k + hf(t_{k+1}, x_{k+1})$$

- Trapezoidal rule.

$$x_{k+1} = x_k + h(f(t_k, x_k) + f(t_{k+1}, x_{k+1}))$$

- 3-step Adams-Moulton.

$$x_{k+1} = x_k + \frac{h}{24} (9f(t_{k+1}, x_{k+1}) + 19f(t_k, x_k) - 5f(t_{k-1}, x_{k-1}) + f(t_{k-2}, x_{k-2}))$$