CS 3214: Computer Systems Lecture 17: Performance of Multithreaded Programs

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### Announcement

- □ Midterm on 10/27 (Thur), In-class (Surge 104C), 75min
- □ Exam includes 3-5 multipart questions
- Format
  - Closed book, closed notes, closed computer
  - One letter size "cheatsheet" (front + back)
- □ Covered topics
  - Processes: dual-mode, context/mode switching, process states
  - Process APIs, system calls, signals, basic I/Os
  - Linking and loading: static + dynamic linking, scoping
  - Multi-threaded programming: locks, semaphore, condition variable, thread-safety, deadlock
  - Resources:
    - CSAPP3e: Chapters 1, 7, 8, 9, 10, and 12
    - Project I, 2
    - Exercises I, 2, 3

#### Special accommodations

## **Performance Considerations**

Ways to evaluate synchronization implementation

- Correctness
- Fairness
- Performance
- □ Cost of locking
  - Indirect cost
    - resulting in loss of performance due to the use of locking
    - fully concurrently ightarrow partially concurrent
  - Direct cost
    - (involved in actions the system had to take to implement it)
    - ak.a, Lock function implementation overhead

## **Indirect Cost**

□ A microbenchmark / simulation experiment to measure locking cost

- 5 CPU-bound processes contending for L locks
- holding each lock for duration D
- then running for duration U without lock
- Thread chooses lock randomly.

### Indirect Cost: Single Lock

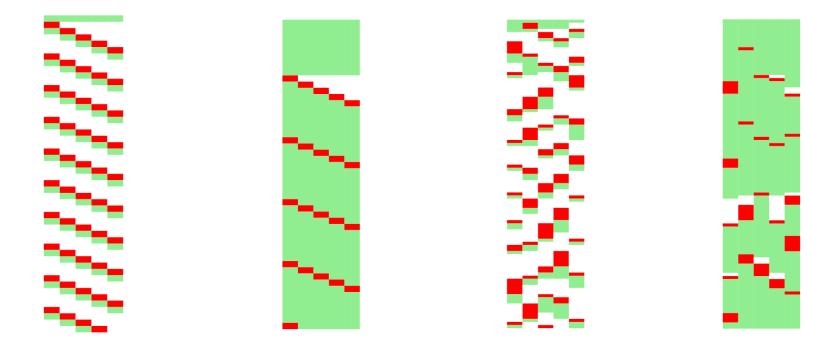
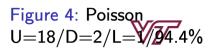


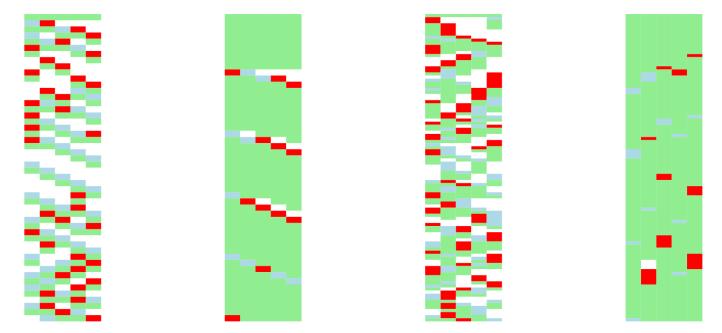
Figure 1: Fixed: U=2/D=2/L=1/40.8%

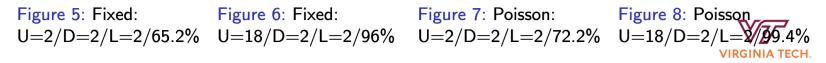
Figure 2: Fixed: U=18/D=2/L=1/96%

Figure 3: Poisson: U=2/D=2/L=1/41.6%



### **Indirect Cost: Two Locks**





### **Indirect Cost: Four Locks**

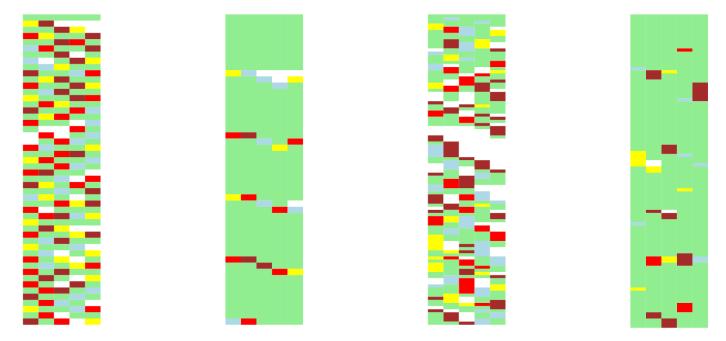


Figure 9: Fixed:Figure 10: Fixed:Figure 11: Poisson:Figure 12: PoissonU=2/D=2/L=4/89.6%U=18/D=2/L=4/98%U=2/D=2/L=4/79.2%U=18/D=2/L=4/99.4%

### Indirect Cost: Loss of Parallelism

- Serialization due to locks diminishes CPU utilization and increases an individual task's latency
  - For parallel, mostly CPU-bound applications, it translates directly into loss of speedup
  - Particularly if locks are contended, no other tasks to run when threads are blocked
- This serialization effect would be exacerbated if blocked threads held locks (e.g., I/O, sleep, sem wait, pthread join?)
- Rule: Critical sections should not call any functions that may block, or else the critical section may become inaccessible

pthread\_mutex\_lock(&shutdownLock);
pthread\_mutex\_lock(&infoLock);
while (!moreInformation)
 pthread\_cond\_wait(&moreInfo, &infoLock);
pthread\_mutex\_unlock(&infoLock);
pthread\_mutex\_unlock(&shutdownLock);

pthread\_mutex\_lock(&lock); read(fd, buf, sizeof(buf)); pthread\_mutex\_unlock(&lock);

# **Solution: Breaking Up Locks**

- Cautionary side note: several large software systems were either never parallelized or started with a "big lock" approach: the Linux kernel, Python's GIL, gtk GUI lock
- Idea: instead of having lock L protect data (A, B, C) introduce locks LA, LB, LC to protect A, B, and C, respectively.
- □ Thus, updates to A will not prevent simultaneous updates to B

#### □ This introduces 3 risks

- Higher risk of atomicity violations: if A and B must be updated in tandem (atomically) say update to B is dependent on A having a value, both locks must be held. Always holding both locks negates purpose of having 2 locks; not holding them both where needed leads to atomicity violations
- Higher risk of deadlocks: if there are situations where both locks must be held, a locking order must be established to avoid deadlocks
- More frequent calls to lock/unlock translates to increased direct cost (locking overhead)

# **Direct Cost of Locking**

- $\Box$  What happens under the hood in a call to pthread mutex lock()?
  - Fast path: an atomic instruction tries to acquire the lock (if available) without causing a mode switch (e.g. cmpxchg %rax, (%rbx)) in memory flag that indicates if lock is available
  - For <u>fast path numbers</u>, see Jeff Dean/Peter Norvig/Colin Scott Numbers Every Programmer Should Know
    - 17× L1 reference, 4× L2 reference, 16 × main memory reference (17ns as of 2010's)
  - Slow path: if atomic instruction indicates that lock is already held, make system call (*futex\_wait*) and inform kernel that thread should block. Then, context switch to other ready thread (if any)

#### □ pthread mutex unlock()?

- Fast path: just place lock into unlocked state
- Slow path (someone is waiting for the lock): make system call (*futex\_wakeup*) and inform kernel to wake up any waiting thread(s). These threads are unblocked (made ready), placed into ready queue, and eventually scheduled - another context switch

#### □ Both mode and context switches can be costly

- Pipeline stalls
- Cache pollution