

Distributed Snapshot (Global State Recording)

Problems:

- recording a "consistent" state of the global computation
 - checkpointing for fault tolerance (rollback, recovery)
 - testing and debugging
 - monitoring and auditing
- detecting stable properties in a distributed system via snapshots.
 A property is "stable" if, once it holds in a state, it holds in all subsequent states.
 - termination
 - deadlock
 - garbage collection

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Definitions

Local State and Actions:

```
\begin{split} & local \; state: & LS_i \\ & message \; send: & send(m_{ij}\;) \\ & message \; receive: & rec(m_{ij}\;) \\ & time: & time(x) \\ & send(m_{ij}\;) \; \epsilon \; LS_i \; iff \; time(send(m_{ij}\;)) < time(LS_i\;) \\ & rec(m_{ij}\;) \; \epsilon \; LS_j \; iff \; time(rec(m_{ij}\;)) < time(LS_j\;) \end{split}
```

Predicates:

```
\begin{split} & transit(LS_{i}\text{ , }LS_{j}\text{ )} = \\ & \left\{m_{ij} \mid send(m_{ij}\text{ )} \text{ }\epsilon\text{ }LS_{i}\text{ }\Lambda\text{ }!(\text{ }rec(m_{ij}\text{ )} \text{ }\epsilon\text{ }LS_{j}\text{ )}\text{ )}\text{ }\}\\ & inconsistent(LS_{i}\text{ , }LS_{j}\text{ )} = \\ & \left\{m_{ij} \mid !(send(m_{ij}\text{ )} \text{ }\epsilon\text{ }LS_{i}\text{ )}\text{ }\Lambda\text{ }rec(m_{ij}\text{ )} \text{ }\epsilon\text{ }LS_{j}\text{ )}\text{ }\} \end{split}
```

Consistent Global State:

```
\forall i, \forall j : 1 \le i, j \le n :: inconsistent(LS_i, LS_j) = \Phi
```

Global-State-Detection Algorithm

Marker-Sending Rule for a Process p:

For each channel c, incident on, and directed away from p: p sends one marker along c after p records its state and before p sends further messages along c.

Marker-Receiving Rule for a Process q:

if (q has not recorded its state) then

begin q records its state;

q records the state of c as the empty sequence;

end

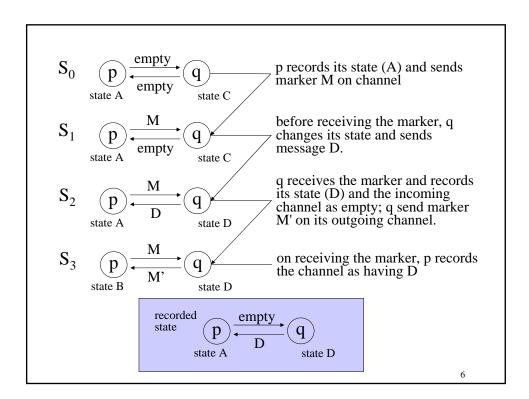
else q records the state of c as the sequence of message received along c after q's state was recorded and before q received the marker along c.

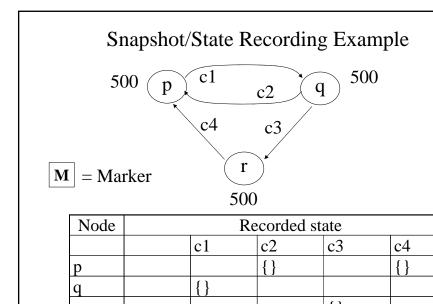
Detecting a Stable Property

begin

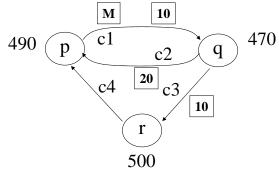
record a global snapshot, S*; test for the stable property in S*;

end;

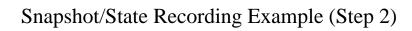


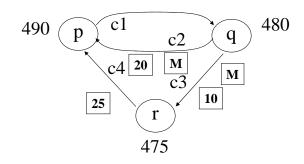






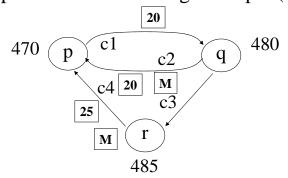
Node	Recorded state				
	state	c1	c2	c3	c4
p	490		{}		{}
q		{}			
r				{}	



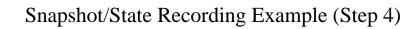


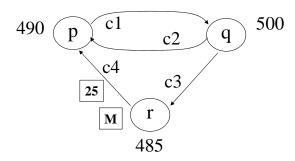
Node	Recorded state				
	state	c1	c2	c3	c4
p	490		{}		{}
q	480	{}			
r				{}	

Snapshot/State Recording Example (Step 3)



Node	Recorded state				
	state	c1	c2	c3	c4
p	490		{}		{}
q	480	{}			
r	485			{}	

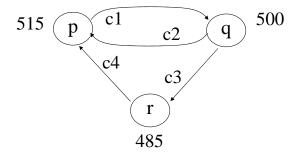




Node	Recorded state				
	state	c1	c2	c3	c4
p	490		{20}		{}
q	480	{}			
r	485			{}	

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Snapshot/State Recording Example (Step 5)



Node	Recorded state				
	state	c1	c2	c3	c4
p	490		{20}		{25}
q	480	{}			
r	485			{}	