# Time and Ordering

The two critical differences between centralized and distributed systems are:

- absence of shared memory
- absence of a global clock

We will study:

- how programming mechanisms change as a result of these differences
- algorithms that operate in the absence of a global clock
- algorithms that create a sense of a shared, global time
- algorithms that capture a consistent state of a system in the absence of shared memory



How can the events on P be related to the events on Q? Which events of P "happened before" which events of Q? Partial answer: events on P and Q are strictly ordered. So:

$$P_1 --> P_2 --> P_3$$

and

$$Q_1 --> Q_2 --> Q_3$$



Realization: the only events on P that can causally affect events on Q are those that involve communication between P and Q.

If  $P_1$  is a send event and  $Q_2$  is the corresponding receive event then it must be the case that:

$$P_1 --> Q_2$$



"Happened Before" relation:

- If  $E_i$  and  $E_j$  are two events of the same process, then  $E_i - > E_j$  if i < j.
- •If  $E_i$  and  $E_j$  are two events of different processes, then  $E_i --> E_j$  if  $E_i$  is a message send event and  $E_j$  is the corresponding message receive event.
- •The relation is transitive.

# Lamport's Algorithm

Lamport's algorithm is based on two implementation rules that define how each process's local clock is incremented.

Notation:

- the processes are named P<sub>i</sub>,
- each process has a local clock, C<sub>i</sub>
- the clock time for an event a on process  $P_i$  is denoted by  $C_i$  (a).

<u>Rule 1:</u>

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If a and b are two successive events in P_i and a --> b then C_i(b) = C_i(a) + d where d > 0.
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<u>Rule 2:</u>

If a is a message send event on  $P_i$  and b is the message receive event on  $P_j$  then:

- the message is assigned the timestamp  $t_m = C_i$  (a)
- $C_j(b) = max(C_j, t_m + d)$

### Example of Lamport's Algorithm



# Limitation of Lamport's Algorithm

In Lamport's algorithm two events that are causally related will be related through their clock times. That is:

If a --> b then C(a) < C(b)

However, the clock times alone do not reveal which events are causally related. That is, if C(a) < C(b) then it is not known if a --> b or not. All that is known is:

if C(a) < C(b) then b - / - > a

It would be useful to have a stronger property - one that guarantees that

a --> b iff C(a) < C(b)

This property is guaranteed by Vector Clocks.

## Vector Clock Rules

Each process  $P_i$  is equipped with a clock  $C_i$  which is an integer vector of length n.

 $C_i(a)$  is referred to as the timestamp event a at  $P_i$ 

 $C_i[i]$ , the *i*th entry of  $C_i$  corresponds to  $P_i$ 's own logical time.

 $C_i[j], j \neq i$  is  $P_i$ 's best guess of the logical time at  $P_i$ 

#### **Implementation rules for vector clocks:**

**[IR1]** Clock  $C_i$  is incremented between any two successive events in process  $P_i$ 

$$C_i[i] := C_i[i] + d$$
 (d > 0)

**[IR2]** If event *a* is the sending of the message *m* by process  $P_i$ , then message *m* is assigned a vector timestamp  $t_m = C_i(a)$ ; on receiving the same message *m* by process  $P_j$ ,  $C_j$  is updated as follows:

$$\forall k, C_j[k] := \max(C_j[k], t_m[k])$$

### Vector Clocks



### Causal Ordering of Messages



## Birman-Schiper-Stephenson Protocol

1. Before broadcasting a message *m*, a process  $P_i$  increments the vector time  $VT_{Pi}[i]$  and timestamps *m*. Note that  $(VT_{Pi}[i] - 1)$  indicates how many messages from  $P_i$  precede *m*.

2. A process  $P_j \neq P_i$ , upon receiving message *m* timestamped  $VT_m$  from  $P_i$ , delays its delivery until both the following conditions are satisfied.

a.  $VT_{Pj}[i] = VT_m[i] - 1$ 

b.  $VT_{Pj}[k] \ge VT_m[k] \ \forall k \in \{1, 2, ..., n\} - \{i\}$ 

where *n* is the total number of processes.

Delayed messages are queued at each process in a queue that is sorted by vector time of the messages. Concurrent messages are ordered by the time of their receipt.

3. When a message is delivered at a process  $P_{j}$ ,  $VT_{Pj}$  is updated according to the vector clocks rule [IR2]