Memory Management

Subdividing memory to accommodate multiple processes

Memory needs to be allocated to ensure a reasonable supply of ready processes to consume available processor time

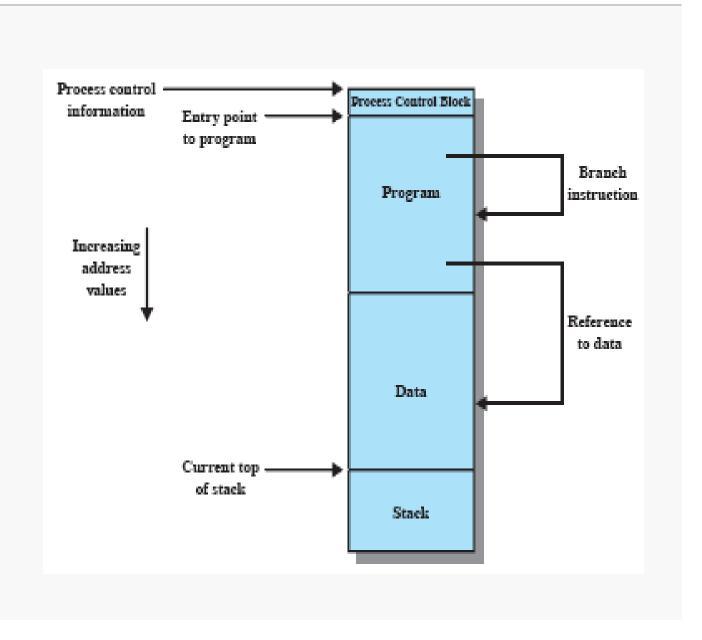
Relocation

Programmer does not know where the program will be placed in memory when it is executed

While the program is executing, it may be swapped to disk and returned to main memory at a different location (relocated)

Memory references must be translated in the code to actual physical memory address

Addressing Requirements



Memory Management Requirements

Protection

Processes should not be able to reference memory locations in another process without permission

Impossible to check absolute addresses at compile time

Must be checked at run time

Memory protection requirement must be satisfied by the processor (hardware) rather than the operating system (software)

Operating system cannot anticipate all of the memory references a program will make

Sharing

Allow several processes to access the same portion of memory

Better to allow each process access to the same copy of the program rather than have their own separate copy

Memory Management Requirements

Logical Organization

Programs are written in modules

Modules can be written and compiled independently

Different degrees of protection given to modules (read-only, execute-only)

Share modules among processes

Physical Organization

Memory available for a program plus its data may be insufficient

Overlaying allows various modules to be assigned the same region of memory

Programmer does not know how much space will be available

Fixed Partitioning

Equal-size partitions

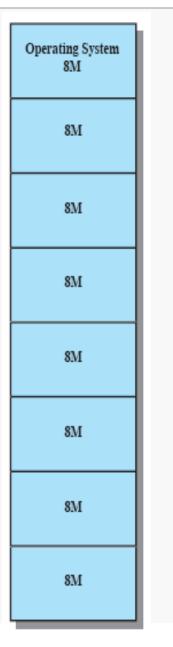
Any process whose size is less than or equal to the partition size can be loaded into an available partition

If all partitions are full, the operating system can swap a process out of a partition

A program may not fit in a partition. The programmer must design the program with overlays

Main memory use is inefficient. Any program, no matter how small, occupies an entire partition. This is called internal fragmentation.

Because all partitions are of equal size, it does not matter which partition is used, so placement algorithm is essentially trivial.



Fixed Partitioning

Unequal	l-size	partitions
o moqua.	DILLO	Partitions

Can assign each process to the smallest partition within which it will fit

Queue for each partition

Processes are assigned in such a way as to minimize wasted memory within a partition

Main memory use is potentially more efficient. Any program, no matter how small or large is placed in a closer-sized partition. Does not eliminate internal fragmentation.

Management of partitions is more complex, hence more overhead.

Operating System 8M

2M

4M

6M

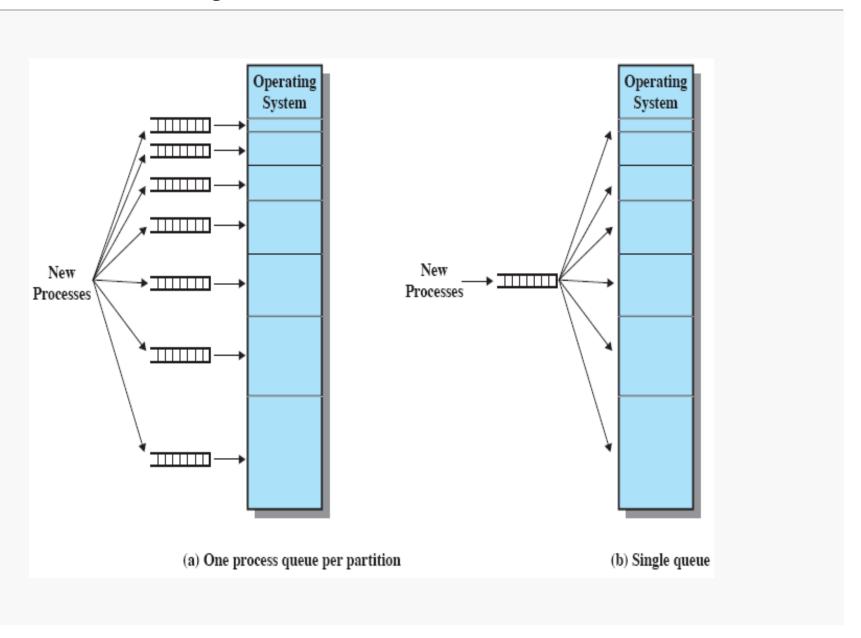
8M

8M

12M

16M

Process Scheduling



Dynamic Partitioning

Partitions are of variable length and number

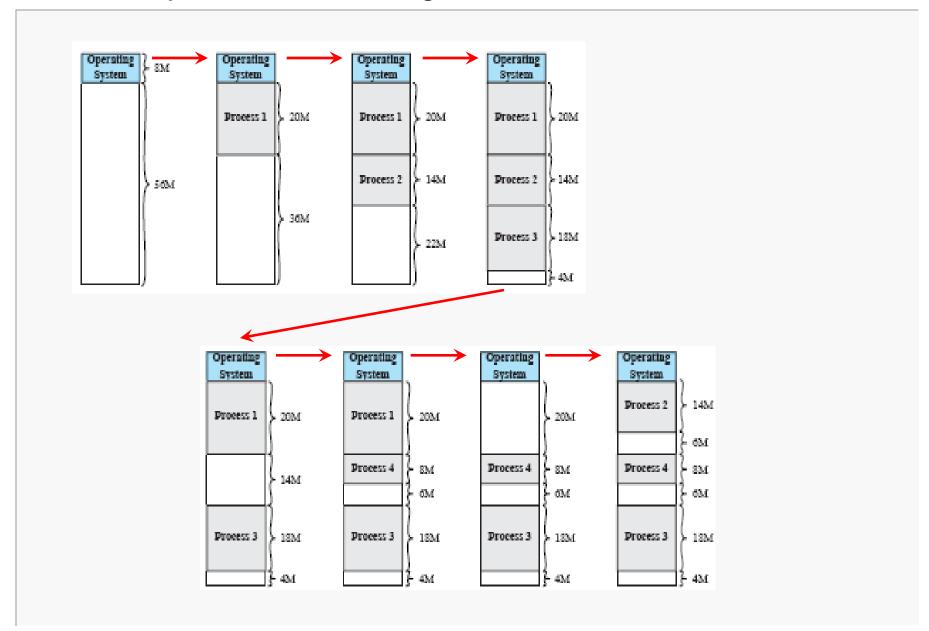
Process is allocated exactly as much memory as required

Eventually get holes in the memory. This is called external fragmentation

Must use *compaction* to shift processes so they are contiguous and all free memory is in one block

However, compaction is time-consuming, and it requires some scheme for adjusting addresses when relocating processes in memory

Effect of Dynamic Partitioning



DP Placement Algorithm

Operating system must decide which free block to allocate to a process

Best-fit algorithm

Chooses the block that is closest in size to the request

Worst performer overall

Since smallest block is found for process, the smallest amount of fragmentation is left

Memory compaction must be done more often

First-fit algorithm

Scans memory form the beginning and chooses the first available block that is large enough

Fastest

May have many process loaded in the front end of memory that must be searched over when trying to find a free block

Next-fit

Scans memory from the location of the last placement

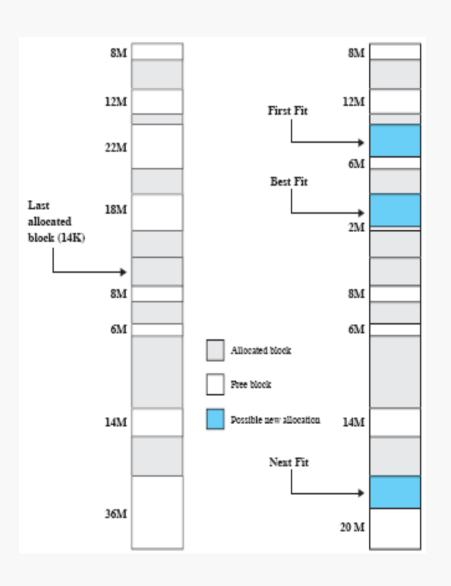
More often allocate a block of memory at the end of memory where the largest block is found

The largest block of memory is broken up into smaller blocks

Compaction is required to obtain a large block at the end of memory

Examples

Before and after allocation of a 16MB block:



Buddy System

Entire space available is treated as a single block of 2^U If a request of size s such that $2^{U-1} < s <= 2^U$, entire block is allocated Otherwise block is split into two equal buddies Process continues until smallest block greater than or equal to s is generated

1 Mbyte block	1 M					
Request 100 K	A = 128K	A = 128K 128K 256K 512K				
Request 240 K	A = 128K	128K	B = 256K	512K		
Request 64 K	A = 128K	C = 64K 64K	B = 256K	512K		
Request 256 K	A = 128K	C = 64K 64K	B = 256K	D = 256K	256K	
Release B	A = 128K	C = 64K 64K	256K	D = 256K	256K	
Release A	128K	C = 64K 64K	256K	D = 256K	256K	
Request 75 K	E = 128K	C=64K 64K	256K	D = 256K	256K	
-	E = 128K	128K	256K	D = 256K	256K	
Release E			2K	D = 256K	256K	
Release D		1M				
Release D			1	NT.		

Paging

Partition memory into small equal fixed-size chunks and divide each process into the same size chunks

The chunks of a process are called pages and chunks of memory are called frames

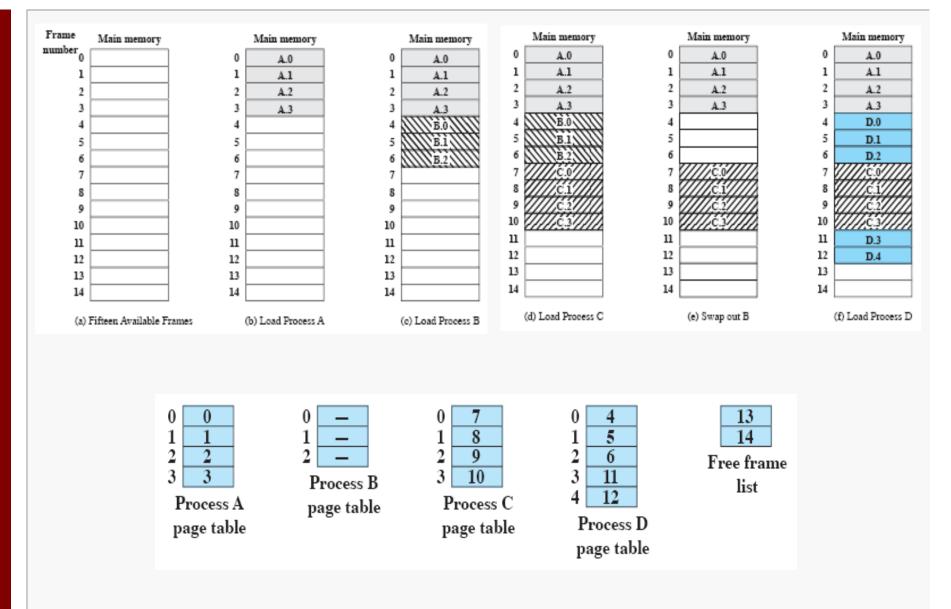
Operating system maintains a page table for each process

Contains the frame location for each page in the process

Memory address consist of a page number and offset within the page

Allocation of Free Frames

MM Background 14



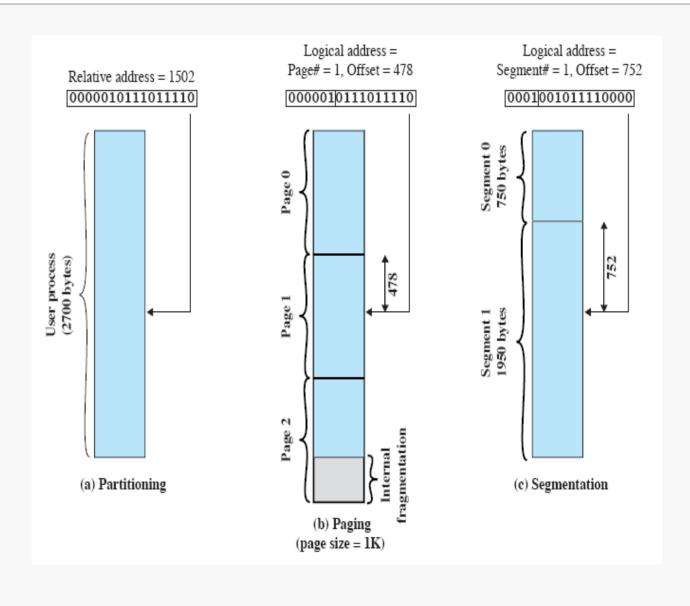
Segmentation

All segments of all programs do not have to be of the same length There is a maximum segment length

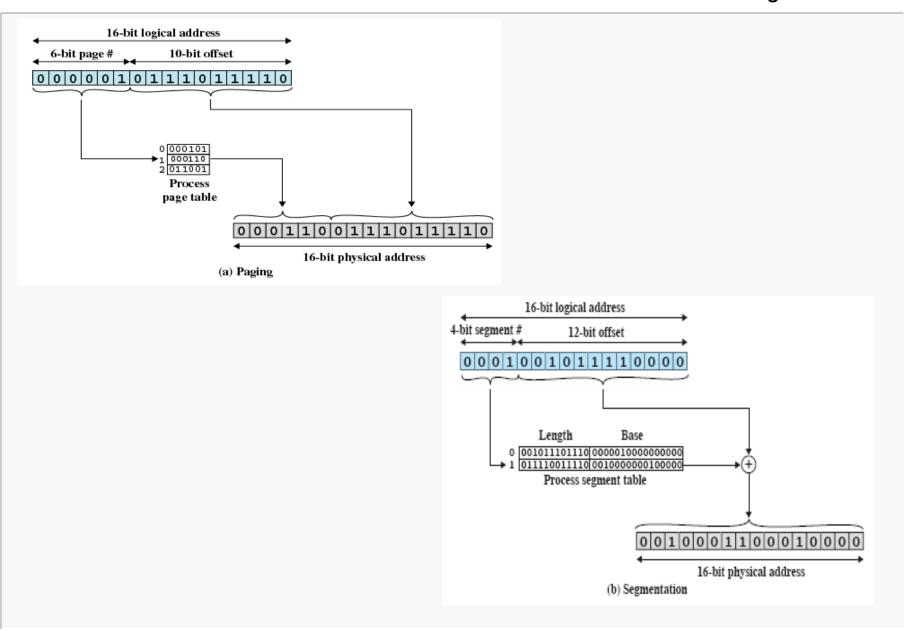
Addressing consist of two parts - a segment number and an offset

Since segments are not equal, segmentation is similar to dynamic partitioning

Logical Addresses



Address Translation



Relocation and Addresses

When program loaded into memory the actual (absolute) memory locations are determined

A process may occupy different partitions at different times, which means different absolute memory locations during execution (from swapping)

Compaction will also cause a program to occupy a different partition which means different absolute memory locations

Paging and segmenting will fragment a process into discontiguous pieces.

Logical address

Reference to a memory location independent of the current assignment of data to memory Translation must be made to the physical address

Relative address

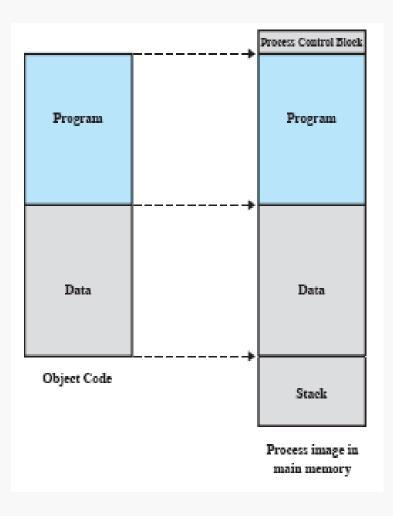
Address expressed as a location relative to some known point

Physical address

The absolute address or actual location in main memory

Process Image

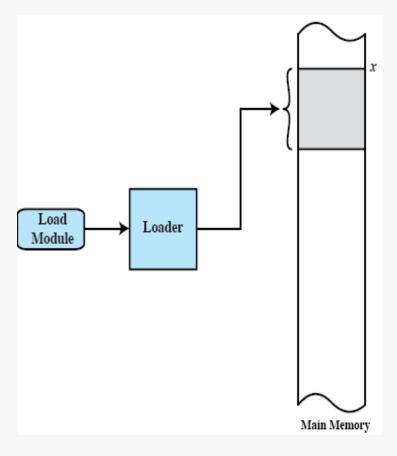
First step in process creation is to load the program into memory and create a process image.



Process Loading

The loader has the responsibility of placing the process image into memory, given the load module created by the linker.

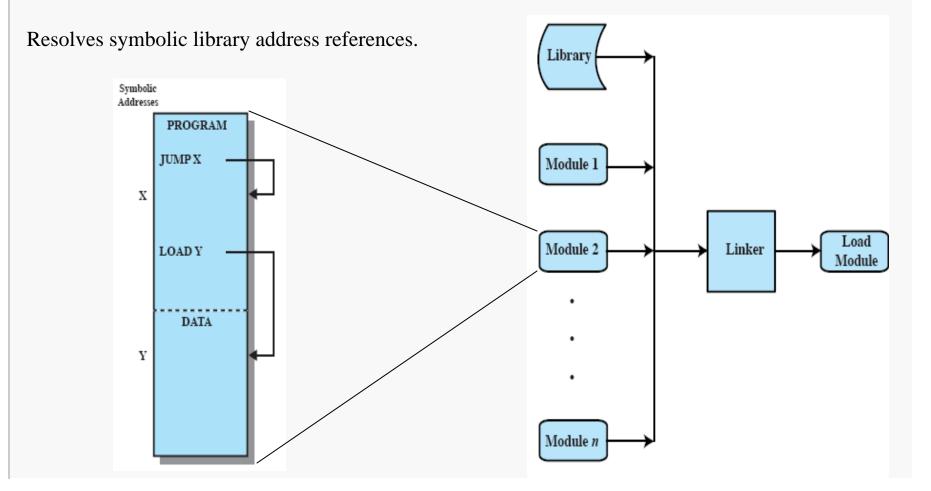
Here's a typical overview (assuming contiguous allocation of main memory):



Linking

The linker takes a collection of object modules as input and produces a load module, consisting of an integrated set of program and data modules, which will be processed by the loader.

Resolves symbolic inter-module address references.



Absolute Load Module

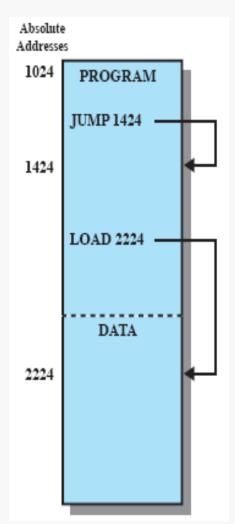
An absolute load module would be created by mapping references to absolute addresses depending upon a specific base address at load time:

Link-time binding of references to physical addresses.

Simple processing by linker.

Loader simply copies load module into memory.

Loader MUST copy load module to correct base address or program will not execute correctly.



Relative Load Module

A relative load module would be created by mapping references to relative addresses that would be translated to physical addresses at load time.

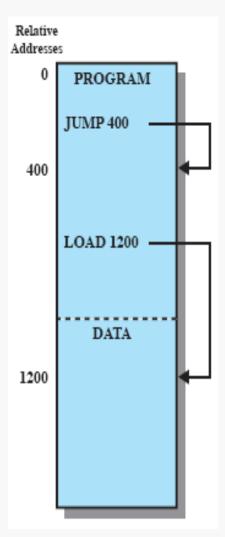
Load-time binding of relative references to physical addresses.

Linker must leave tags in the load module to guide the loader's actions – *relocation dictionary*.

Loader must find each relative address in the load module and add the base address (determined at load time) to it.

Too expensive for systems that use swapping to control system load.

Logically inadequate for systems that use paging or segmented memory management.



Dynamically Relocatable Load Module

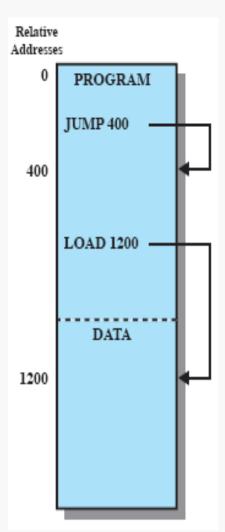
A dynamically relocatable load module would also be created by mapping references to relative addresses that would be translated to physical addresses at run time.

Run-time binding of relative references to physical addresses.

Loader merely copies load module with relative addresses into memory.

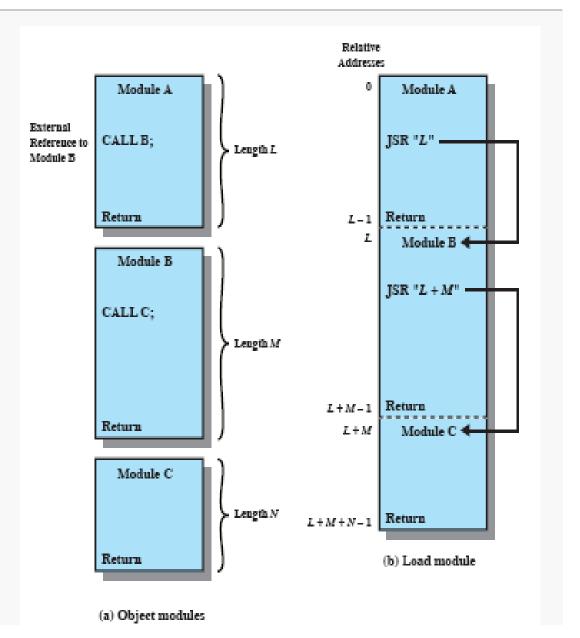
Hardware support MUST be provided to make this efficient.

Dominant form of loading on modern systems.



Object Module to Load Module

The linker that produces a relocatable load module works something like this:



Relocation and Hardware

Base register

Starting address for the process

Bounds register

Ending location of the process

These values are set when the process is loaded or when the process is swapped in

The value of the base register is added to a relative address to produce an absolute address

The resulting address is compared with the value in the bounds register

If the address is not within bounds, an interrupt is generated to the operating system

