

Project 2: User Programs

Abdelmounaam Rezgui

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Overview

- Objective: Enable user programs to run and interact with the OS via system calls
- Directories:
 - userprog/
 - threads/
 - examples/

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Using the File System -1-

- NOT the focus of this project
- User programs are loaded from the FS
- Many system calls deal with the FS (e.g., `open()`, `read()`, `write()`)
- Simple file system provided in the `filesys` directory
 - Look at: `filesys.h` and `file.h`
 - Limit is 16 files
 - No subdirectories

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Using the File System -2-

- Create a (simulated) disk:
 - `pintos-mkdisk <img-file> <size>`
 - `img-file` = filename for disk (usually "fs.dsk")
 - `size` = disk capacity, MB
- Format disk
 - `pintos -f -q`
 - `-f` = format, `-q` = quit after boot
- Copy to disk:
 - `Pintos -p <source> -a <dest> -- -q`
 - `-p` = source file, `-a` = filename on disk
- Run program:
 - `Pintos run <executable>`
- `$ make check`: will build a disk for you

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Sample user programs

- In `examples/`
 - `cat`, `echo`, `halt`, `hex-dump`, `ls`, `shell`
- You should be able to write and run your own programs
- Create a test disk
- Copy programs to the test disk

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Requirements

- 1) Argument passing
- 2) System calls
- 3) Process termination
- 4) Deny writes to executables
- 5) DESIGNDOC

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Getting Started

- In the default version, programs will crash
- To get simple programs to run:
 - `*esp = PHYS_BASE - 12;`
- This will **NOT** make argument passing work

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Argument Passing -1-

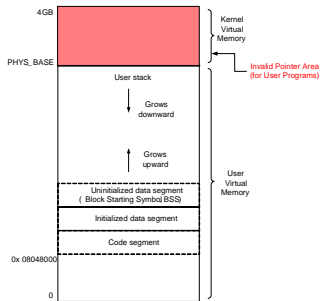
- Motivation:
 - kernel creates first process
 - one process creates another
- \$ pintos run 'pgm alpha beta'
- You may:
 - use `strtok_r()` to parse the command line
 - assume cmd line length < 4KB

```

pgm.c
main(int argc,
     char *argv[]) {
    ...
}
$ pintos run 'pgm alpha beta'
argc = 3
argv[0] = "pgm"
argv[1] = "alpha"
argv[2] = "beta"
    
```

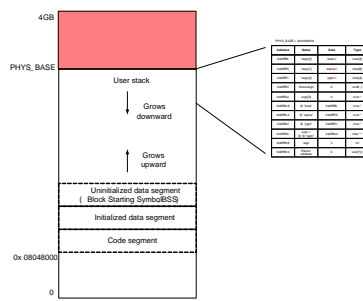
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Argument Passing -2-



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Argument Passing -3-



System Calls -1-

- User programs make **system calls**
 - E.g., `open()`, `close()`, `exit()`, `halt()`, ...
- Implement system calls:
 - Process control:
 - `exit()`, `exec()`, and `wait()`
 - Filesystem calls:
 - `create()`, `open()`, `close()`, `read()`, `write()`, `seek()`, `tell()`, `filesize()`, `remove()`
 - `halt()`

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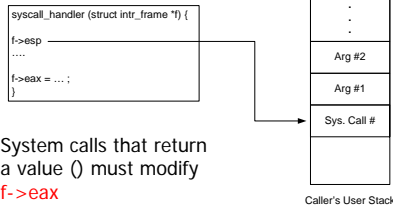
System Calls -2-

- The OS deals with **software exceptions** (called "internal interrupts" in the x86)
- SEs are events that occur in program code. They may be:
 - Errors: e.g., page faults, division by 0
 - System Calls
- SEs don't execute in interrupt context
 - i.e., `intr_context() == false`
- In the 80x86 arch, the 'int' instruction is used to make system calls
- In Pintos, user programs invoke 'int \$0x30' to make system calls

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System Calls -3-

- A system call has:
 - System call number
 - (possibly) arguments
- System call numbers are in: `lib/syscall-nr.h`
- When `syscall_handler()` gets control:



- System calls that return a value () must modify `f->eax`

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System Calls -4-

- Filesystem calls
 - You must decide how to implement file descriptors
 - O(n) data structures for file descriptors are OK
 - For **this** project, access granularity is the **entire** file system. Use **ONE** lock for the **entire** file system
 - `write(1, ...)` writes to the console. Use `putbuf()`.
 - `read(0, ...)` reads from the stdin (keyboard). Use `kbd_getc()`.

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System Calls -5-

- `exec(const char *cmd_line)`
 - Runs 'cmd_line', passes args, returns pid
- `exit()` retains error codes for `wait()`

```

main() {
    pid_t p;
    p = exec("cp file1 file2");
    ...
}

```

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System Calls -6-

- `wait(pid_t pid)`
 - Waits for process pid to die and returns the status that pid returned to `exit()`
 - Returns -1 if
 - pid was killed by the kernel
 - pid is not a child
 - Wait has already been successfully called

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System Calls -7-

- Parent may or may not wait for its child
- Parent may call `wait()` after child terminates!
- Implement `process_wait()` in `process.c`
- Then, implement `wait()` in terms of `process_wait()`
- Conditions and semaphores will help
 - Think about what semaphores may be used for and how they must be initialized

```
main() {
    int i; pid_t p;
    p = exec("pgm a b");
    i = wait (p);
    ... /* i must be 5 */
}
```

```
main() {
    int status;
    ... status = 5;
    exit(status);
}
```

pgm.c

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Process Termination

- Record the argument passed to the `exit()` syscall
- When a **user process** exits:

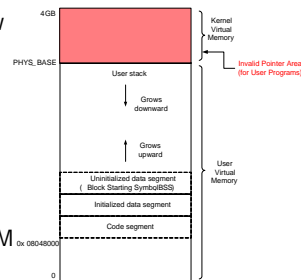

```
printf("%s: exit(%d)\n", ...)
```
- ALL programs call `exit()` unless, of course, if they're terminated
 - Returning from `main` implicitly calls `exit()`

```
_start() is { exit( main(...) ); }
```

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Virtual Memory Layout -1-

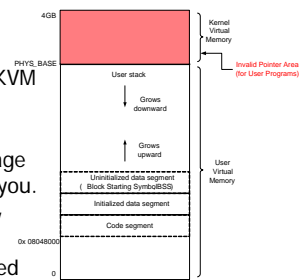
- Stack does **NOT** grow until Project 3
- Heap never grows
- Uninitialized means "zero-initialized"
- UVM is per-process
- A user program accesses only its UVM



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Virtual Memory Layout -2-

- If it attempts to access KVM → **Page fault**
- Kernel threads access KVM and the UVM of the **running** user process
- In **this** project, this image is **ALREADY** set up for you.
- You only have to query the page table to see which pages are mapped



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Memory Access -1-

- Kernel needs to access memory through pointers given by a user program
- user-provided pointers may be **invalid**
 - point to unmapped VM
 - point to KVM address space
- How to handle this ?

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Memory Access -2-

- Two options:
 - verify the validity of a user-provided pointer, then dereference it – **STRONGLY RECOMMENDED!**
 - dereference and handle **during** page fault
 - Check only that user pointer points below `PHYS_BASE`
 - Dereference it
 - If it causes a page fault, handle it
 - You need to modify the code for `page_fault()`

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Memory Access -3-

- In BOTH cases:
 - Graceful termination
 - Misbehaving processes must be killed
 - Orderly shutdown
 - No resource leaks
 - E.g., release locks, free allocated memory pages, etc.
- Data may span page boundaries

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Denying Writes to Executables

- You may use:
 - `file_deny_write()` to prevent writes to an open file
 - `file_allow_write()` re-enables them (if no other process has already denied them)
 - If a file is closed, writes are re-enabled.

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Misc

- Read **Section 4.2** (page 51) (Suggested Order of Implementation) in Pintos documentation
- Do not forget the **Design Document**
- **Good Luck !**

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