

Adding a System Call to a 2.6.x Linux Kernel

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Configuration Used to Develop These Instructions

- Dell laptop running Windows XP Pro
- Windows XP running VirtualPC
- VirtualPC running Mandrake Linux 9.2
- Mandrake 9.2 running modified 2.6.1 kernel

Prerequisites

- You must have root access (CS lab machines are not available).

Instructions to Add System Call

1. Download the latest version of the 2.6 Linux kernel from www.kernel.org.
2. Unzip and untar the kernel directory into /usr/src/.
3. In /usr/src/Linux-x.x.x/kernel/, Create a new file myservice.c to define your system call.

```
#include <Linux/linkage.h> //for linking a system call
#include <Linux/kernel.h> //for the printk
```

```
asmlinkage int sys_myservice (int arg1, char* arg2) {
    printk(KERN_EMERG "my service is running");
    //kernel messages logged to /var/log/kernel/warnings
    return(1);
}
```

4. In /usr/src/Linux-x.x.x/include/asm/unistd.h, define an index for your system call. **Your index should be the number after the last system call defined in the list.**

```
#define __NR_myservice      274
```

5. Also, you should increment the system call count.

```
#define __NR_syscalls      275
```

6. In /usr/src/Linux-x.x.x/arch/i386/kernel/entry.S, you should define a pointer to hold a reference to your system call routine. **It is important that your data entry placement corresponds to the index you assigned to your system call.**

```
.long sys_myservice
```

7. Add your system call to the Makefile in /usr/src/Linux-x.x.x/kernel/Makefile. Add your object after the other kernel objects have been declared.

```
obj-y += myservice.o
```

8. Make your system from /usr/src/Linux-x.x.x

```
make xconfig //save the defaults
make dep //make dependency list
make bzImage //build your kernel
```

9. Add a new boot image to Lilo, by editing /etc/lilo.conf. Your lilo configuration will vary slightly. After saving, run lilo -v to install your settings. **Don't just modify an existing lilo entry; you may need it if your new kernel has bugs.**

```
image=/usr/src/Linux-x.x.x/arch/i386/boot/bzImage
    label="Linux-test"
    root=/dev/hda5
    read-only
```

10. Making a user test file. You also need to copy your edited unistd.h from /usr/src/Linux-x.x.x/include/asm/ to /usr/include/kernel/ because it contains your system call's index.

```
#include <Linux/errno.h>
#include<sys/syscall.h>
#include <Linux/unistd.h>
```

```
long errno; //this is the return code from the system call
//this is a macro defined in unistd.h to help prototype sys calls
_syscall2(int, myservice, int, arg1, char*, arg2);
```

```
main() {
    myservice(1, "hi");
}
```

11. Reboot into your new kernel and compile your user test program to try out your system call. You will know if it worked if you see a kernel message in /var/log/kernel/warnings announcing that your service is running.