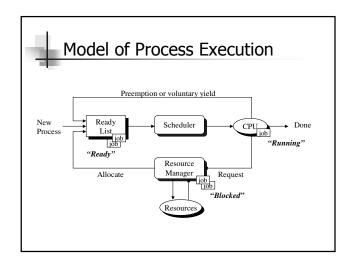
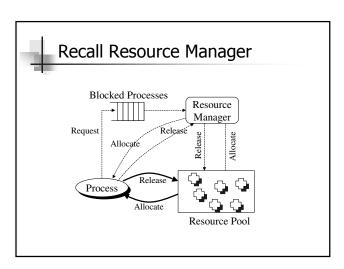
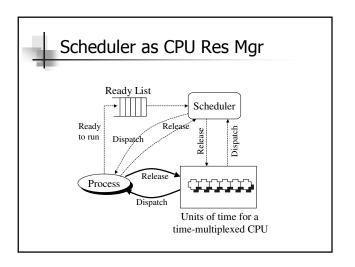
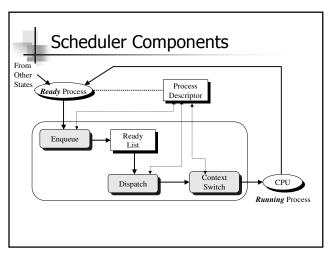


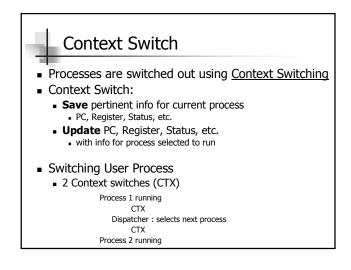
- Why do we even <u>need</u> to a process scheduler?
 - In simplest form, CPU must be *shared* by
 - OS
 - Application
 - In reality, [multiprogramming]
 - OS : many separate pieces (processes)
 - Many Applications
- Scheduling [Policy] addresses...
 - When to remove a process from CPU ?
 - Which ready process to allocate the CPU to ?

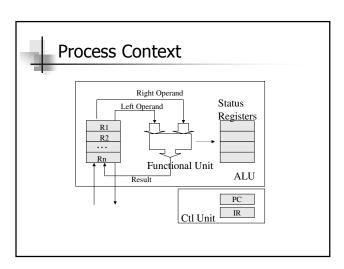


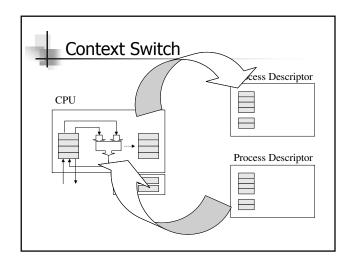














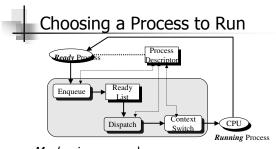
Invoking the Scheduler

- Need a *mechanism* to call the scheduler
- Voluntary call
 - Process blocks itself
 - Calls the scheduler
- Involuntary call
 - External force (interrupt) blocks the process
 - Calls the scheduler



Contemporary Scheduling

- Involuntary CPU sharing timer interrupts
 - <u>Time quantum</u> determined by interval timer – usually fixed size for every process using the system
 - Sometimes called the *time slice length*



- *Mechanism* never changes
- Strategy = <u>policy</u> the dispatcher uses to select a process from the ready list
- Different policies for different requirements



Policy Considerations

- Policy can control/influence:
 - CPU utilization
 - Average time a process waits for service
 - Average amount of time to complete a job
- Could strive for any of:
 - Equitability
 - Favor very short or long jobs
 - Meet priority requirements
 - Meet deadlines



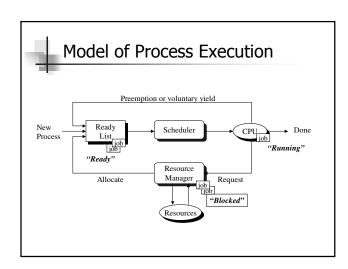
Optimal Scheduling

- Suppose the scheduler knows each process p_i's <u>service time</u>, τ(p_i) -- or it can estimate each τ(p_i):
- Policy can optimize on any criteria, e.g.,
 - CPU utilization
 - Waiting time
 - Deadline
- To find an optimal schedule:
 - Have a finite, fixed # of p_i
 - Know τ(p_i) for each p_i
 - Enumerate all schedules, then choose the best



However ...

- The τ(p_i) are almost certainly just estimates
- General algorithm to choose optimal schedule is O(n²)
- Other processes may arrive while these processes are being serviced
- Usually, optimal schedule is only a <u>theoretical benchmark</u> – scheduling policies try to <u>approximate</u> an optimal schedule





Selection Strategies

- Motivation
 - To "optimize" some aspect of system behavior
- Considerations
 - Priority of processExternal : assignedInternal : aging
 - Fairness : no starvation
 - Overall Resource Utilization

...



Selection Strategies...

- Considerations...
 - Turnaround time
 - Average time / job
 - Throughput
 - Jobs / time unit
 - Response time
 - System availability
 - Deadlines



- Let $P = \{p_i \mid 0 \le i < n\} = \text{set of processes}$
- Let S(p_i) ∈ {running, ready, blocked}
- Let $\tau(p_i)$ = Time process needs to be in running state (the *service time*)
- Let $W(p_i)$ = Time p_i is in ready state before <u>first</u> transition to running (<u>wait time</u>)
- Let T_{TRnd}(p_i) = Time from p_i first enter ready to last exit ready (<u>turnaround time</u>)
- Batch $\underline{Throughput \ rate}$ = inverse of avg T_{TRnd}
- Timesharing response time = W(p_i)



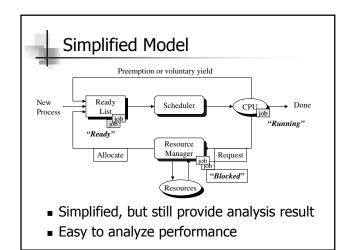
Definition & Terms

- Time Quantum
 - Amount of time between timer interrupts
 - Also called Time Slice
- Service Time τ (P_i)
 - Amount of time process needs to be in Running state (acquired CPU) before it is completed
- Wait Time W (P_i)
 - Time a process spends waiting in the Ready state before its first transition to the Running state



Definition & Terms...

- Turnaround Time T (P_i)
 - Amount of time between moment process first enters Ready state and the moment the process exits Running state for the last time (completed)
- Service time, Wait time & Turnaround time are measurable metrics used to compare scheduling algorithms

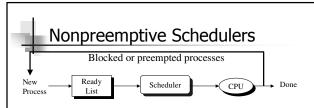




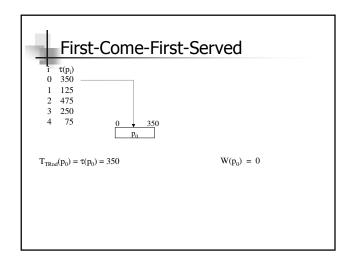
Classes of Scheduling Algorithms

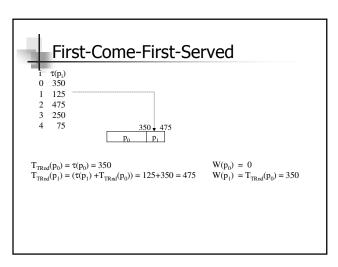
- 2 major classes
 - Non-preemptive
 - Run to completion
 - Preemptive
 - Process with highest priority always gets CPU

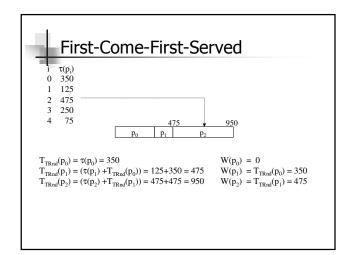
Recall: Several ways to establish priority

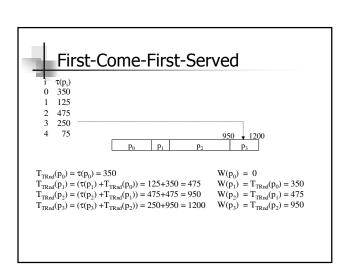


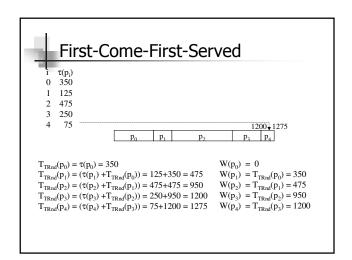
- Try to use the simplified scheduling model
- Only consider <u>running</u> and <u>ready</u> states
- Ignores time in <u>blocked</u> state:
 - "New process created when it enters ready state"
 - "Process is destroyed when it enters blocked state"
 - Really just looking at "small phases" of a process

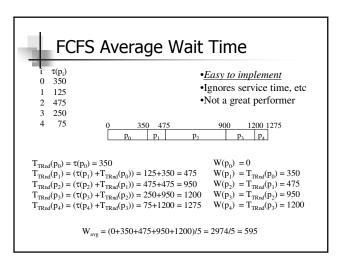


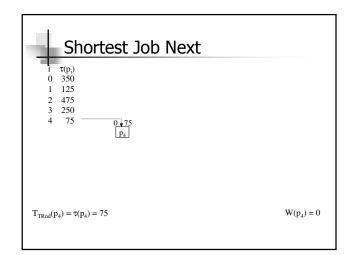


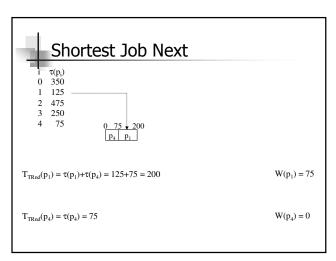


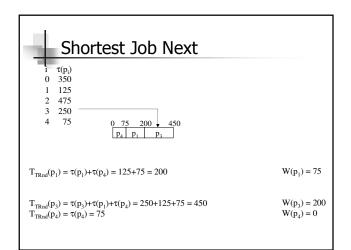


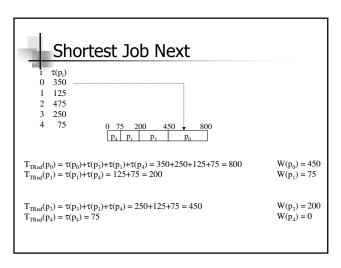


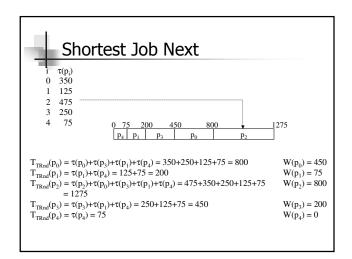


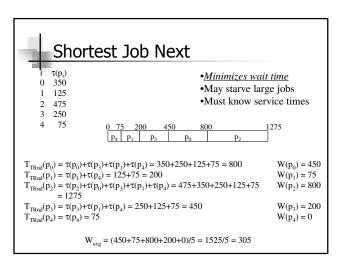


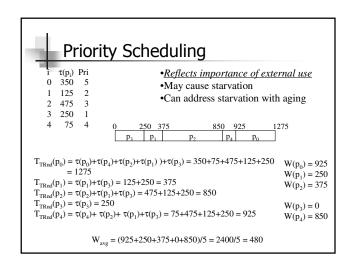


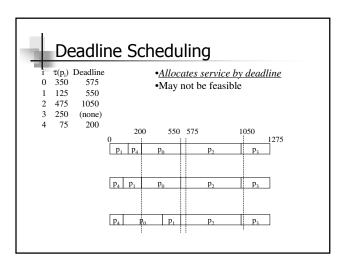


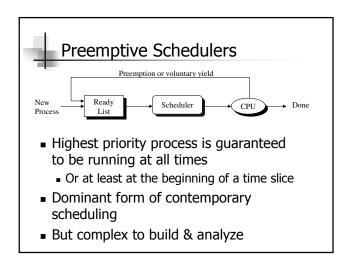


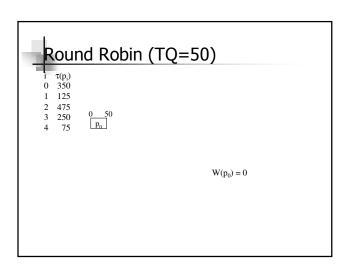








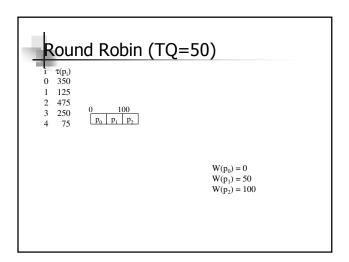


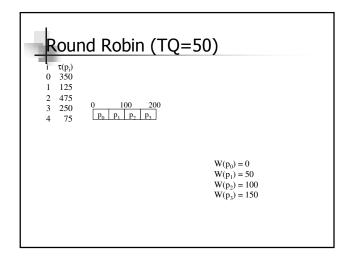


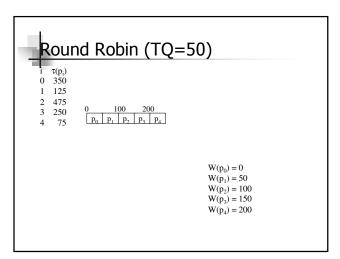
```
Round Robin (TQ=50)

1 \tau(p_1)
0 350
1 125
2 475
3 250
4 75
p_0
p_1

W(p_0) = 0
W(p_1) = 50
```



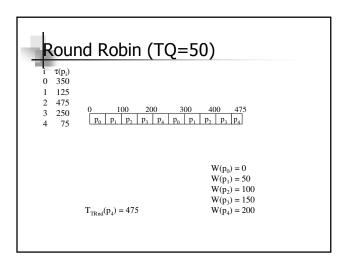


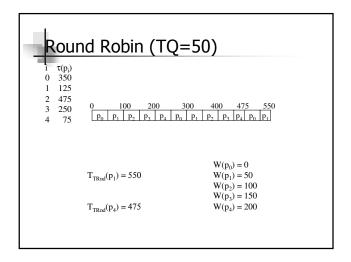


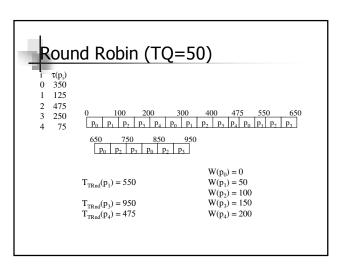
```
Round Robin (TQ=50)

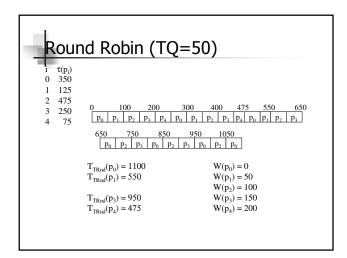
i \tau(p_1)
0 350
1 125
2 475
3 250
4 75

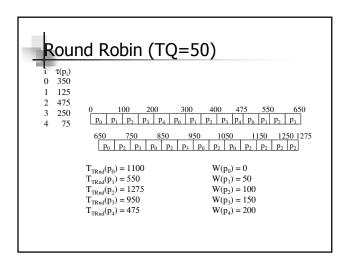
W(p_0) = 0
W(p_1) = 50
W(p_2) = 100
W(p_3) = 150
W(p_4) = 200
```

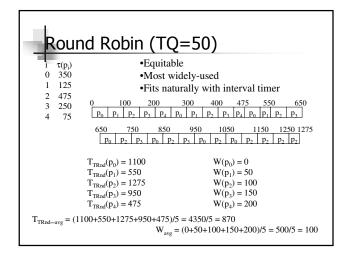


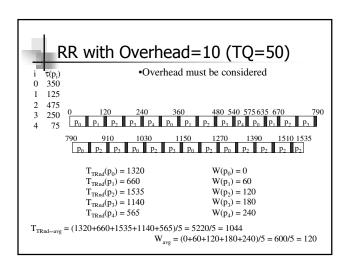


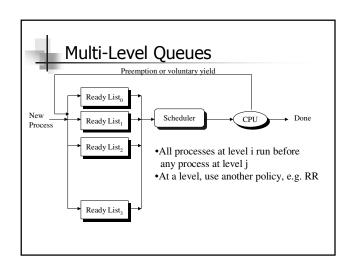






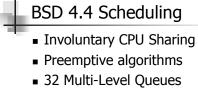




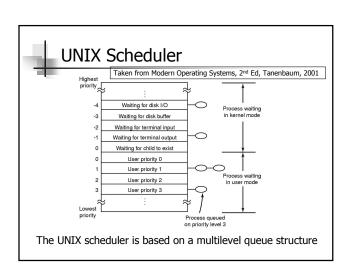


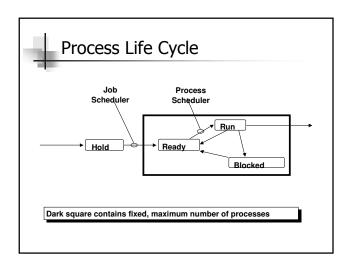
Contemporary Scheduling

- Involuntary CPU sharing -- timer interrupts
 - <u>Time quantum</u> determined by interval timer -usually fixed for every process using the system
 - Sometimes called the <u>time slice length</u>
- Priority-based process (job) selection
 - Select the highest priority process
 - Priority reflects policy
- With *preemption*
- Usually a variant of *Multi-Level Queues*



- Queues 0-7 are reserved for system functions
- Queues 8-31 are for user space functions
- nice influences (but does not dictate) queue level







Job Scheduler

- Controls when jobs will be allowed to contend the CPU
- Most popular techniques

FIFO First in, first out

SJF Shortest job first

Process Scheduler

- Controls when individual jobs (processes) will actually get the CPU
- Only interesting in multi-programming
- Most popular technique is Round Robin
 - Give each process one time slice in turn until complete

Turnaround and Weighted Turnaround Time

Let: N be number of jobs

A_i be arrival time of i-th job

F_i be finish time of i-th job

Turnaround time for ith job:

 $T_i = F_i - A_i$

Average turnaround time for ith job:

 $T = \Sigma T_i / N$

Weighted turnaround time for ith job:

 $WT_i = (F_i - A_i) / (Service-time)_i$

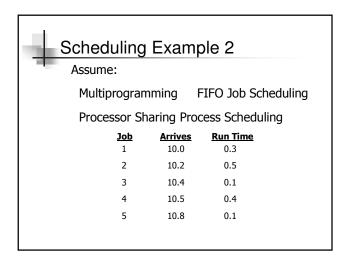
Average Weighted Turnaround time:

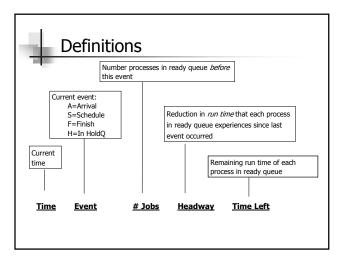
 $WT = \Sigma WT_i / N$

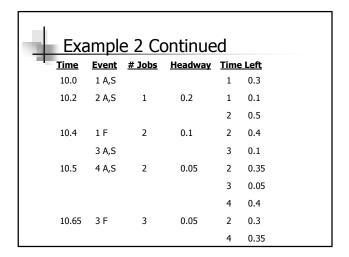


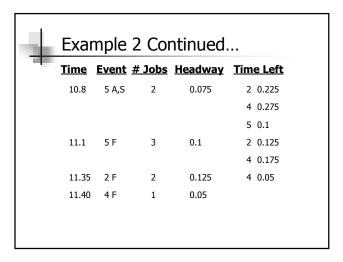
Processor Sharing (PS) "Theoretical" Scheduling Algorithm

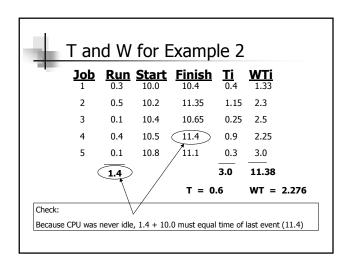
- Limit of RR as time quantum goes to zero.
- Like giving each CPU cycle to a different process, in round robin fashion.
- N processes scheduled by PS
 - Each job runs on dedicated *N*-fold slower CPU.
 - Thus, READY = RUNNING.
- CPU Time "shared" equally among processes

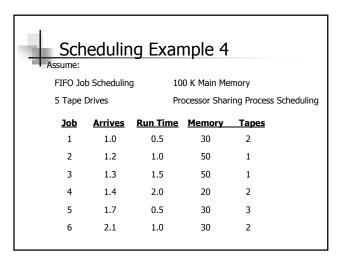


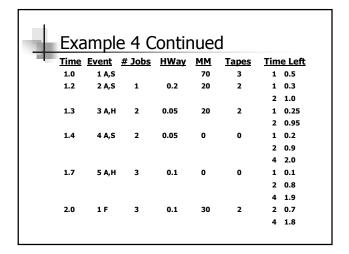












Exa	amp	le 4 (Con	tinue	ed	
<u>Time</u>	<u>Event</u>	# Jobs	<u>HWay</u>	<u> MM</u>	<u>Tapes</u>	Time Left
2.1	6 A,S	2	0.05	0	0	2 0.65
						4 1.75
						6 1.0
4.05	2 F	3	0.65	50	1	4 1.1
	3 S			0	0	6 0.35
						3 1.5
5.1	6 F	3	0.35	30	2	4 0.75
						3 1.15
6.6	4 F	2	0.75	50	4	3 0.4
	5 S			20	1	5 0.5
7.4	3 F	2	0.4	70	2	5 0.1
7.5	5 F	1	0.1	100	5	

T ar	nd W	for E	Exam	ole 4	
Job 1	Run 0.5	Arrives 1.0	Finish 2.0	<u>Ti</u> 1.0	<u>WTi</u> 2.0
2	1.0	1.2	4.05	2.85	2.85
3	1.5	1.3	7.4	6.1	4.06
4	2.0	1.4	6.6	5.2	2.6
5	0.5	1.7	7.5	5.8	11.6
6	2.1	2.1	5.1	3.0	3.0
Т :	= 3.99	WT :	= 4.35	23.95	26.11