Chapter 9



High-level Synchronization

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Introduction to Concurrency

Concurrency

- Execute two or more pieces of code "at the same time"
- Why?
 - No choice:
 - Geographically distributed data
 - Interoperability of different machines
 - A piece of code must "serve" many other client processes
 - To achieve reliability
 - By choice:
 - To achieve speedup
 - Sometimes makes programming easier (e.g., UNIX pipes)



Possibilities for Concurrency

Architecture:	Program Style:

Uniprocessor with:	Multiprogramming,
- I/O channel	multiple process system
- I/O processor - DMA	programs
Multiprocessor	Parallel programming
Network of processors	Distributed Programs

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Examples of Concurrency in Uniprocessors

Example 1: Unix pipes

Motivations:

- fast to write code
- fast to execute

Example 2: Buffering

Motivation:

- required when two <u>asynchronous</u> processes must communicate

Example 3: Client/Server model

Motivation:

- geographically distributed computing



Operating System issues to Support Concurrency

Synchronization

• What primitives should OS provide?

Communication

What primitives should the OS provide to the interface communication protocol?

Hardware Support

Needed to implement OS primitives

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Operating System issues to Support Concurrency...

Remote execution

- What primitives should OS provide?
 - Remote Procedure Call (RPC)
 - Remote Command Shell

Sharing address space

Makes programming easier

Light-weight threads

Can a process creation be as cheap as a procedure call?



Definitions

- Concurrent process execution can be:
 - interleaved, or
 - physically simultaneous
- Interleaved
 - Multi-programming on uniprocessor
- Physically simultaneous
 - Uni- or multi-programming on multiprocessor

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Definitions...

- Process, thread, or task
 - Scheduleable unit of computation
- Granularity
 - Process "size" or computation to
 - Communication ratio
 - Too small: excessive overhead
 - Too large: less concurrency

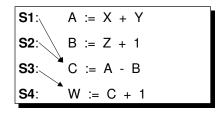


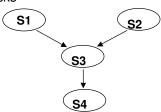
Precedence Graph

Consider writing a program as a set of tasks.

Precedence graph:

specifies execution ordering among tasks





Parallelizing compilers for computers with vector processors build dependency graphs.

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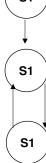
Cyclic Precedence Graph

What does the following graph represent?

S2 must be performed before S3 begins

AND

S3 must be performed before S2 begins



Precedence Graphs must be **ACYCLIC**



Concurrency Conditions

Let *Si* denote a statement.

Read set of Si:

$$R(Si) = \{ a1, a2, ..., an \}$$

Set of all variables referenced in Si

Write set of Si:

$$W(Si) = \{ b1, b2, ..., bm \},\$$

Set of all variables changed by Si

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Concurrency Conditions...

$$C := A - B$$

$$R(C := A - B) = \{A, B\}$$

$$W(C := A - B) = \{C\}$$

cin >> A

$$R (cin >> A) = \{ \}$$

$$W (cin >> A) = \{ A \}$$



Bernstein's Conditions

The following conditions must hold for two statements S1 and S2 to execute concurrently with valid results:

- 1) R(S1) INTERSECT $W(S2) = \{\}$
- 2) W(S1) INTERSECT $R(S2) = \{\}$
- 3) W(S1) INTERSECT $W(S2) = \{\}$

These are called the **Bernstein Conditions**.

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Structured Parallel Constructs

PARBEGIN / PAREND

PARBEGIN

Sequential execution splits off into several concurrent sequences

PAREND

Parallel computations merge

PARBEGIN

Statement 1;

Statement 2;

0 0

Statement N;

PAREND;

PARBEGIN

Q := C mod 25;

Begin

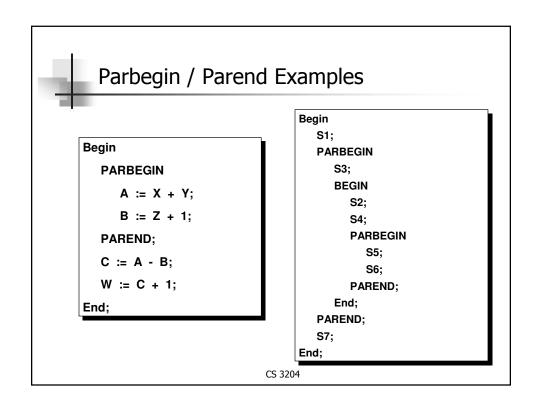
N := N - 1;

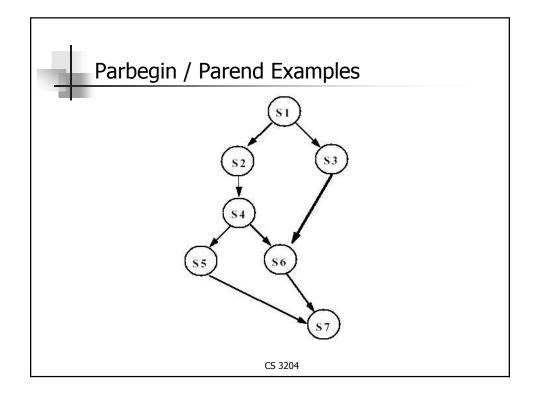
T := N / 5;

End;

Proc1 (X, Y);

PAREND;







Synchronization with Monitors



Monitors

- P & V are primitive operations
- Semaphore solutions are difficult to accurately express for complex synchronization problems
- Need a High-Level solution: Monitors
- A Monitor is a collection of procedures and shared data
- Mutual Exclusion is enforced at the monitor boundary by the monitor itself
- Data may be global to all procedures in the monitor or local to a particular procedure
- No access of data is allowed from outside the monitor



Condition Variables

- Within the monitor, Condition Variables are declared
- A queue is associated with each condition variable
- Only two operations are allowed on a condition variable:

X.wait The procedure performing the wait is put on the queue associated with x
 X.signal If queue is non-empty: resume some process at the point it was made to wait

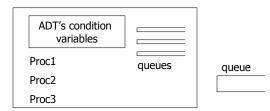
- Note: V operations on a semaphore are "remembered," but if there are no waiting processes, the signal has no effect
- OS scheduler decides which of several waiting monitor calls to unlock upon signal

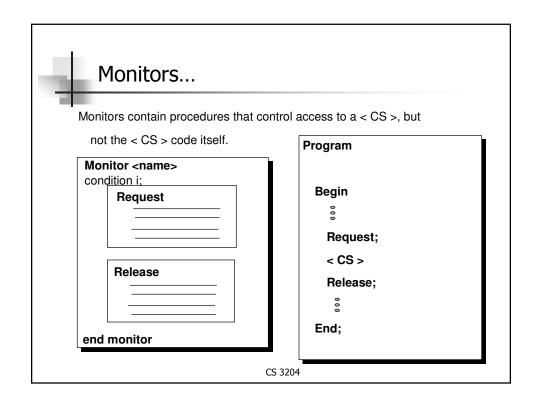
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Monitor...

- Queue to enter monitor via calls to procedures
- Queues within the monitors via condition variables
- ADTs and condition variables <u>only</u> accessible via monitor procedure calls





N-Process Critical Section: **Monitor Solution** Monitor NCS { OK: condition Busy: boolean <-- FALSE Request() { if (Busy) OK.wait; Busy = TRUE; Procedure P { Release() { NCS.Request(); Busy = FALSE; <CS>; NCS.Release(); OK.signal; main() { parbegin P;P;P;P; parend } CS 3204



Shared Variable Monitor

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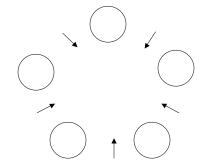
Reader & Writer Schema

```
writer() {
reader() {
                                         while(true) {
  while(true) {
                                              . . .
        . . .
                                              startWrite();
       startRead();
                                              <write resource>
       <read the resource>
                                             finishWrite();
       finishRead();
                      fork(reader, 0);
                      fork(reader, 0);
                       fork(writer, 0);
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```

Reader & Writers Problem: The solution

```
monitor reader_writer_2{
   int numberOfReaders = 0;
   boolean busy = false;
   condition okToRead, okToWrite;
public:
   startRead(){
       if(busy || okToWrite.queue) okToRead.wait;
        numberOfReaders = numberOfReaders+1;
        okToRead.signal;
   finishRead() {
        numberOfReaders = numberOfReaders-1;
        if (numberOfReaders =0) okToWrite.signal;
   startWrite(){
        if(busy || numberOfReaders != 0) okToWrite.wait;
        busy = true;
   finishWrite() {
        busy = false;
        if(okToWrite.queue) okToWrite.signal;
        else okToRead.signal;
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```

Dining Philosophers' Problem



while(TRUE) {
 think();
 eat();
}

Dining Philosophers' Problem: The solution

```
enum status {eating, hungry, thinking};
monitor diningPhilosophers{
   status state[N]; condition self[N]; int j;
// This procedure can only be called from within the monitor
   test(int i) {
        if((state[i-1 MOD N] != eating) && (state[i] == hungry)
                && (state[i+1 MOD N] != eating) ) {
            state[i] = eating;
            self[i].signal;
public:
  pickUpForks(){
        state[i] = hungry;
        if(state[i] != eating) self[i].wait;
   putDownForks(){
        state[i] = thinking;
        test(i-1 MOD N); test(i+1 MOD N);
   diningPhilosophers() { // Monitor initialization code
        for(int i=0; i<N; i++) state[i] = thinking;</pre>
```

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Monitor implementation of a ring buffer

```
monitor ringBufferMonitor;
var ringBuffer: array[0..slots-1] of stuff;
    slotInUse: 0..slots;
    nextSlotToFill: 0..slots-1;
    nextSlotToEmpty: 0..slots-1;
    ringBufferHasData, ringBufferHasSpace: condition;
procedure fillASlot(slotData: stuff);
begin
    if(slotInUse = slots) then wait(ringBufferHasSpace);
        ringBuffer[nextSlotToFill] := slotData;
        slotInUse := slotInUse + 1;
        nextSlotToFill := (nextSlotToFill+1) MOD slots;
        signal(ringBufferHasData);
end;
```



Monitor implementation of a ring buffer...

```
procedure emptyASlot(var slotData: stuff);
begin

if(slotInUse = 0) then wait(ringBufferHasData);
slotData := ringBuffer[nextSlotToEmpty];
slotInUse := slotInUse - 1;
nextSlotToEmpty := (nextSlotToEmpty-1) MOD slots;
signal(ringBufferSpace);
end;
begin

slotInUse := 0;
nextSlotToFill := 0;
nextSlotToEmpty := 0;
end.
```