

Slides

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Single Source File Programs

- Programs where all the code is contained within 1 file.
- Large programs results in problems.

Disadvantages

- Very long compile time
- Errors requires recompilation of entire program
- Difficult to edit

Multi-File Programs

- Code for a program is stored in several source files.

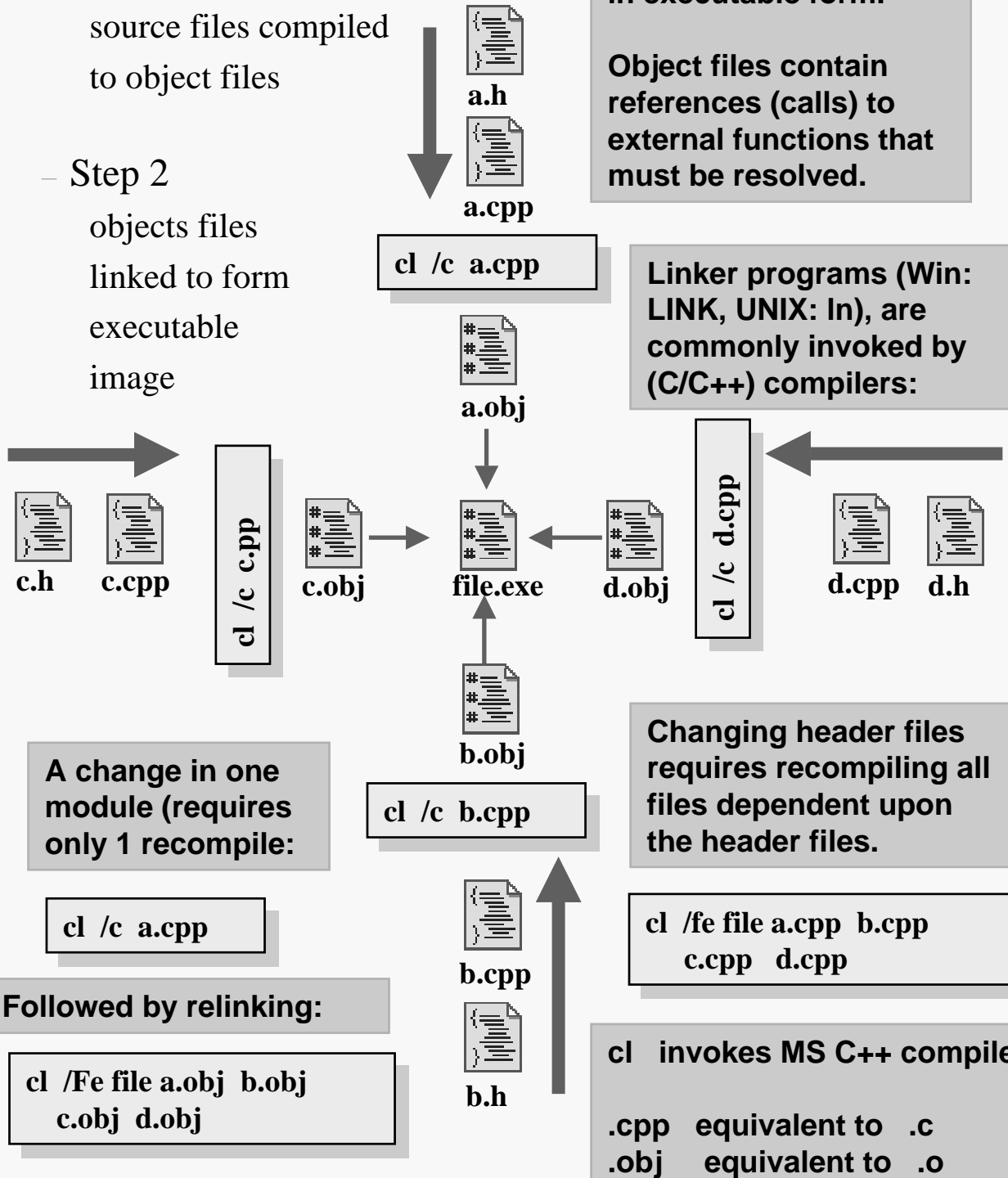
Advantages

- Decreases re-compile time for errors.
 - ‡ Modification of code in one file does NOT require compilation of other files, (exception: if function interfaces have changed).
- Programs can be broken into smaller, simpler subsystems.
- Separate compilation helps support structured methods and modular decomposition for developing large systems.
- Allows languages to be used in conjunction with other programming languages.
- Eases testing in large systems.
- Allows access to system functions, code libraries and packages.
- Facilitates code reusability.



Separate Compilation Steps

- Step 1
source files compiled
to object files
- Step 2
objects files
linked to form
executable
image



C++ Module Components

– Two Files:



a.h

† **Interface File:** (header file .h) contains *public* declarations of all articles that are accessible (visible) and usable by external modules that include the interface file.

‡ Articles consist of constants, typedefs, enum types, class/struct declarations and function prototypes (only parameter types need to be specified, parameter names included are ignored by the compiler).



a.cpp

† **Implementation File:** (code file .c or .cpp) contains *private* declarations and definitions of all articles that are inaccessible (invisible) and **NOT** usable by external modules that include the interface file.

‡ The full declarations of the function prototypes given in the header file are specified.

‡ Articles declared in the implementation file that are **NOT** declared in the interface file are considered local/internal to the module and can only be accessed by the module's code **NOT** by external code.

Traditional C Function Declarations

- Parameter type lists cannot be included in Fn declarations

```
int fn( );
```

- ANSI C compilers will accept traditional C Fn declarations.
- Compiler does NOT know the types of the parameters.
- Compiler cannot perform type checking on the arguments.
- Compiler cannot perform coercion/conversion/promoting between parameters & arguments.

```
longint = fn(longint);
```

† above call will yield incorrect results



Mixing Traditional C & C++ Function Declarations

- Prototypes are required in C++
- In defining functions and their prototypes, using void in the parameter types lists is optional:

```
void fn( );    «=»    void fn( void );
```

- void is NOT a keyword in traditional C

```
int fn( );
```

- The above declaration specifies that fn accepts an unknown number of arguments.

Traditional C Function Invocation Declarations

- Function calls prior to fn definitions results in default declarations.
- Example:

```
fn(x); /* encountered before fn declaration */
```

- Assumed default declaration:

```
int fn();
```

- Parameter list attributes are unknown.
- No type checking or coercion/conversion can be performed.

Traditional C Function Definitions & Invocation

- Traditional C fn declaration/definition prior to invocation:

```
int    fn(x);  
long   x;  
{ - - - }
```

- Traditional “C” compilers still treat the parameter list attributes as unknown.
- Programmer has the responsibility for ensuring that the correct number and type of arguments are passed.

C++ Function Prototypes

- Compiler performs type checking of parameters & arguments.

Declarations & Definitions

- Declarations give only the attributes of identifiers (type).
- Definitions give the attributes of identifiers and reserves storage.
- Identifiers can only be defined once in a program, but may be declared multiple times.
- Definitions should **NOT** be placed in header files.

External Definitions

- Definitions that occur outside all functions in a file.
- Scope extends to the end of the file.
- Cannot be accessed outside of file, unless declared as an **extern** identifier in separately compiled files.

```
extern int x;  
extern void fn(long);
```

Array sizes must be given in definitions but are optional in declarations.



- Extern declarations are NOT definitions (no storage is reserved, no initialization can be performed).

Global (separate compilation) Variables

- extern declarations allow for common storage across compilation units.
- extern declarations are to **avoided at all costs** due to the same problems inherent in their use in single file programs.

Problem Statement

- Separate files may use the same header file.
 - † Assume a programmer has stored system wide constants in: **const.h**
 - † Assume **const.h** is included in the modulea header file: modulea.h
 - † Assume moduleb includes modulea.h and **const.h**.
- **const.h** header definitions would be duplicated in moduleb.cpp after preprocessing

Solution: Conditional Compilation

- Preprocessor directives:

`#if` `#ifdef` `#ifndef` `#elif` `#else`
`#endif` `#undef` `#define`

- Usage: const.h

`#ifndef` `CONST_H`
`#define` `CONST_H`

type definitions,
constants, etc...

**CONST_H is a
preprocessor
identifier not a
C/C++ identifier**

`#endif`

- Inclusion of const.h instructs the preprocessor to check if `CONST_H` has been previously defined during preprocessing. If it has not then it is defined and the const.h declarations are copied into the source, otherwise no inclusion occurs.

defined Preprocessor Directive

```
defined < identifier >
```

- Evaluates to true if the identifier has been previously defined in the preprocessing.

Platform Specific Compilation

```
#define WIN9x      or      #define WINNT2K
    .                .                .

#if defined(WIN9x )
    // WIN9x specific code
#elif defined(WINNT2K)
    // WINNT2K specific code
#else
    .                .                .

#endif
```

Preprocessor directives other than those covered here are available.

Debugging

- Can be utilized to compile or skip diagnostic output statements
- Two Methods:

```
#define  DEBUG      1
    .                .                .

#if  DEBUG
    cout << "Debug:" << string1 << endl;
#endif
```

```
#define  DEBUG
    .                .                .

#ifdef  DEBUG
    cout << "Debug:" << string1 << endl;
#endif
```

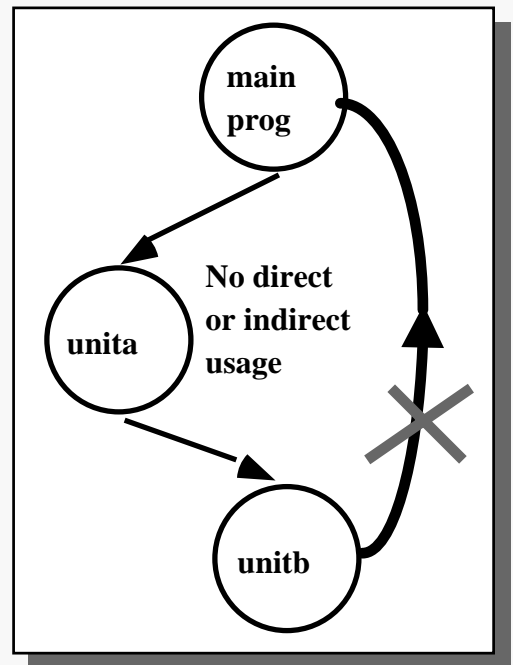
Lifetime

- Variables declared above all functions in a source file (file-scoped) and inside of main() exist throughout the execution (life) of the program — since main() drives all other routines.
- All other variables declared inside of functions exist only for the lifetime (execution) of the function (automatic) — excluding static (and extern).

– Restricted Access

– Given the diagram at the right:

- The main program only needs to call routines in unit A, and does not require any access to routines, consts, or other elements in unit B.
- Unit A needs only to call the routines in unit B.



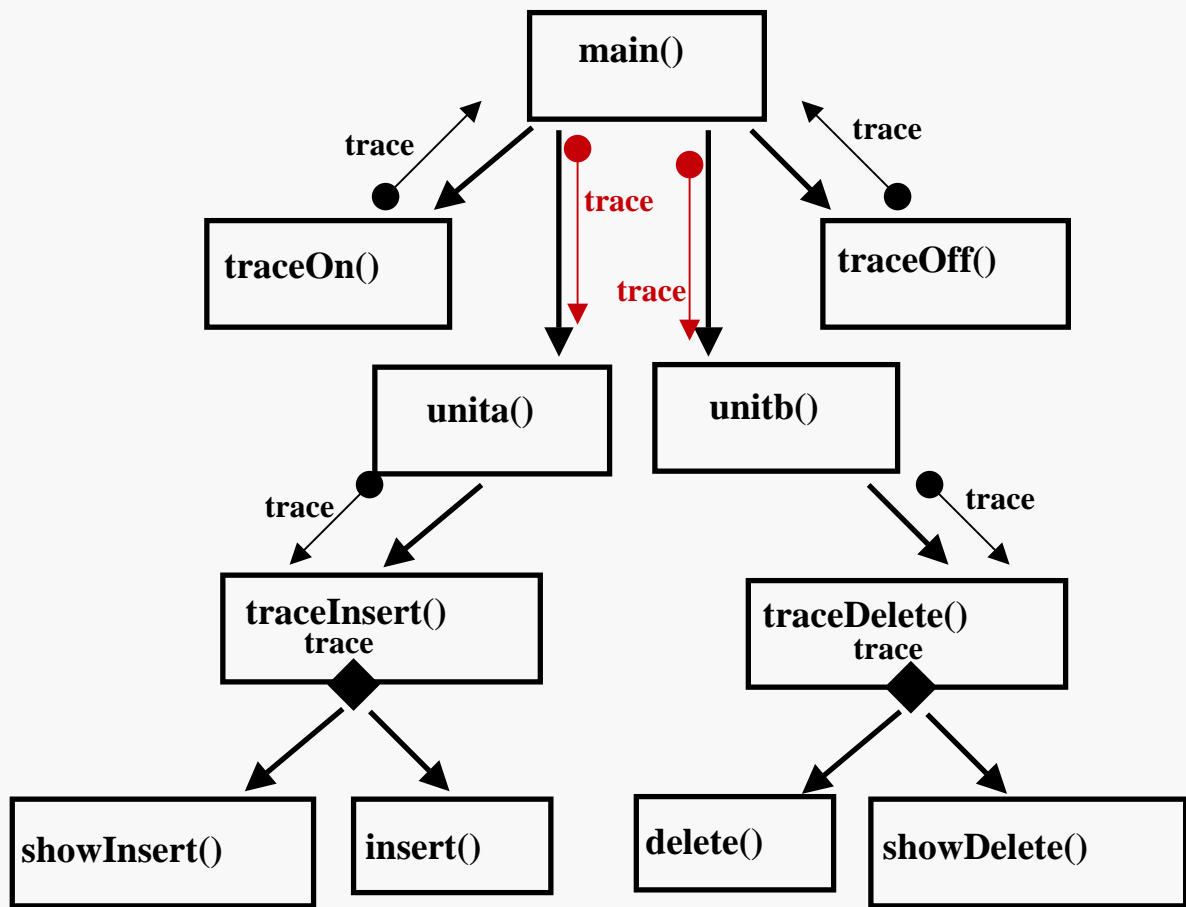
```
//main.cpp
#include "main.h"
#include "const.h"
#include "unita.h"
void main()
{
}
```

```
// unita.cpp
#include "const.h"
#include "unita.h"
#include "unitb.h"
```

```
// unitb.cpp
#include "const.h"
#include "unitb.h"
```

Restricted Access

- Problem: Special graphical trace/debug routines need to be executed at particular times during system execution.
 - † Trace flag is not needed for unitA or unitB.
 - † Complicates interfaces and exposes trace to possible or accidental misuse.



- ✗ - Solution 1: Make Trace global. Simplifies interfaces but does not solve scope problem.
- ✓ - **Solution 2:** Hide trace in the private declarations of a separately compiled module, limit access to module functions.

tracer.h

```
#ifndef TRACER_H
#define TRACER_H

void initTrace(void) ;
void traceOn(void) ;
void traceOff(void) ;
bool traceActive(void);

#endif
```

tracer.cpp

```
#include "tracer.h"

bool trace;

void initTrace(void)
    { trace = false; }

void traceOn(void)
    { trace = true; }

void traceOff(void)
    { trace = false; }

bool traceActive()
    { return trace; }
```

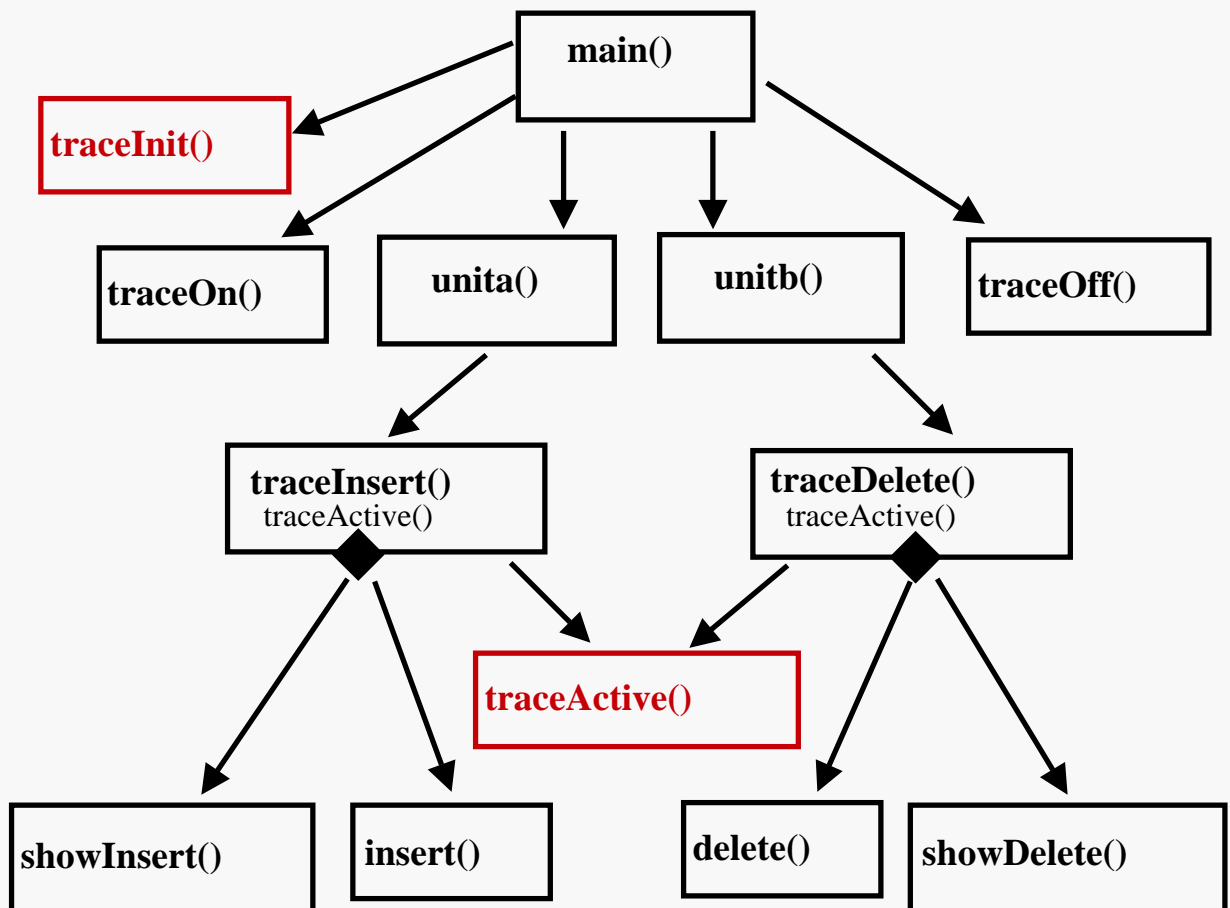
**Localized 'global'
variable**

**trace can be accessed
and changed in any
function in tracer.cpp,
but NOT in any code
external to tracer.cpp**

**Achieves information
hiding/encapsulation
that a class
implementation would
provide.**

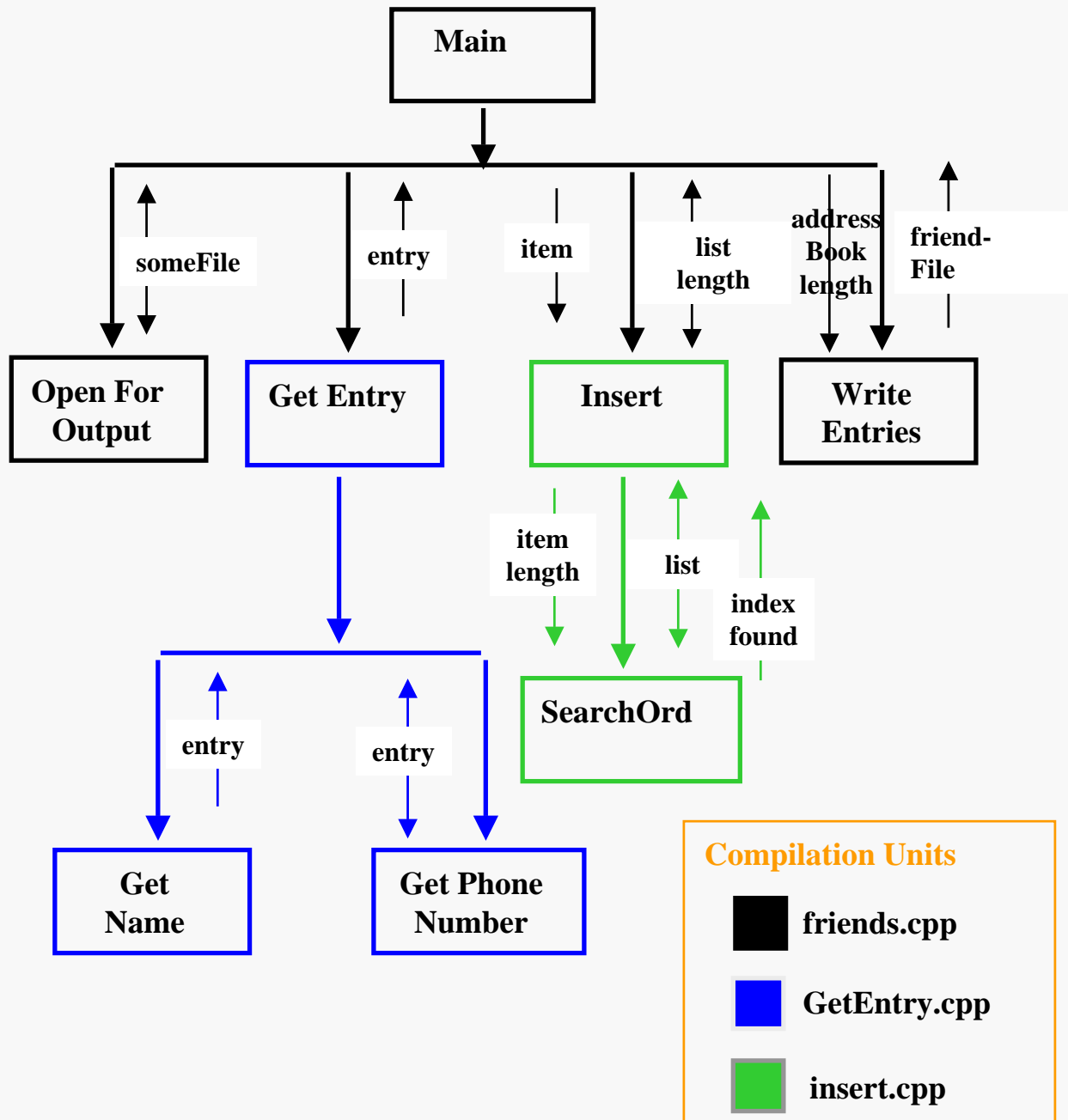
Tradeoff

- Interface simplification achieved at increase of number of system modules.



Reference

- adapted from: “*Programming and Problem Solving with C++*”, N. Dale, C. Weems & M. Headington, D.C. Heath, ©1996, 794-808.



globals.h

```
#ifndef GLOBALS_H
#define GLOBALS_H

#include <iostream>
#include <iomanip> // For setw()
#include <fstream> // For file I/O
#include <cctype> // For toupper()
using namespace std;

const int MAX_FRIENDS = 150; // Max number of friends

typedef char String8[9]; // 8 characters plus '\0'
typedef char String15[16]; // 15 characters plus '\0'

struct EntryType
{
    String15 firstName;
    String15 lastName;
    int areaCode; // Range 100..999
    String8 phoneNumber;
    int month; // Range 1..12
    int day; // Range 1..31
    int year; // Range 1900..2100
};

void OpenForOutput( ofstream& );
void WriteEntries( const EntryType[], int, ofstream& );

#endif
```

globals.h does NOT correctly model the structure chart program design.

friends.cpp

```
/**
 * Friends program
 * This program creates an address book by reading
 * first names, last names, phone numbers, and birth
 * dates from standard input and writing an alphabetical
 * listing to an output file
 */

#include "globals.h"      // global constants & types
#include "GetEntry.h"    // address book building
#include "insert.h"      // insert sort of address book

int main()
{
    EntryType addressBook[MAX_FRIENDS]; // friends' recs

    int length = 0; // Number entries addressBook
    EntryType entry; // Current rec being read
    char response; // Response char
    ofstream friendFile; // Output file entries

    OpenForOutput(friendFile);
    if ( !friendFile )
        return 1;

    // . . .

}
```


GetEntry.h

```

//*****
// Friends program
// GetEntry.h header file
//*****

#ifndef GetEntry_H
#define GetEntry_H

#include "globals.h"    // For global constants & types

void GetEntry( EntryType& );
void GetName( EntryType& );
void GetPhoneNumber( EntryType& );

#endif

```

Why does GetEntry.h incorrectly model the design of the program structure chart?

GetEntry.cpp

```

#include "GetEntry.h"    // For header file

// *****

void GetEntry( /* out */ EntryType& entry )
{
    GetName(entry);
    GetPhoneNumber(entry);
    cout << "Enter birth date as 3 integers, separated by"
         << " spaces: MM DD YYYY" << endl;
    cin >> entry.month >> entry.day >> entry.year;

    // . . .
}

```

insert.h

```
// *****
// Friends program
// insert.h header file
// *****

#ifndef INSERT_H
#define INSERT_H

#include <string.h> // For strcmp()
#include "globals.h" // For global constants & types

void Insert( EntryType[], int&, EntryType );
void SearchOrd( EntryType[], EntryType, int,
               int&, bool& );

#endif
```

Why does insert.h incorrectly model the design of the program structure chart?

Should #includes be placed in the "header.h" files or the "source.cpp" files?

insert.cpp

```
// *****
// Friends program
// insert.cpp file
// *****

#include "insert.h" // For header file

//*****

void Insert( /*inout*/ EntryType list[], // Changed List
            /*inout*/ int& length, // List Length
            /*in*/ EntryType item ) // Insert Item
{
    // Inserts item into its proper place in the sorted list
    // . . .
}
```

```
// Array.h: a static array of Item variables
//
// This class provides an encapsulation of a fixed size array.
//
// The Items are stored in ascending order; it is assumed that
// the relational operators are provided for type Item.

#ifndef ARRAY_H
#define ARRAY_H
#include <iostream>
#include <iomanip>
using namespace std;

#include "Item.h"

const int SIZE = 1000;

class Array {
private:
    int Capacity; // max # of elements list can hold
    int Usage; // # of elements currently in list
    Item List[SIZE]; // the list

    void ShiftTailUp(int Start); // implementation exercise
    void ShiftTailDown(int Start); // implementation exercise
public:
    Array(Item Init = Item()); // Each cell stores copy of Init
    int getCapacity() const; // retrieve Capacity
    int getUsage() const; // Usage
    bool isFull() const; // ask if List is full
    bool isEmpty() const; // or empty
    // insert newValue if not a duplicate
    bool Insert(const Item& newValue);
    bool DeleteAtIndex(int Idx); // delete element at index Idx
    // find index of first occurrence of given value
    int Locate(const Item& toFind) const;
    Item& Get(int Idx); // get reference to element at
    // index Idx
    ~Array(); // destroy Array object
};

#endif
```

```
// Array Class Implementation
//
#include "Array.h"

#include <cstdlib>          // for NULL
#include <cassert>
using namespace std;

////////////////////////////////////// constructor

////////////////////////////////////// Array()
// Initializes list entries to the specified value.
//
// Parameters:
//   Init      value to be stored in each cell
//
// Returns:   none
//
// Pre:      Init has been initialized.
// Post:     Array object has been constructed with List[]
//           of dimension SIZE, usage zero, and each
//           cell holding a copy of Init.
//
// Calls:    none
// Called by: none
//
Array::Array(Item Init) {

    Capacity = SIZE;
    Usage    = 0;

    int Idx;
    for (Idx = 0; Idx < Capacity; Idx++)
        List[Idx] = Init;
}
```

```
////////////////////////////////////////// insert functions
////////////////////////////////////////// Insert
// If newValue does not occur in List[], inserts it in
// correct (ordered) position.
//
// Parameters
//     newValue    Item variable to be inserted.
//
// Returns:      true if insertion succeeded; false otherwise
//
// Pre:         newValue has been initialized.
// Post:        If List[] is full no changes are made.
//              Otherwise, if newValue does not occur in
//              List[] it is inserted at the proper index
//              and the Usage is adjusted accordingly.
//
// Calls:       ShiftTailUp()
// Called by:   none
//
bool Array::Insert(const Item& newValue) {

    if (Usage == Capacity) return false; // array is full

    int Idx = 0;
    while ( (Idx < Usage) && (newValue > List[Idx]) ) {
        Idx++;
    }

    if (newValue == List[Idx]) return false; // already present

    ShiftTailUp(Idx);
    List[Idx] = newValue;
    Usage++;
    return true;
}
```

```
//////////////////////////////////// delete functions
//////////////////////////////////// DeleteAtIndex
// Deletes element at specified index, if possible.
//
// Parameters
//     Idx     index of item to be deleted
//
// Returns:   true if deletion is carried out, false otherwise
//
// Pre:      0 <= Idx < Usage
// Post:     If Idx is not valid, no changes.  Otherwise,
//           the Item variable at Idx has been removed.
//
// Calls:    ShiftTailDown()
// Called by: none
//
bool Array::DeleteAtIndex(int Idx) {
    if ( Idx < 0 || Idx >= Usage) return false;

    ShiftTailDown(Idx);
    Usage--;
    return true;
}
```

```
//////////////////////////////////// retrieval functions
//////////////////////////////////// Locate
// Returns index of first occurrence of specified value
// in List.
//
// Parameters
//     Value  value to be located in List[]
//
// Returns:   If Value occurs in List[], index of
//            first occurrence; -1 otherwise.
//
// Pre:      Value has been initialized.
// Post:     no changes.
//
// Calls:    none
// Called by: none
//
int Array::Locate(const Item& Value) const {

    if (Usage == 0) return -1;

    int Idx = 0;
    while (Idx < Usage) {
        if (List[Idx] == Value)
            return Idx;
        Idx++;
    }
    return -1;
}
```

```
////////////////////////////////////// Get
// Returns reference to List[Idx].
//
// Parameters
//     Idx     index of desired Item variable
//
// Returns:   If Idx is valid, reference to List[Idx];
//            -1 otherwise.
//
// Pre:      0 <= Idx < SIZE
// Post:     no changes.
//
// Calls:    none
// Called by: none
//
Item& Array::Get(int Idx) {

    assert (Idx >= 0 && Idx < SIZE);

    return List[Idx];
}

////////////////////////////////////// array property accessors

////////////////////////////////////// getCapacity
// Returns Capacity (dimension) of List
//
// Returns:  number of elements List[] can hold
//
// Pre:     none
// Post:    no changes.
//
// Calls:   none
// Called by: none
//
int Array::getCapacity() const {

    return Capacity;
}
```



```
////////////////////////////////////// getUsage
// Returns Usage (# cells used) of List
//
// Returns:    number of List cells in use
//
// Pre:        none
// Post:       no changes.
//
// Calls:      none
// Called by:  none
//
int Array::getUsage() const {

    return Usage;
}

////////////////////////////////////// isFull
// Indicates whether List is full.
//
// Returns:    true if List is full; false otherwise
//
// Pre:        none
// Post:       no changes.
//
// Calls:      none
// Called by:  none
//
bool Array::isFull() const {

    return (Usage >= Capacity);
}
```

```
////////////////////////////////////// isEmpty
// Indicates whether List is empty.
//
// Returns:   true if List is empty; false otherwise
//
// Pre:      none
// Post:     no changes.
//
// Calls:    none
// Called by: none
//
bool Array::isEmpty() const {

    return (Usage == 0);
}

////////////////////////////////////// destructor

//////////////////////////////////////
// Dummy destructor included for modifiability.
//
Array::~Array() {
}
```