



# **Time and Ordering**

The two critical differences between centralized and distributed systems are:

- absence of shared memory
- absence of a global clock

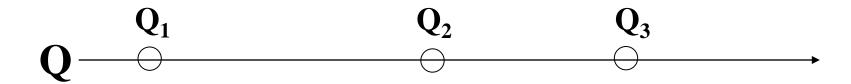
### We will study:

- how programming mechanisms change as a result of these differences
- algorithms that operate in the absence of a global clock
- algorithms that create a sense of a shared, global time
- algorithms that capture a consistent state of a system in the absence of shared memory









How can the events on P be related to the events on Q?

Which events of P "happened before" which events of Q?

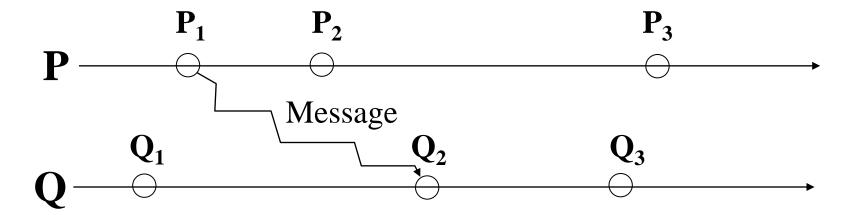
Partial answer: events on P and Q are strictly ordered. So:

$$P_1 --> P_2 --> P_3$$

and

$$Q_1 --> Q_2 --> Q_3$$



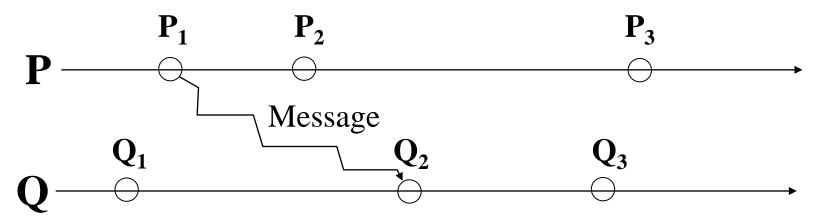


Realization: the only events on P that can causally affect events on Q are those that involve communication between P and Q.

If  $P_1$  is a send event and  $Q_2$  is the corresponding receive event then it must be the case that:

$$P_1 --> Q_2$$





"Happened Before" relation:

If E<sub>i</sub> and E<sub>i</sub> are two events of the same process, then

$$E_{i} --> E_{j} \text{ if } i < j.$$

If E<sub>i</sub> and E<sub>i</sub> are two events of different processes, then

$$E_i \longrightarrow E_i$$

if  $E_i$  is a message send event and  $E_j$  is the corresponding message receive event.

The relation is transitive.



# **Lamport's Algorithm**

Lamport's algorithm is based on two implementation rules that define how each process's local clock is incremented.

### Notation:

- the processes are named P<sub>i</sub>,
- each process has a local clock, C<sub>i</sub>
- the clock time for an event a on process P<sub>i</sub> is denoted by C<sub>i</sub> (a).

### Rule 1:

If a and b are two successive events in  $P_i$  and a --> b then  $C_i$  (b) =  $C_i$  (a) + d where d > 0.

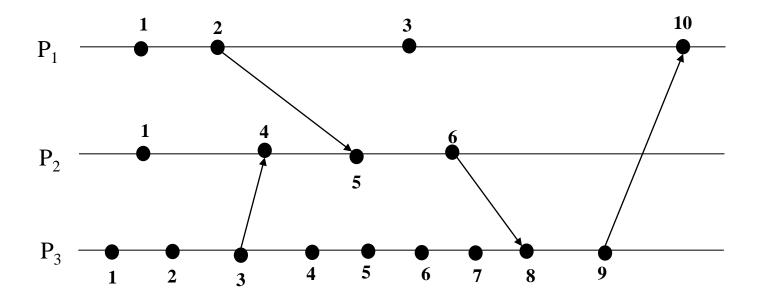
### Rule 2:

If a is a message send event on  $P_i$  and b is the message receive event on  $P_i$  then:

- the message is assigned the timestamp  $t_m = C_i$  (a)
- $C_i(b) = max(C_i, t_m + d)$



# **Example of Lamport's Algorithm**







# **Limitation of Lamport's Algorithm**

In Lamport's algorithm two events that are causally related will be related through their clock times. That is:

If a --> b then 
$$C(a) < C(b)$$

However, the clock times alone do not reveal which events are causally related. That is, if C(a) < C(b) then it is not known if a --> b or not. All that is known is:

if 
$$C(a) < C(b)$$
 then  $b - / - > a$ 

It would be useful to have a stronger property - one that guarantees that

a --> b iff 
$$C(a) < C(b)$$

This property is guaranteed by Vector Clocks.



### **Vector Clock Rules**

Each process  $P_i$  is equipped with a clock  $C_i$  which is an integer vector of length n.

 $C_i(a)$  is referred to as the timestamp event a at  $P_i$ 

 $C_i[i]$ , the *i*th entry of  $C_i$  corresponds to  $P_i$ 's on logical time.

 $C_i[j]$ ,  $j \neq i$  is  $P_i$ 's best guess of the logical time at  $P_i$ 

### Implementation rules for vector clocks:

[IR1] Clock  $C_i$  is incremented between any two successive events in process  $P_i$ 

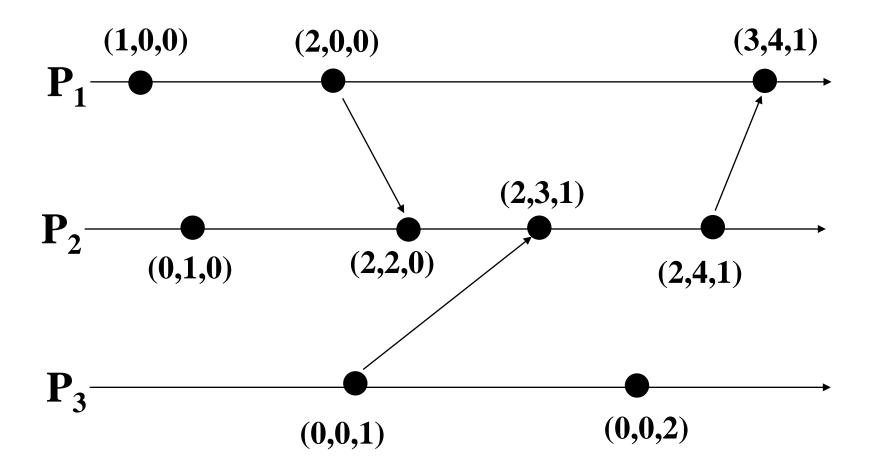
$$C_i[i] := C_i[i] + d \qquad (d > 0)$$

**[IR2]** If event a is the sending of the message m by process  $P_i$ , then message m is assigned a vector timestamp  $t_m = C_i(a)$ ; on receiving the same message m by process  $P_j$ ,  $C_j$  is updated as follows:

$$\forall k, C_j[k] := \max(C_j[k], t_m[k])$$

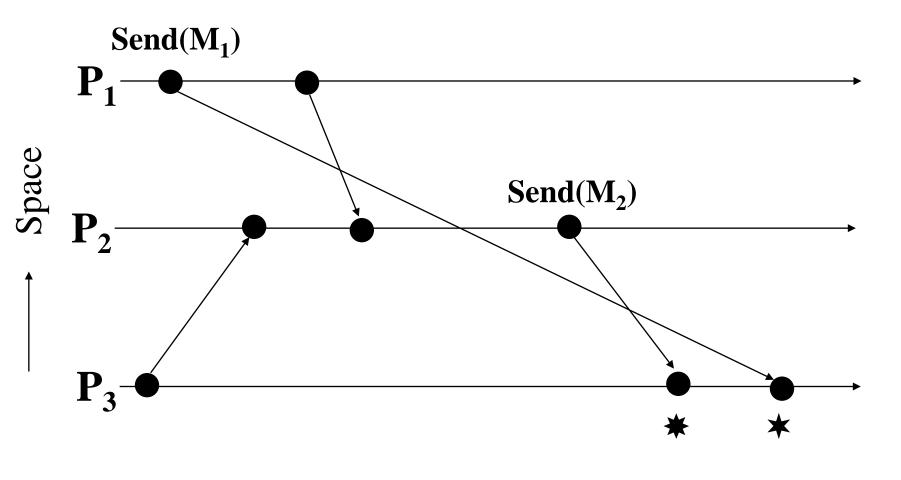


### **Vector Clocks**





# **Causal Ordering of Messages**









# **Birman-Schiper-Stephenson Protocol**

- 1. Before broadcasting a message m, a process  $P_i$  increments the vector time  $VT_{Pi}[i]$  and timestamps m. Note that  $(VT_{Pi}[i] 1)$  indicates how many messages from  $P_i$  precede m.
- 2. A process  $P_j \neq P_i$ , upon receiving message m timestamped  $VT_m$  from  $P_i$ , delays its delivery until both the following conditions are satisfied.

a. 
$$VT_{Pi}[i] = VT_{m}[i] - 1$$

b. 
$$VT_{Pi}[k] \ge VT_m[k] \ \forall k \in \{1,2,...,n\} - \{i\}$$

where n is the total number of processes.

Delayed messages are queued at each process in a queue that is sorted by vector time of the messages. Concurrent messages are ordered by the time of their receipt.

3. When a message is delivered at a process  $P_j$ ,  $VT_{Pj}$  is updated according to the vector clocks rule [IR2]