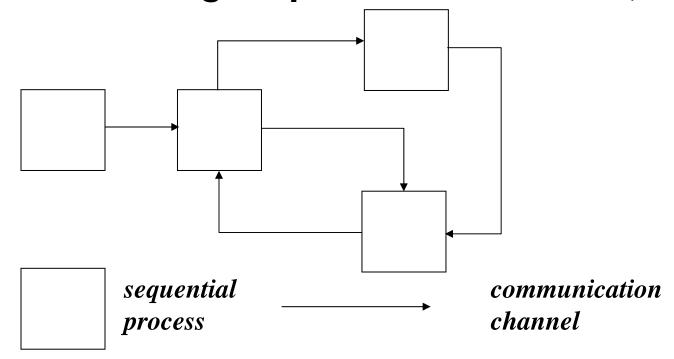




# **Communicating Sequential Processes (CSP)**



- single thread of control
- autonomous
- encapsulated
- named
- static

- synchronous
- reliable
- unidirectional
- point-to-point
- fixed topology



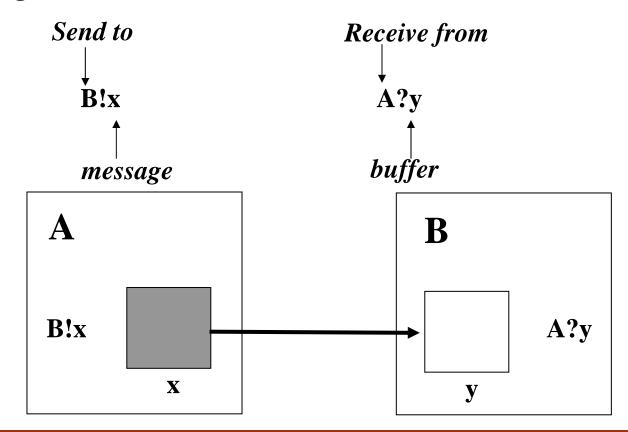


# **Operators**

operators: ! (send)

? (receive)

### usage:

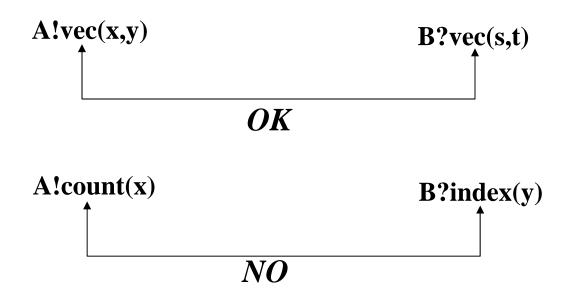






## **Semantics and Type Matching**

- rendezvous semantics: senders (receivers) remain blocked at send (receive) operation until a matching receive (send) operation is made.
- typed messages: the type of the message sent by the sender and the type of the message expected by the receiver must match (otherwise abort).

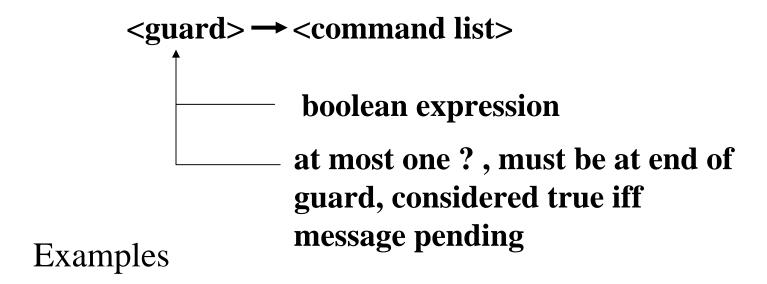






### **Guarded Commands**

**Guarded Commands** 



$$n < 10 \rightarrow A!index(n); n := n + 1;$$
  
 $n < 10; A?index(n) \rightarrow next = MyArray(n);$ 





## **Alternative/Repetitive Commands**

### Alternative Command

$$[G_1 \rightarrow S_1 [G_2 \rightarrow S_2 [G... G_n \rightarrow S_n]]$$

- 1. evaluate all guards
- 2. if more than on guard is true, nondeterministically select one.
- 3. if no guard is true, terminate.

**Note:** if all true guards end with an input command for which there is no pending message, then delay the evaluation until a message arrives. If all senders have terminated, then the alternative command terminates.

## Repetitive Command

\* 
$$[G_1 \rightarrow S_1 [G_2 \rightarrow S_2 [G_n \rightarrow S_n]]$$

repeatedly execute the alternative command until it terminates





### **Examples**

### Examples:

$$[x >= y --> m := x [] y >= x --> m := y ]$$

assign x to m if x is greater than or equal to y assign y to m if y is greater than or equal to x assign either x or y to m if x equals y

```
* [ c: character; west?c --> east!c ]
```

Transmit to the process named <u>east</u> a character received from the process named <u>west</u> until the process named <u>west</u> terminates.





### **Examples**

#### SEARCH

```
i := 0; * [ i < size; content(i) != n --> i := i + 1 ]
```

Scan the array context until the value n is found or until the end of the array of length size is reached

LISTMAN has a simple protocol defined by two messages - an <u>insert</u> message and a <u>has</u> message. The types <u>insert</u> and <u>has</u> are used to disambiguate the integer value passed on each communication with X. INSERT is code (not shown) that adds the value of n to the array content. SEARCH is the code shown above. LISTMAN replies with a boolean value to each has message.





# **Signals between Processes**

A message bearing a type but no data may be used to convey a "signal" between processes. For example:

```
Semaphore::
   val:integer; val = 0;
   *[ X?V()--> val = val + 1
   []
      val > 0; Y?P()--> val = val - 1
```





### **Bounded Buffer Example**

Implements a bounded buffer process using the array buffer to hold up to a maximum of 10 values of type portion. Note how the guarded commands do not accept <u>producer</u> messages when the buffer is full and do not accept <u>consumer</u> messages when the buffer is empty.





### **Example**

```
lineimage:(1...125) character;
 i: integer; i:=1;
 * [ c:character; X?c -->
        lineimage(i);+ c;
        「 i <= 124 --> i := i+1;
         i = 125 --> lineprinter!lineimage; i:=1;
    [ I = 1 --> skip ]
      i>1 --> *[i <= 125 --> lineimage(i):= space; i:= i+1;]
              lineprinter!lineimage
Read a stream of characters from X and print them in lines of 125
characters on a lineprinter completing thelast line with spaces if
```



necessary.



### **Arrays of Processes**

```
X(i: 1..100):: [...process definition...]
```

declares an array of processes all with the same code but with different names (e.g., X(1), X(2), ..., X(100))

Communication among processes in the array is facilitated by the use of input/output commands as illustrated in this code fragment:

where the bound variable  $\underline{i}$  is used to identify the communicating partner process





## **CSP - Comparison with Monitors**

### **Guarded Commands**

- Monitor: begin executing every call as soon as possible, waiting if the object is not in a proper state and signaling when the state is proper
- CSP: the called object establishes conditions under which the call is accepted; calls not satisfying these conditions are held pending (no need for programmed wait/signal operations).

### Rendezvous

- Monitor: the monitor is passive (has no independent task/thread/activity)
- CSP: synchronization between peer, autonomous activities.





### Comparison

### Distribution:

- Monitor: inherently non-distributed in outlook and implementation
- CSP: possibility for distributed programming using synchronous message passing

