# Types of Machine Learning and Model Selection

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# 1st Learning Setting

- Draw data set  $D = \{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$  from distribution  $\mathbb{D}$
- Algorithm A learns hypothesis  $h \in H$  from set H of possible hypotheses A(D) = h
- We measure the quality of h as the expected loss:  $E_{(x,y)\in\mathbb{D}}[\ell(y,h(x))]$ 
  - This quantity is known as the risk
  - E.g., loss could be the Hamming loss  $\ell_{\text{Hamming}}(a, b) = \begin{cases} 0 & \text{if } a = b \\ 1 & \text{otherwise} \end{cases}$

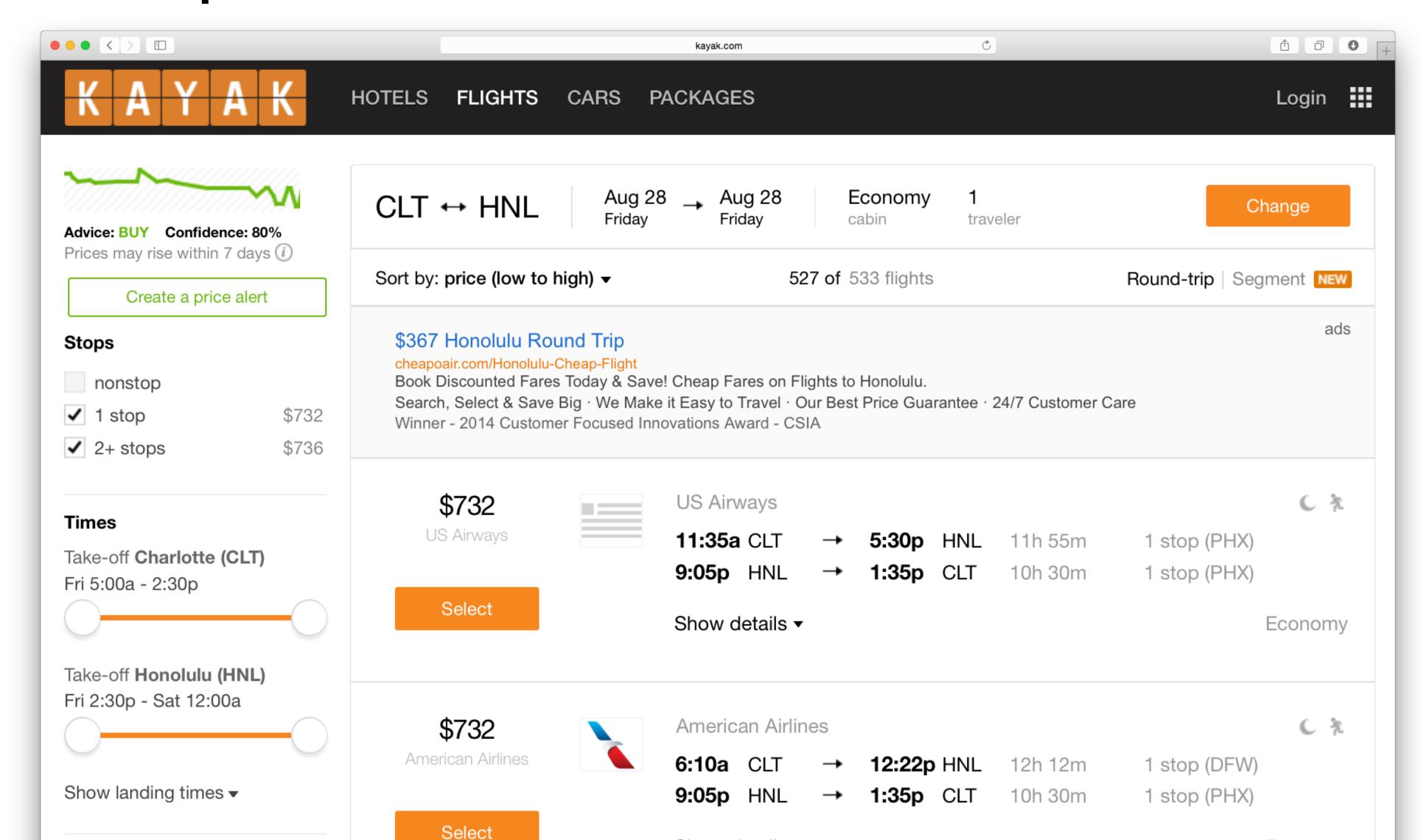
# Example: Digit Classification



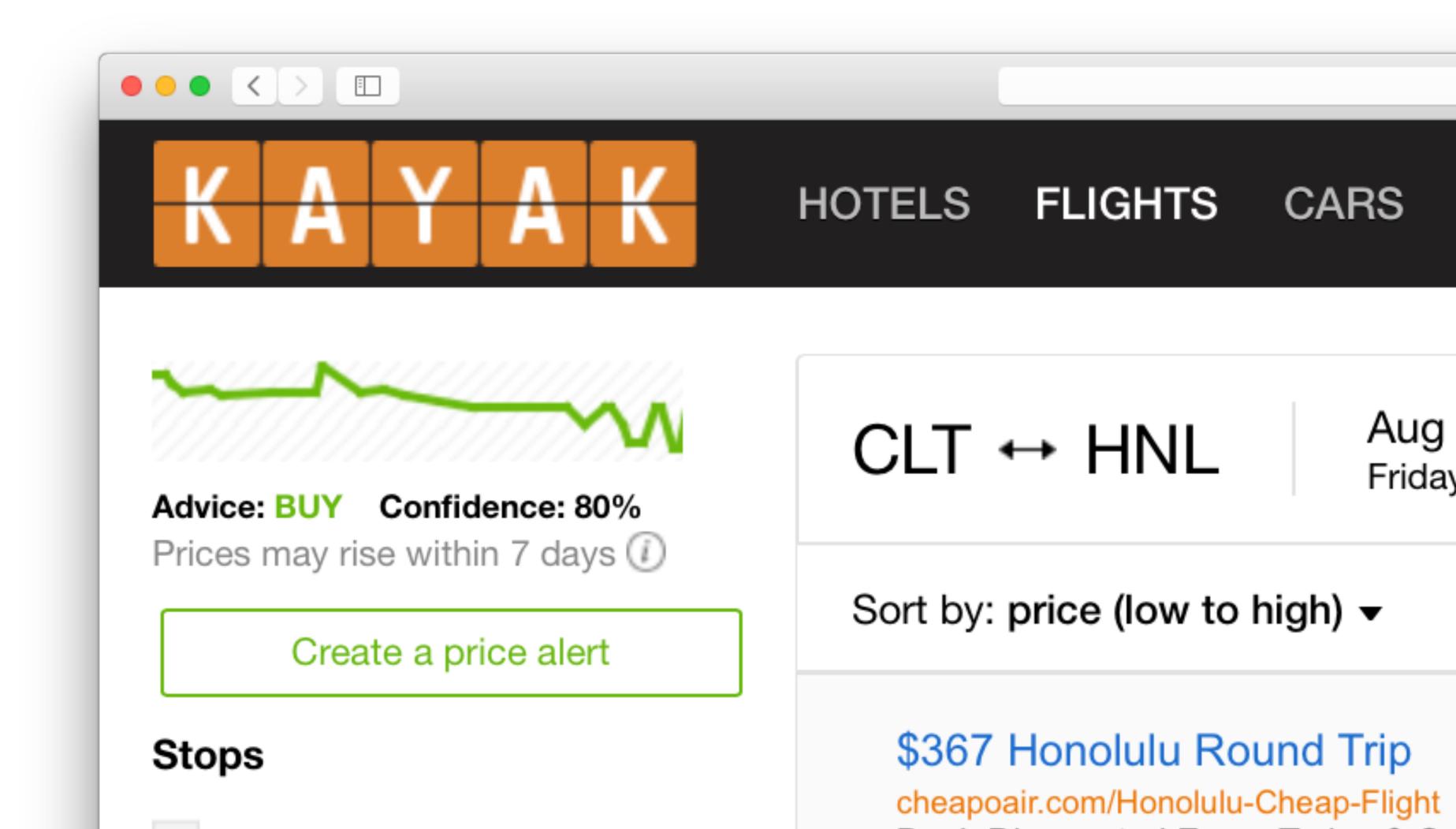


http://ufldl.stanford.edu/housenumbers/

# Example: Airline Price Prediction



# Example: Airline Price Prediction



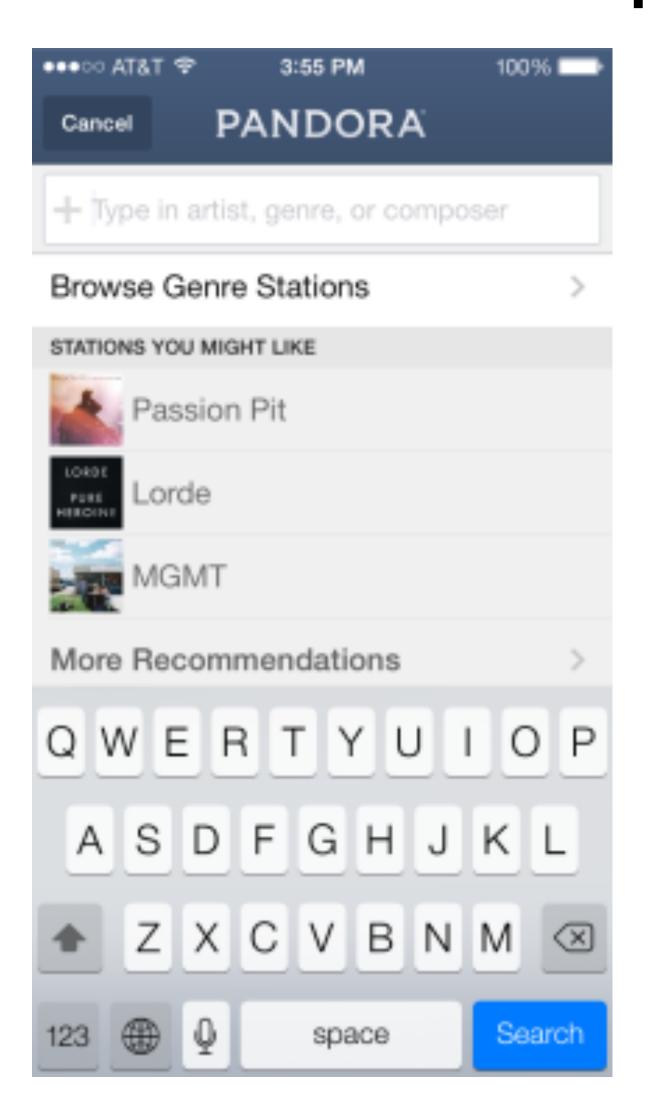
# Batch Supervised Learning

- Draw data set  $D = \{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$  from distribution  $\mathbb{D}$
- Algorithm A learns hypothesis  $h \in H$  from set H of possible hypotheses A(D) = h
- We measure the quality of h as the expected **loss**:  $E_{(x,y)\in\mathbb{D}}[\ell(y,h(x))]$ 
  - This quantity is known as the **risk**
  - E.g., loss could be the Hamming loss  $\ell_{\text{Hamming}}(a, b) = \begin{cases} 0 & \text{if } a = b \\ 1 & \text{otherwise} \end{cases}$  classification

# Online Supervised Learning

- In step *t*, draw data point *x* from distribution
- Current hypothesis *h* guesses the label of *x*
- Get true label from oracle O
- Pay penalty if h(x) is wrong (or earn reward if correct)
- Learning algorithm updates to new hypothesis based on this experience
  - Does not store history

# Example: Recommendation





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# Learning Settings

- Supervised or unsupervised (or semi-supervised, weakly supervised, transductive...)
- Online or batch (or reinforcement...)
- Classification, regression
  - (or structured output, clustering, dimensionality reduction...)
- Parametric or non-parameteric

# Functional Perspective

Input	Learning Setting
Batch of Data Points with Labels	Batch Supervised Learning
Batch of Data Points	Batch Unsupervised Learning
Data Point(s) and Previous Model	Online Supervised Learning

# Concepts

- Supervised and unsupervised learning
- Online and batch learning
- Discriminative and generative
- Output of models: classification and regression

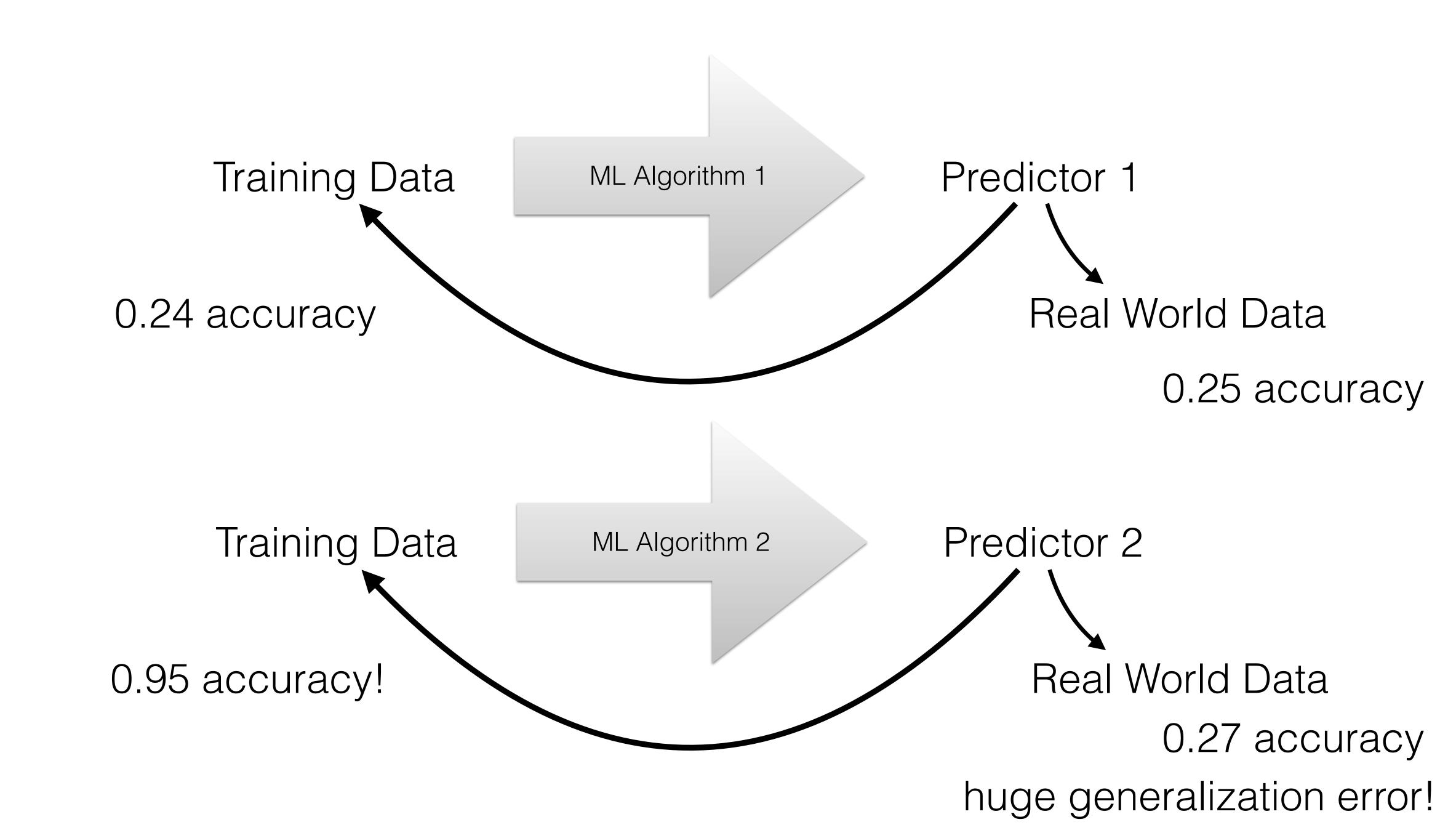
# Model Selection

# Outline

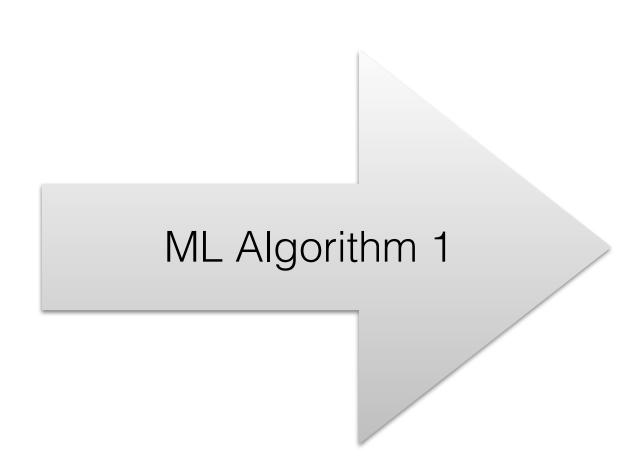
- Overfitting and underfitting
- Bias and variance
- Validation for model selection

# Outline

- Overfitting and underfitting
- Bias and variance
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#### Underfitting



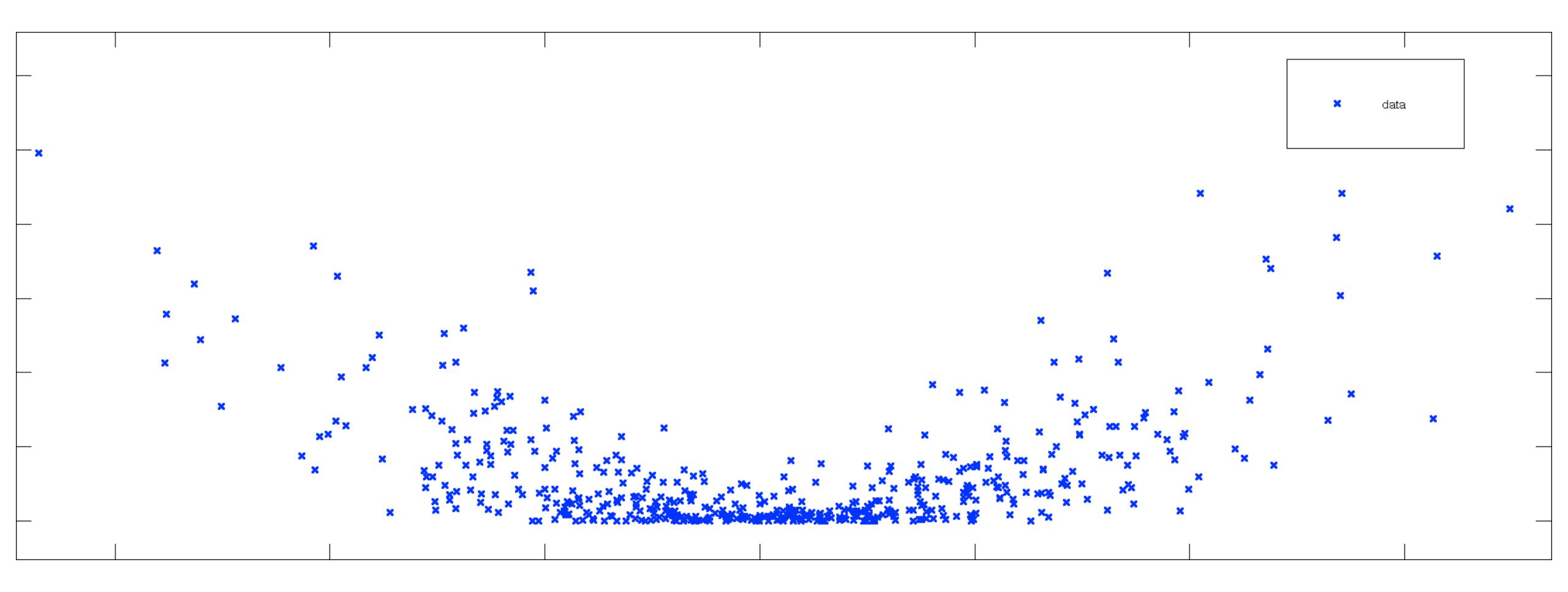
ML Algorithm 2

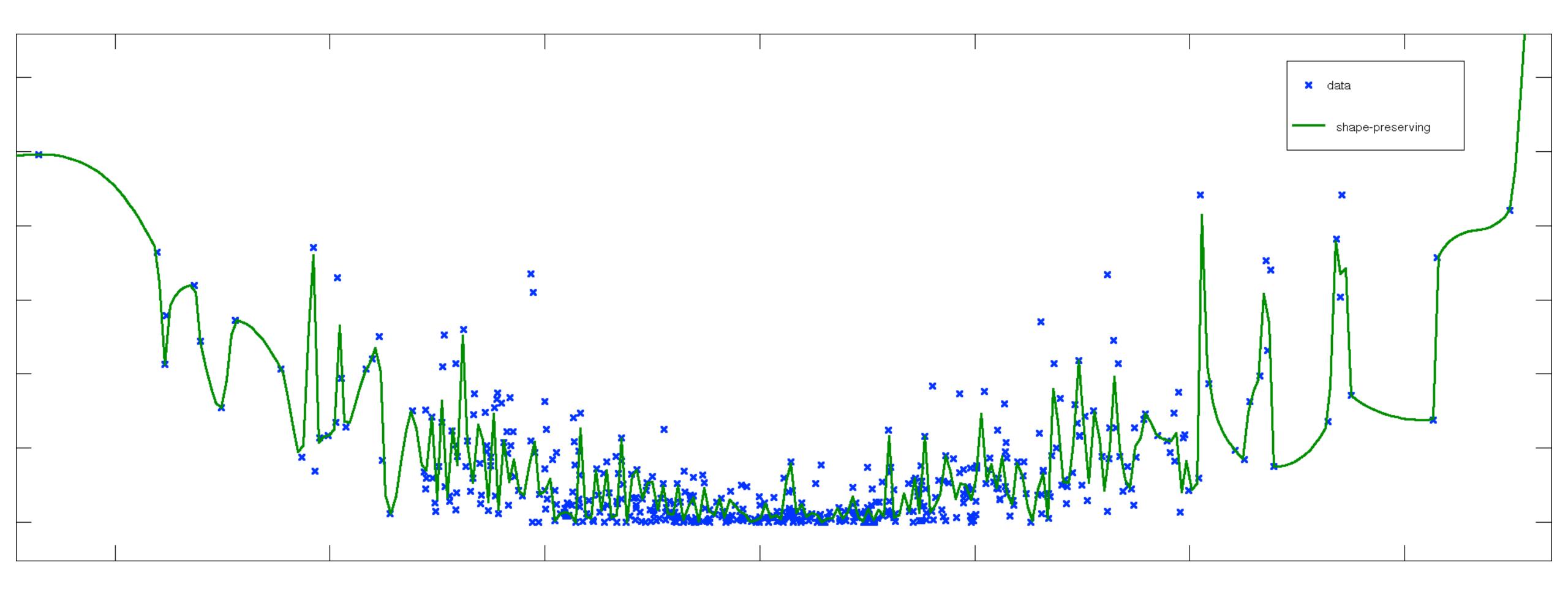
- Low dimensional
- Heavily regularized
- Bad modeling assumptions

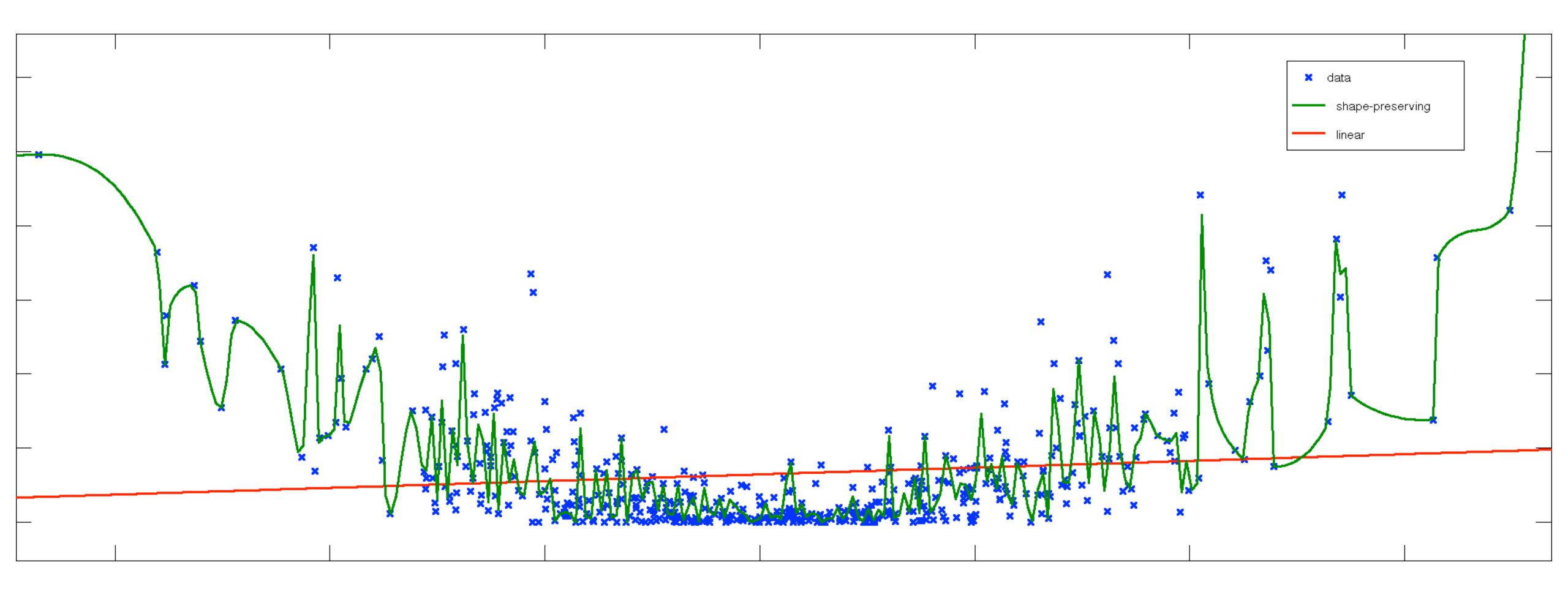
- High dimensional or non-parametric
- Weakly regularized

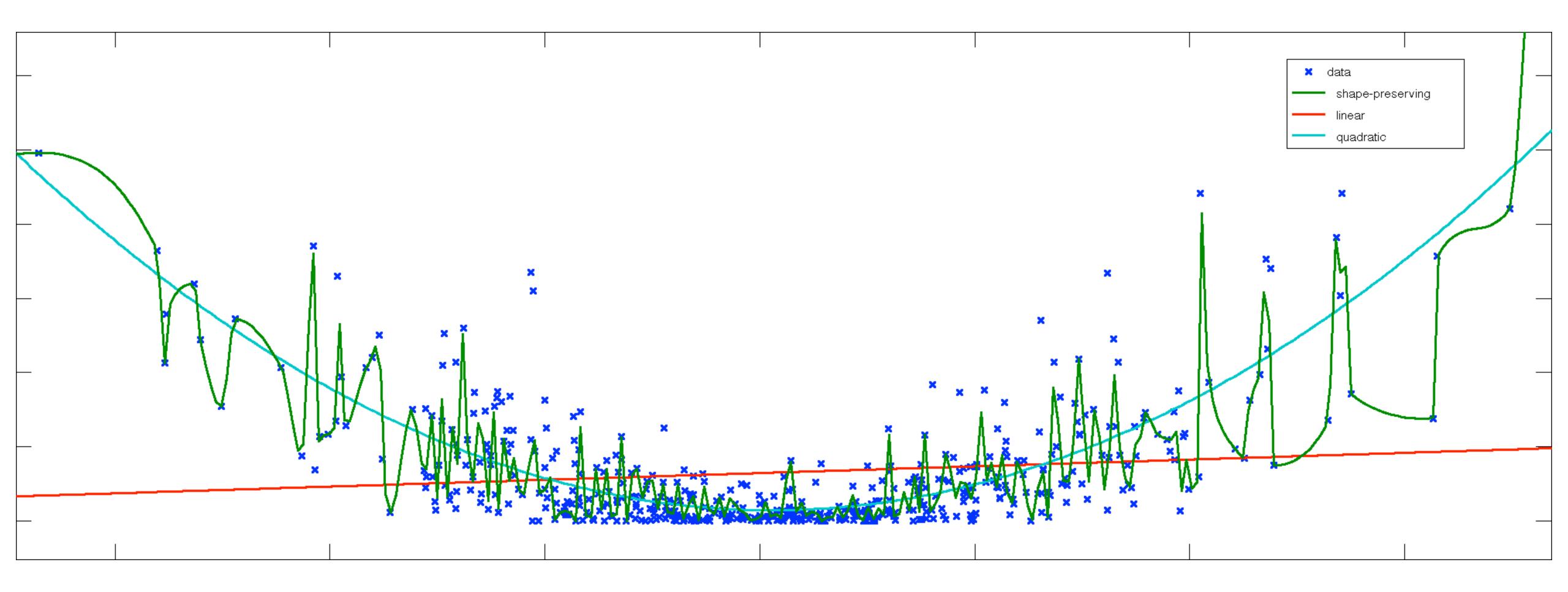
Overfitting

- Not enough modeling assumptions
- Not enough data









# Overfitting and Underfitting

- Training models too complex can cause overfitting
- Training models too simple (or wrong) can cause underfitting

# Outline

- Overfitting and underfitting
- Bias and variance
- Validation for model selection

#### Bias and Variance

- Both contribute to error
- Bias: error from incorrect modeling assumptions
- Variance: error from random noise

http://scott.fortmann-roe.com/docs/BiasVariance.html

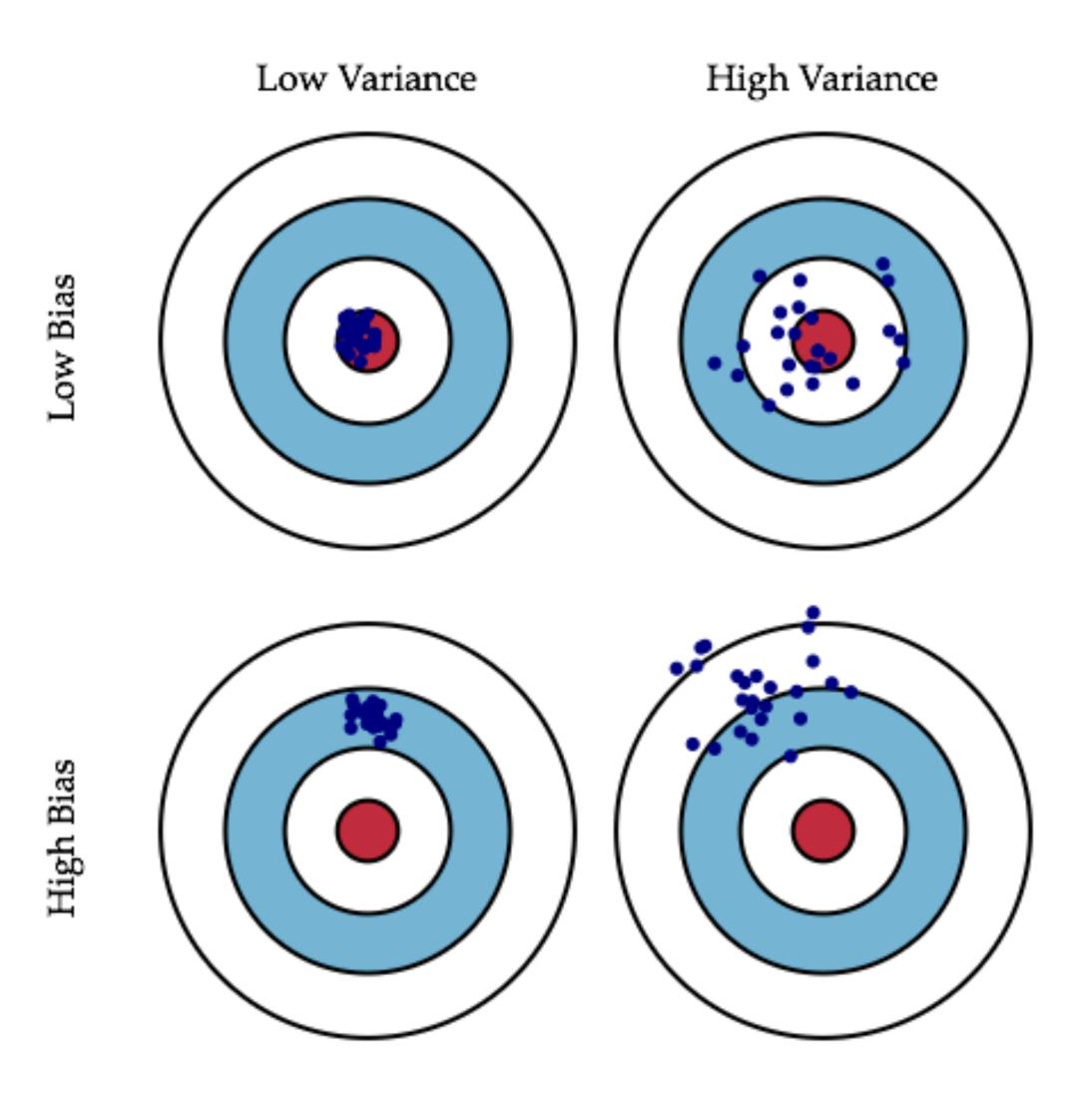


Fig. 1 Graphical illustration of bias and variance.

#### Mathematical Definition

after Hastie, et al.  $2009 \frac{1}{2}$ 

If we denote the variable we are trying to predict as Y and our covariates as X, we may assume that there is a relationship relating one to the other such as  $Y = f(X) + \epsilon$  where the error term  $\epsilon$  is normally distributed with a mean of zero like so  $\epsilon \sim \mathcal{N}(0, \sigma_{\epsilon})$ .

We may estimate a model f(X) of f(X) using linear regressions or another modeling technique. In this case, the expected squared prediction error at a point x is:

$$Err(x) = E\left[ (Y - \hat{f}(x))^2 \right]$$

This error may then be decomposed into bias and variance components:

$$Err(x) = \left(E[f(\hat{x})] - f(x)\right)^2 + E\left[\left(f(\hat{x}) - E[f(\hat{x})]\right)^2\right] + \sigma_e^2$$

$$Err(x) = Bias^2 + Variance + Irreducible Error$$

That third term, irreducible error, is the noise term in the true relationship that cannot fundamentally be reduced by any model. Given the true model and infinite data to calibrate it, we should be able to reduce both the bias and variance terms to 0. However, in a world with imperfect models and finite data, there is a tradeoff between minimizing the bias and minimizing the variance.

$$Err(x) = E\left[ (Y - f(x))^2 \right]$$

be decomposed into bias and variance components:

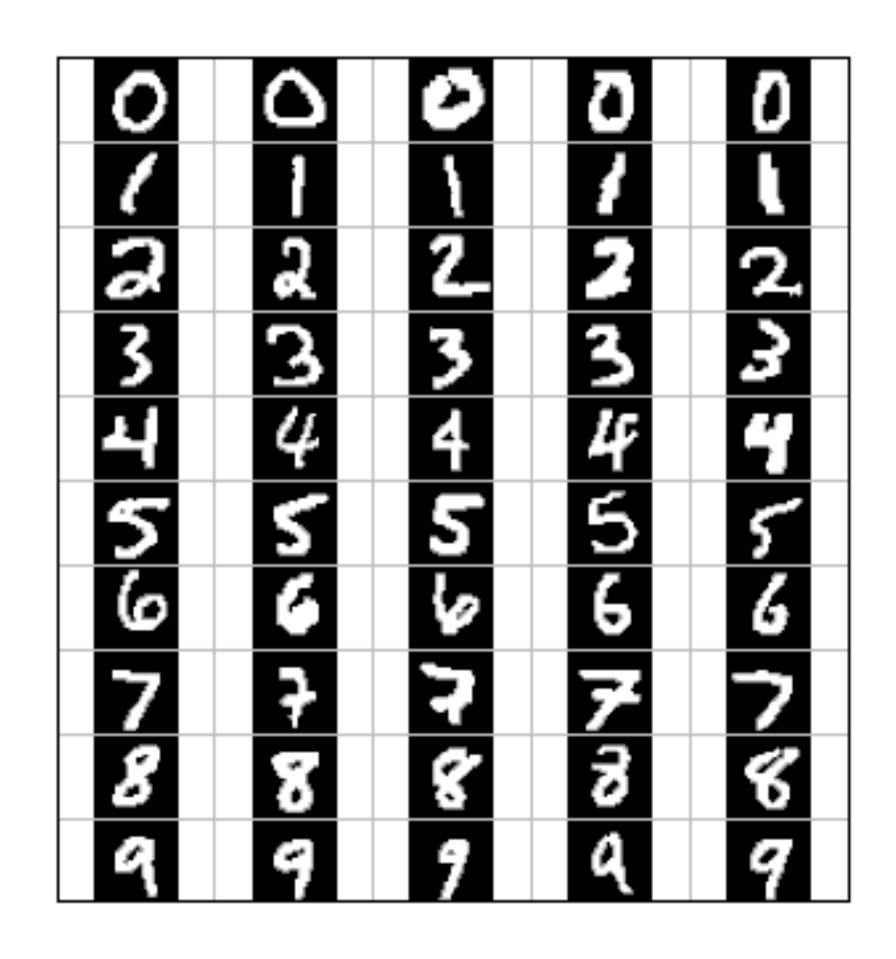
$$Err(x) = \left(E[f(x)] - f(x)\right)^2 + E\left[\left(f(x) - E[f(x)]\right)^2\right] + \sigma_e^2$$
expected true function learned expected function
$$Err(x) = Bias^2 + Variance + Irreducible Error$$

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# Outline

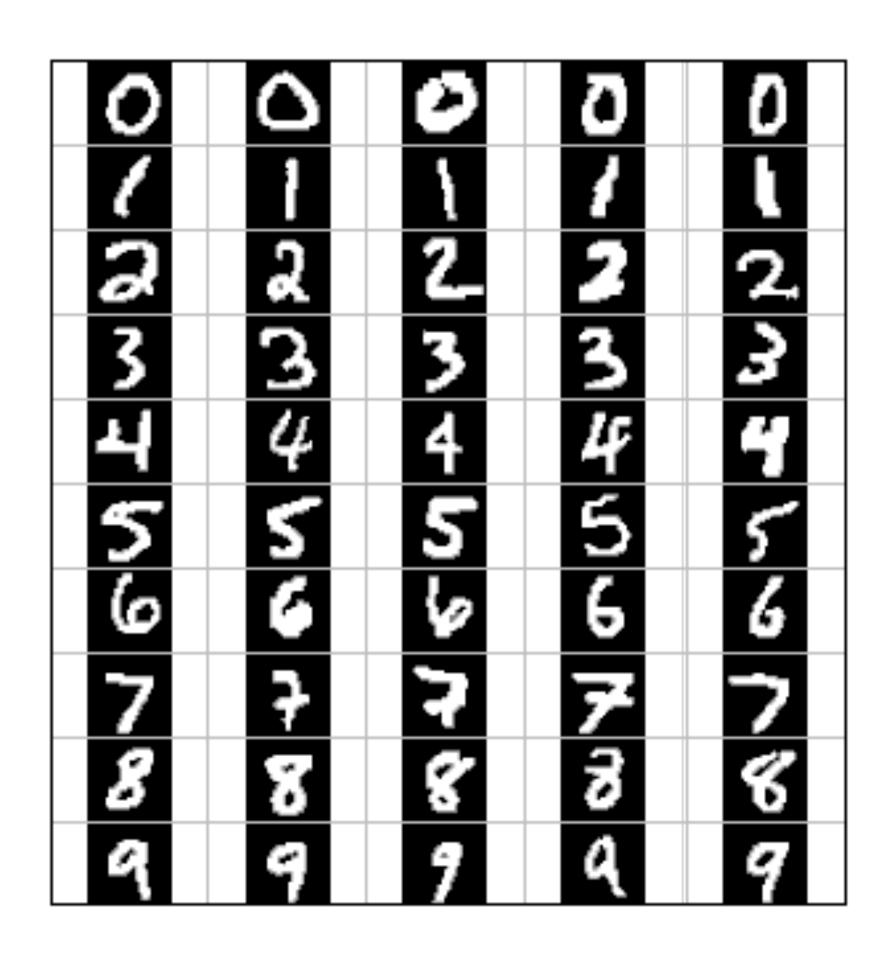
- Overfitting and underfitting
- Bias and variance
- Validation for model selection

# Nearest-Neighbor Classifiers



```
classifier = {
           O: 0,
                     100% training accuracy!
           \( \): 0,
          ②:0,
          a: 0,
          () : 0,
                    53% testing accuracy...
```

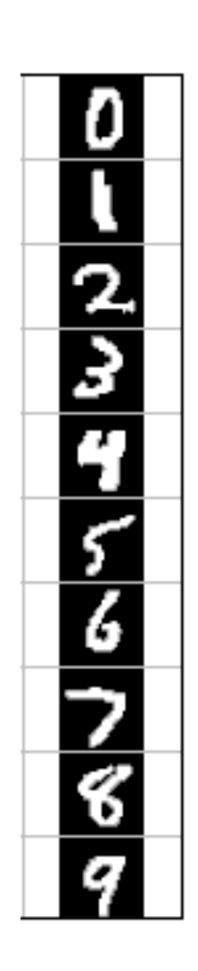
## Held-out Validation



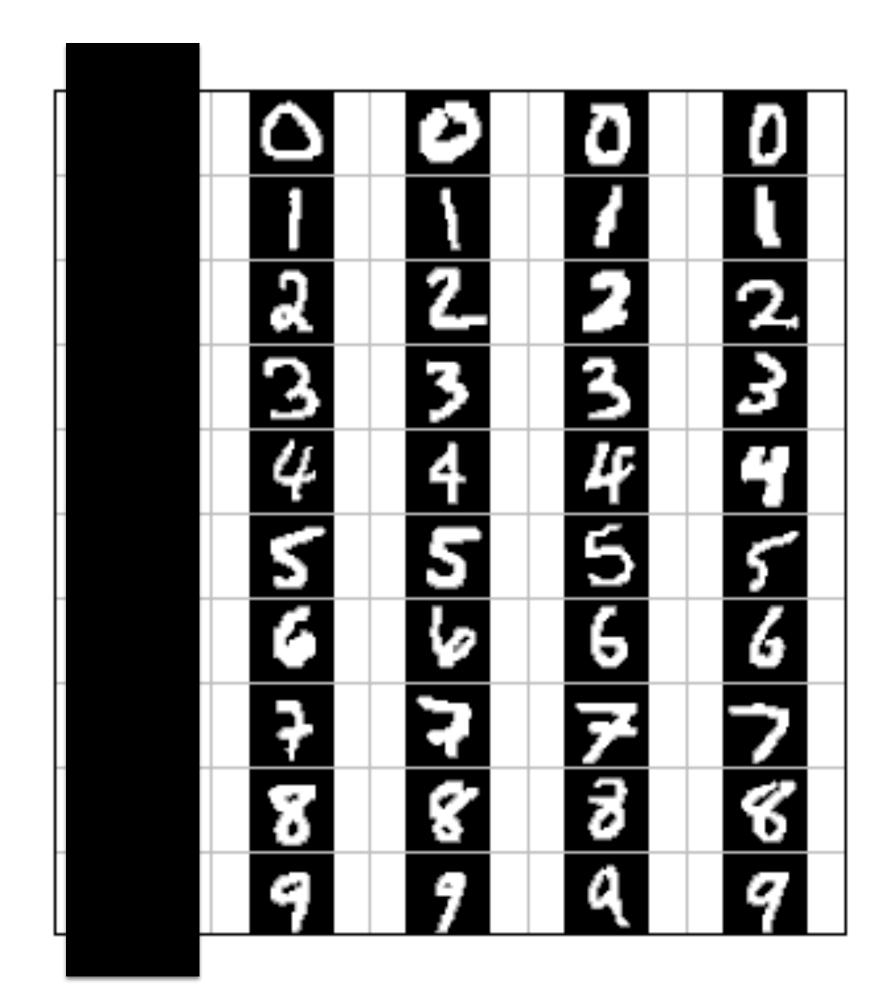
## Held-out Validation

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4	4	4	4
5	5	5	5
6	6	6	6
7	7	7	7
8	8	8	3
9	9	9	٩

	Accuracy on training data	Accuracy on validation data
Simple	0.91	0.83
Medium	0.95	0.88
Complex	0.99	0.79
Super Complex	1.0	0.54



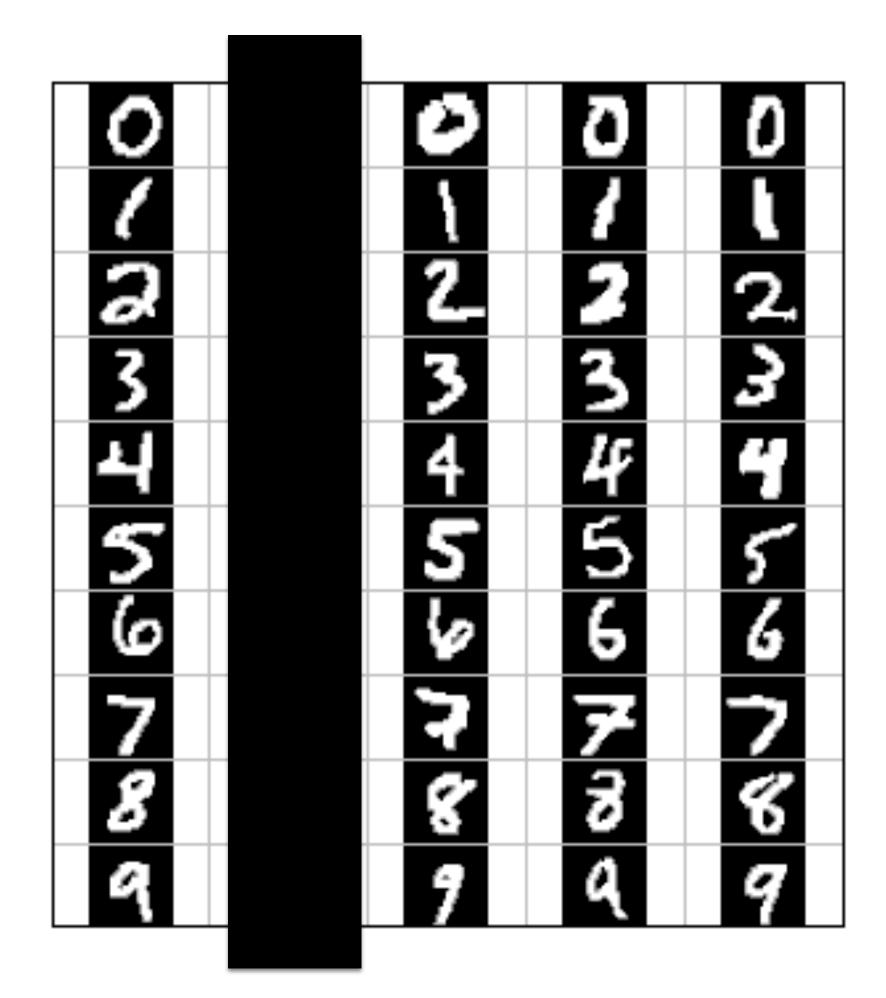
Fold 1



training data



Fold 2

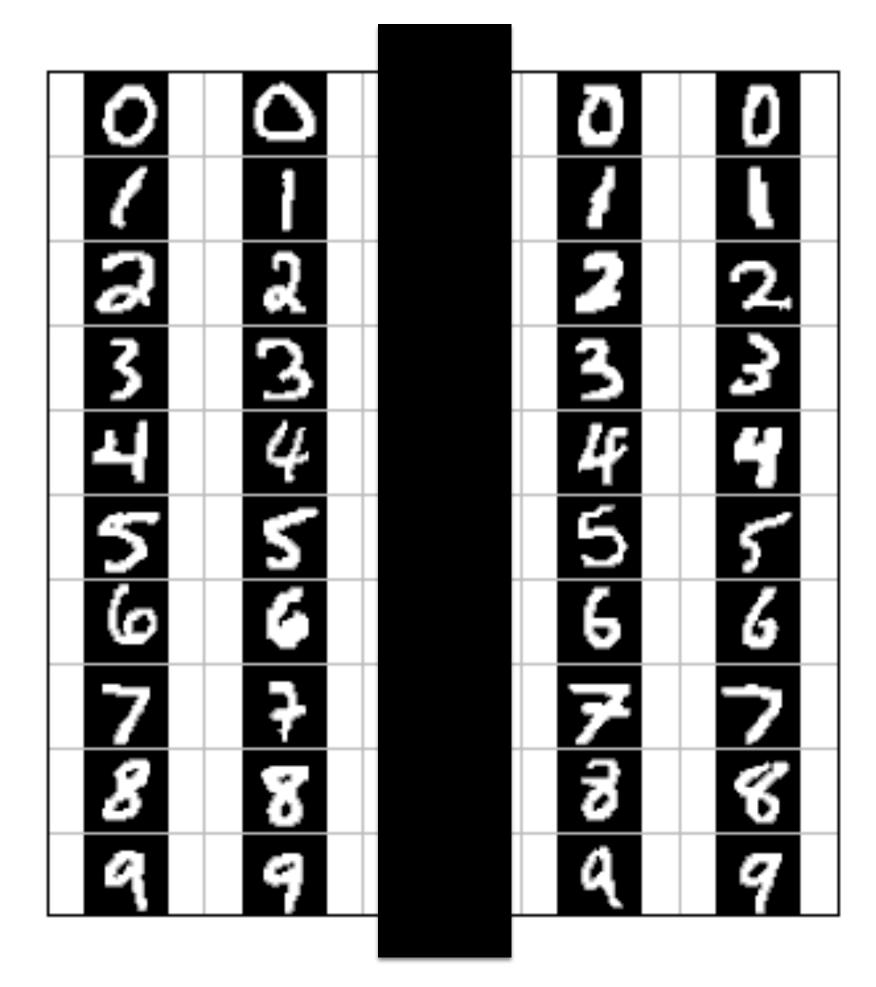


training data



validation data

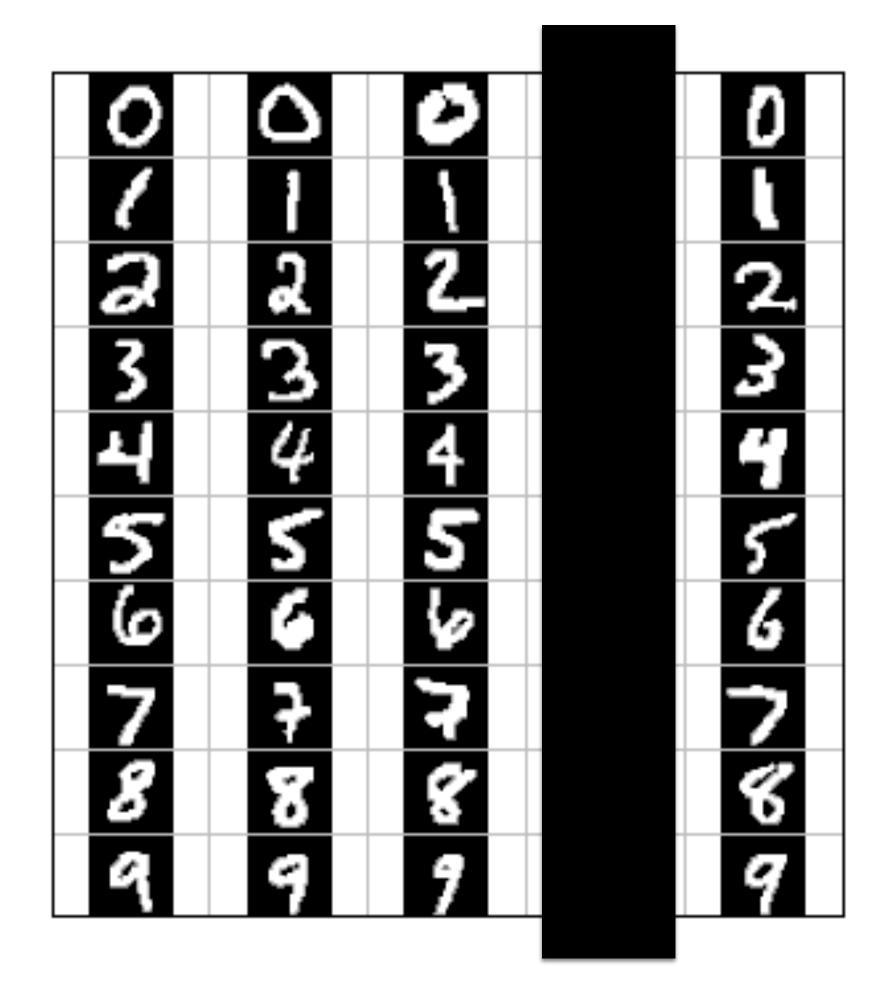
Fold 3



training data



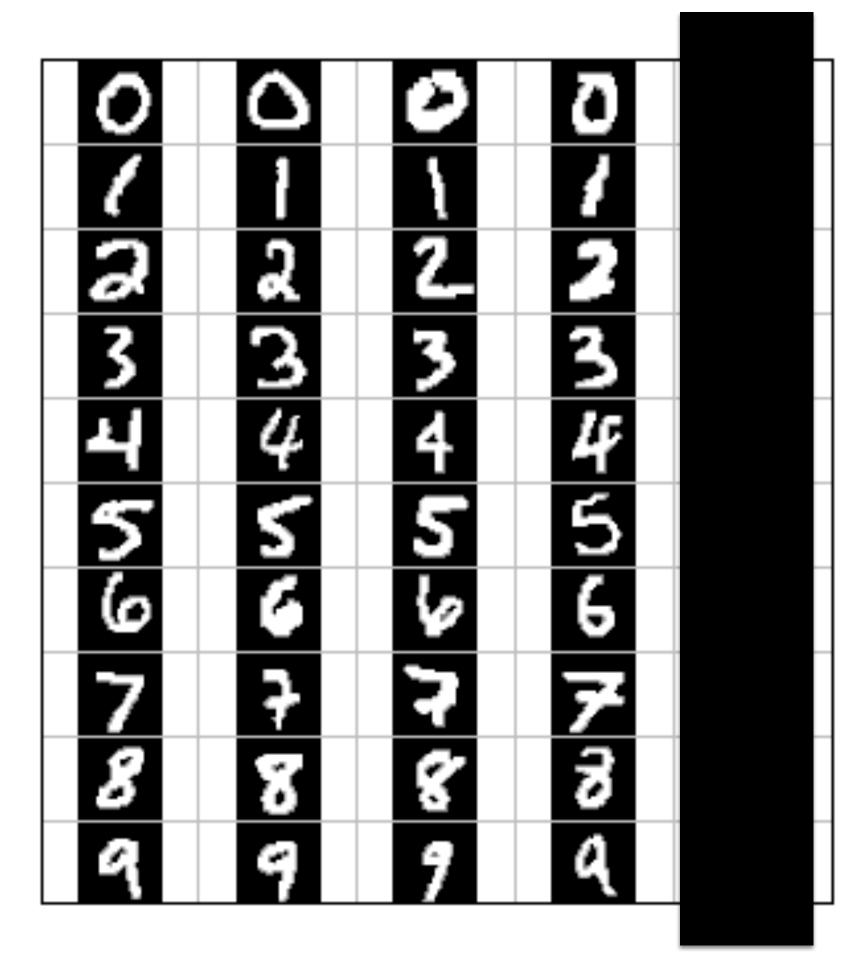
Fold 4



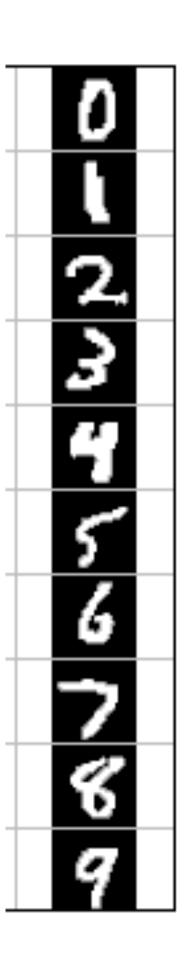
training data

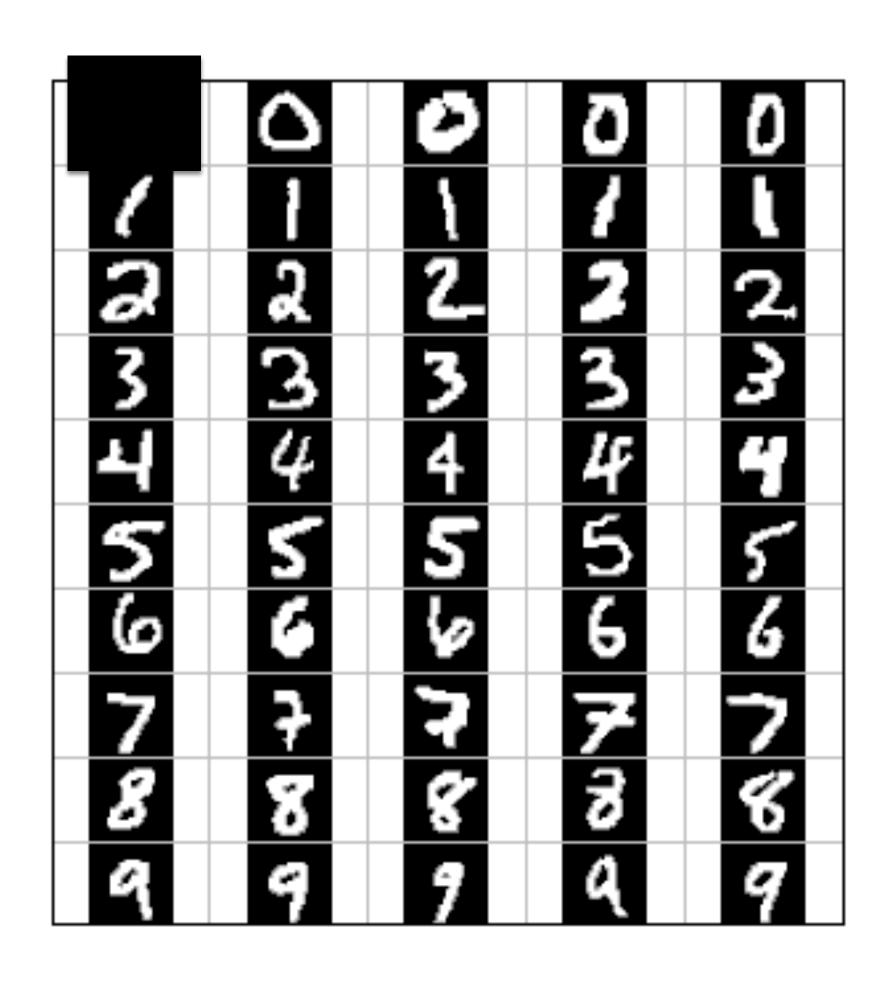


Fold 5



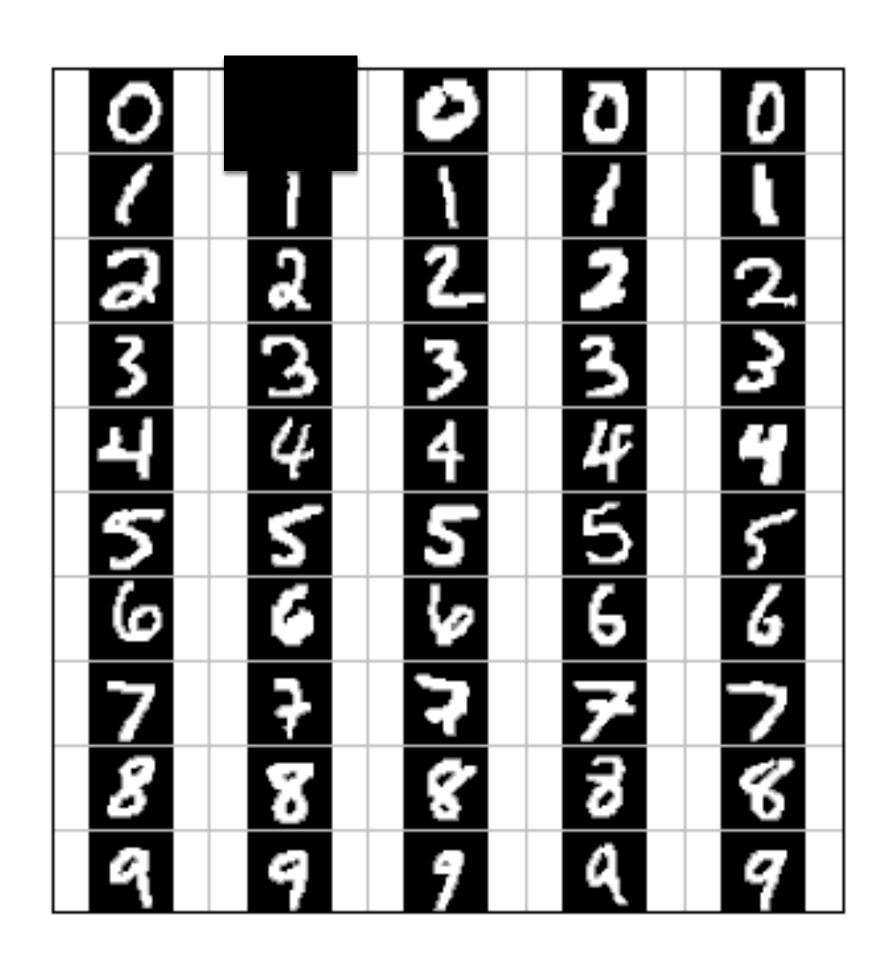
training data





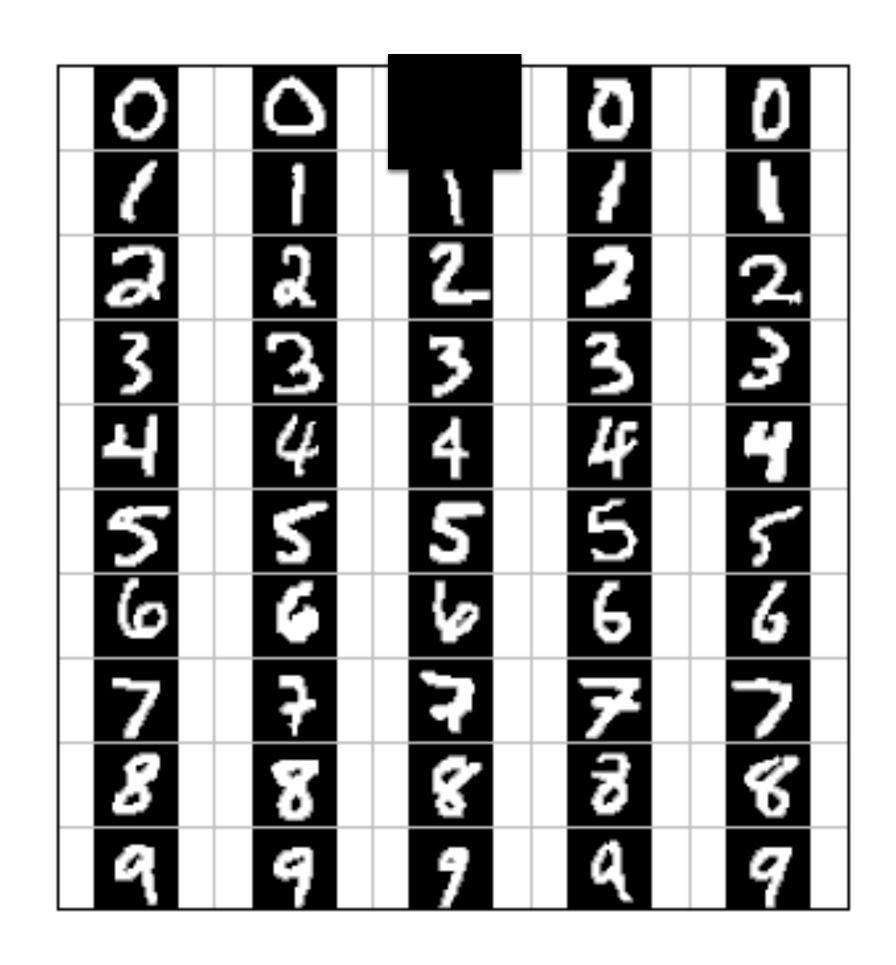


training data



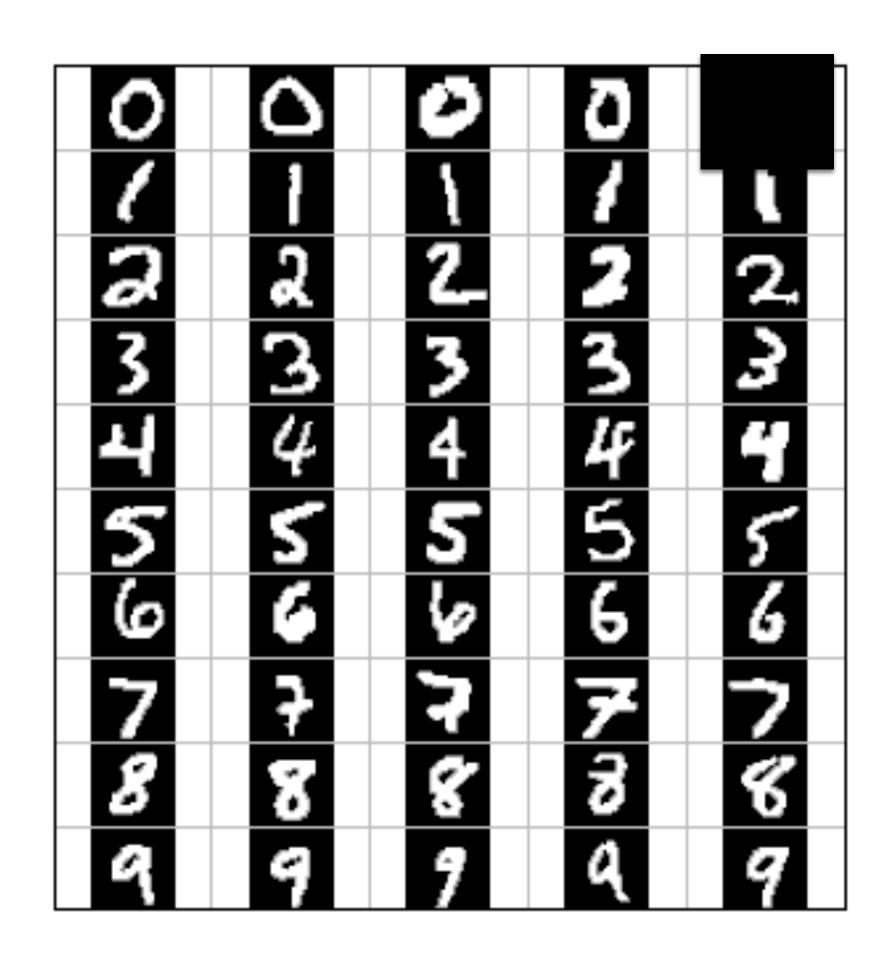


training data



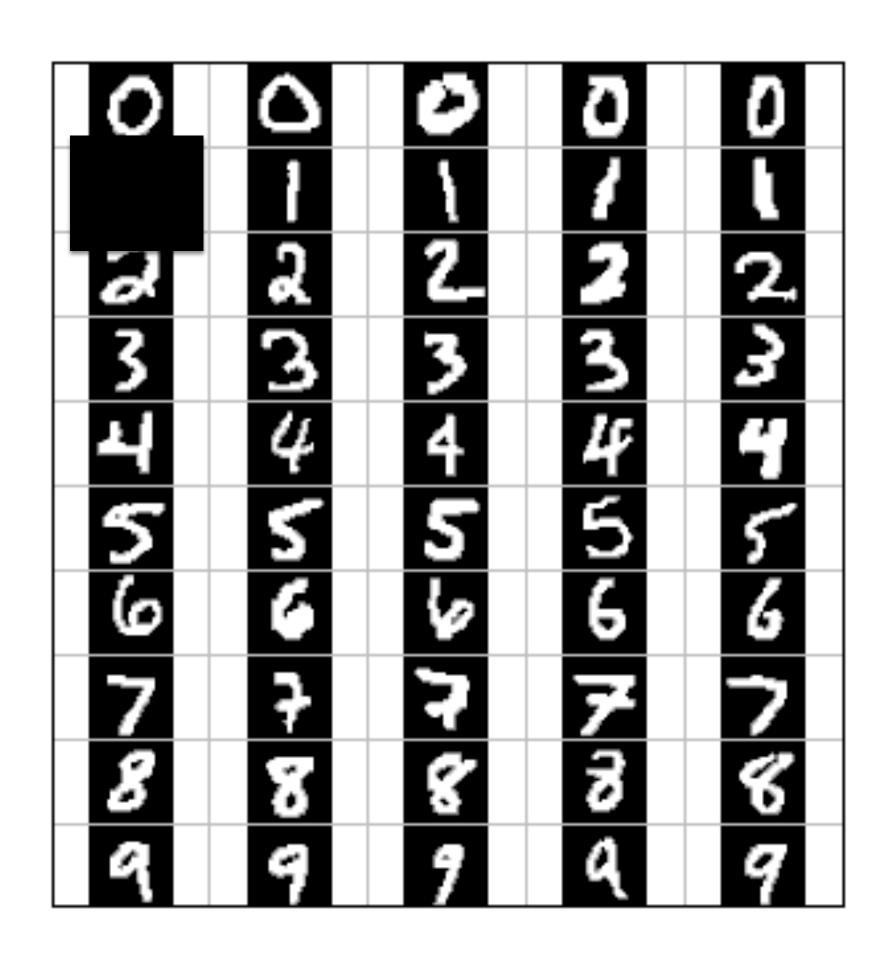


training data



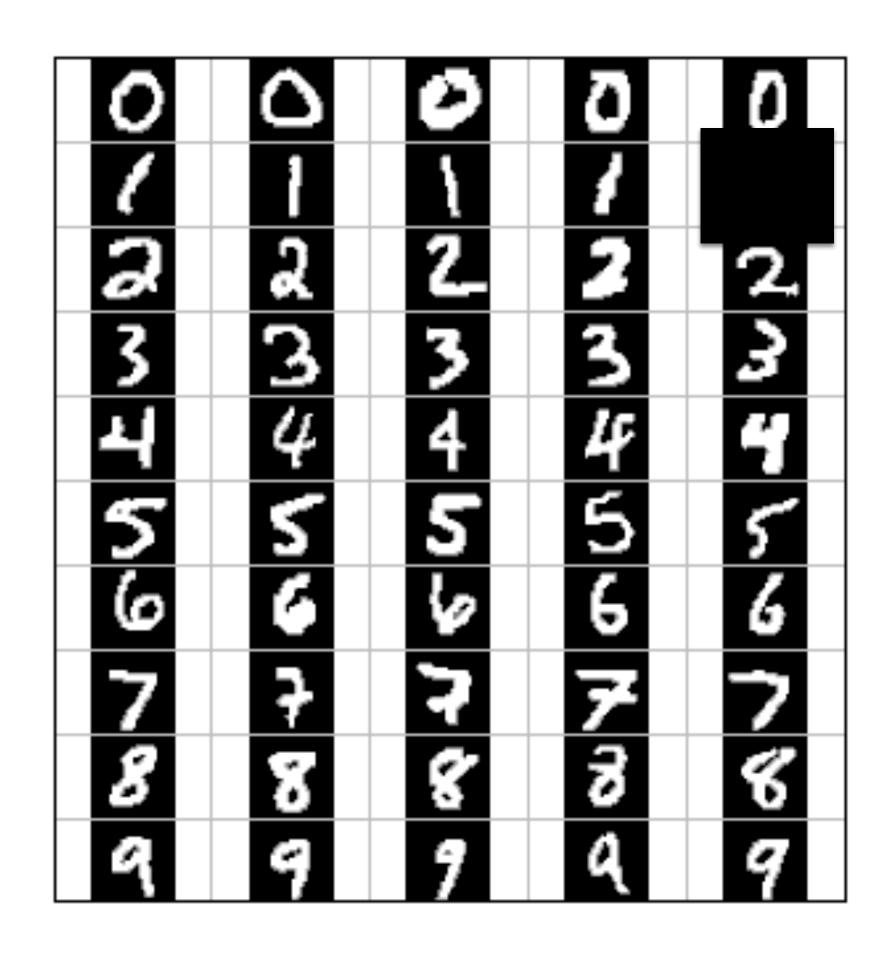


training data



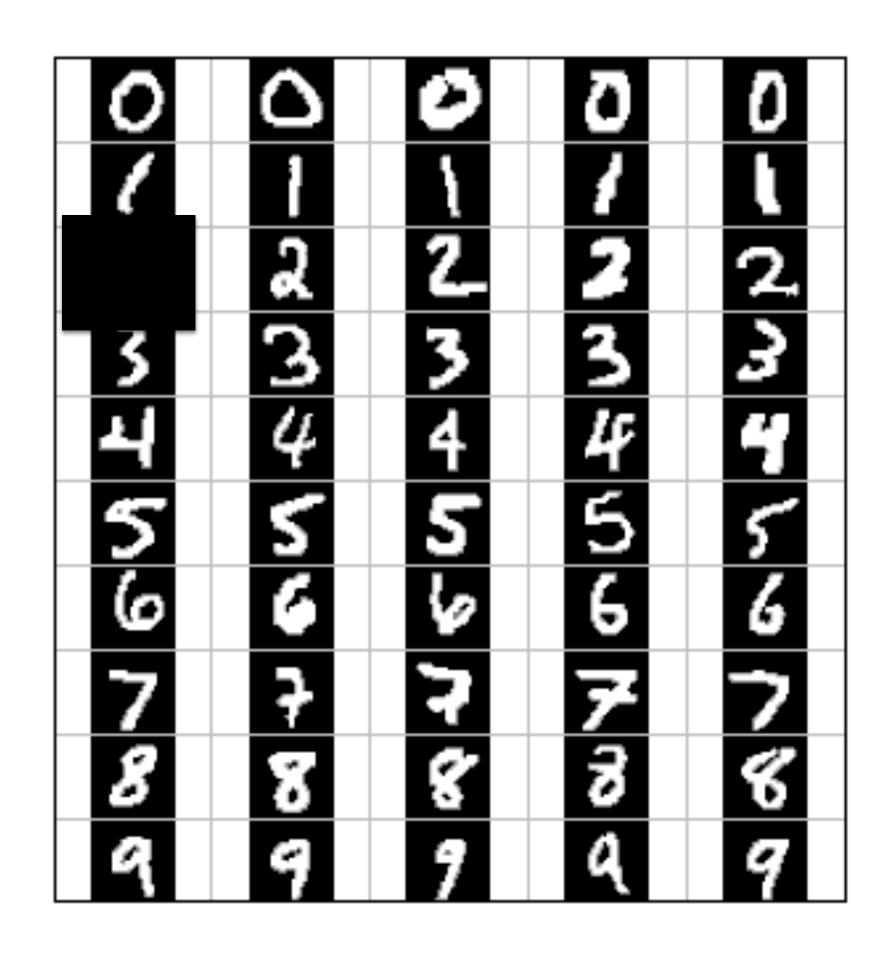


training data





training data

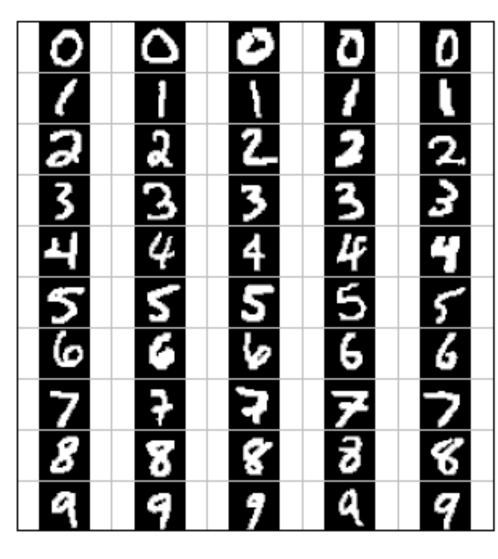




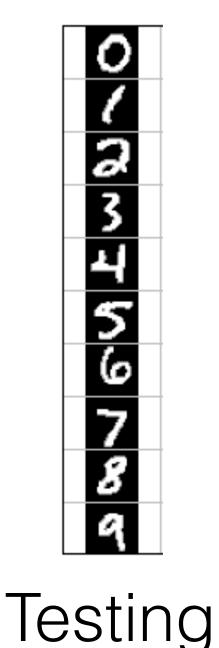
training data

# How Many Folds?

- What are the pros and cons of leave-one-out cross-validation?
- We usually train on N-1 folds and test on 1 fold. What are pros and cons of doing the inverse: train on 1 fold and test on N-1 folds?



Training



# Testing versus Validation

- Best practice for experiments:
  - Hold out test set completely hidden from training
  - Use validation on training data for model (or parameter) selection
  - Evaluate on held-out test data

#### Model Selection via Validation

- Measure performance on held-out training data
  - Simulate testing environment
- Rotate folds of held-out subsets
- Can even hold out one at a time: leave-one-out validation
- Use (cross) validation performance to tune extra parameters

# Summary

- Types of machine learning
- Complexity, overfitting, bias
- Validation, cross-validation