Probabilistic Graphical Models and Bayesian Networks

Artificial Intelligence Bert Huang Virginia Tech

Concept Map for Segment

Probabilistic Graphical Models

Probabilistic Time Series Models

Particle Filters

(Neural Networks)



- Probabilistic graphical models
- Bayesian networks
- Inference in Bayes nets

Outline

Probabilistic Graphical Models

- PGMs represent probability distributions
- They encode conditional independence structure with graphs
- They enable graph algorithms for inference and learning

Probability Identities

- Random variables in caps (A)
 - values in lowercase: A = a or just a for shorthand

•
$$P(a | b) = P(a, b) / P(b)$$

- P(a, b) = P(a | b) P(b)
- P(b | a) = P(a | b) P(b) / P(a)

conditional probability

joint probability





Probability via Counting





P(circle, red)





Probability via Counting



8





2/3

Probability via Counting

2	
	3
1	

P(circle | red) = P(circle, red) / P(red)

3/8 2/8

8



2/3

Probability via Counting

	2	
		3
	1	

P(circle | red) P(red) = P(circle, red) 3/8 2/8

8

Probability Identities

- Random variables in caps (A)
 - values in lowercase: A = a or just a for shorthand
- P(a | b) = P(a, b) / P(b)
- P(a, b) = P(a | b) P(b)
- P(b | a) = P(a | b) P(b) / P(a)





Bayesian Networks

P(R, W, S, C) = P(R) P(C) P(W | C, R) P(S | W)P(X | Parents(X))





 Each variable is conditionally independent of its non-descendents given its parents



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- Each variable is conditionally independent of its non-descendents given its parents
- Each variable is conditionally independent of any other variable given its Markov blanket
 - Parents, children, and children's parents



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Inference

- Given a Bayesian Network describing P(X, Y, Z), what is P(Y)
 - First approach: enumeration

P(R, W, S, C) = P(R) P(C) P(W | C, R) P(S | W) $P(r|s) = \sum \sum P(r, w, s, c) / P(s)$ W С $P(r|s) \propto \sum \sum P(r)P(c)P(w|c,r)P(s|w)$ С W $P(r|s) \propto P(r) \sum P(s|w) \sum P(c)P(w|c,r)$ W

С

Second Approach: Variable Elimination $P(r|s) \propto \sum P(r) P(r) P(c) P(w|c,r) P(s|w)$ W C $f_C(w) = \sum P(c)P(w|c,r)$

 $P(r|s) \propto \sum P(r)P(s|w)f_c(w)$ W

P(Y)?W X Z $f_w(x) = \sum P(w)P(x|w)$ $P(Y) = \sum \int f_w(x) P(Y|x) P(z|Y)$ X Z $f_{X}(Y) = \sum f_{w}(x)P(Y|x)$ X

P(W, X, Y, Z) = P(W)P(X|W)P(Y|X)P(Z|Y)

$P(Y) = \sum \sum \sum P(w)P(x|w)P(Y|x)P(z|Y)$

 $P(Y) = \sum f_x(Y)P(z|Y)$



 $(w) \rightarrow (x) \rightarrow (z)$ $P(Y) = \sum \sum \sum P(w)P(x|w)P(Y|x)P(z|Y)$ W X Z $f_w(x) = \sum P(w)P(x|w)$ $P(Y) = \sum \int f_w(x) P(Y|x) P(z|Y)$ X Z $P(Y) = \sum f_x(Y)P(z|Y)$ $f_{X}(Y) = \sum f_{w}(x)P(Y|x)$ X



- irrelevant to the query
- Iterate: \bullet
 - choose variable to eliminate
 - sum terms relevant to variable, generate new factor
 - until no more variables to eliminate
- Exact inference is #P-Hard
 - in tree-structured BNs, linear time (in number of table entries)

Variable Elimination

• Every variable that is not an ancestor of a query variable or evidence variable is

Learning in Bayes Nets

- Super easy!
- Estimate each conditional probability by counting