

CS4254

Computer Network Architecture and Programming

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Threads

Threads

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Outline

- Threads (Chapter 26)
 - Introduction
 - Basic Thread Functions
 - TCP echo client using threads
 - TCP Echo Server using threads
 - Thread Synchronization

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Introduction ^{1/4}

- Problems with **fork** approach for concurrency
 - Expensive
 - ✓ Memory copied from parent to child
 - ✓ All descriptors are duplicated in the child
 - ✓ Can be implemented using *copy-on-write* (don't copy until child needs own copy)
 - IPC (Inter-process communication) required to pass information between parent and child after fork
- Threads can help!!

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Introduction ^{2/4}

- Threads
 - **Advantages**
 - ✓ Lightweight process
 - ✓ Thread creation can be 10-100 times faster than process creation
 - ✓ Lower context-switching overhead
 - ✓ All threads within a process share same global memory
 - ✓ POSIX threads standard
 - ❑ *Pthreads* library
 - ❑ supported by Linux and is portable to most UNIX platforms
 - ❑ Has been ported to Windows

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Introduction 3/4

- **Threads**

- **Disadvantages**

- ✓ Global variables are shared between threads → Inadvertent modification of shared variables can be disastrous (need for concurrency control)
- ✓ Many library functions are not *thread-safe*.
 - ❑ Library functions that return *pointers to internal static arrays* are not thread safe
 - ❑ To make it thread-safe → caller allocates space for the result and passes that pointer as argument to the function
- ✓ Lack of robustness: If one thread crashes, the whole application crashes

Introduction 4/4

- **Threads**

- **State**

- ✓ Threads within a process share global data: process instructions, most data, descriptors, etc, ...
 - ❑ File descriptors are shared. If one thread closes a file, all other threads can't use the file
- ✓ Each thread has its own stack and local variables
- ✓ I/O operations block the calling thread.
- ✓ Some other functions act on the whole process. For example, the **exit()** function terminates the entire process and all associated threads.

Basic Thread Functions 1/6

- **pthread_create** function

```
#include <pthread.h>
int pthread_create (pthread_t * tid, const pthread_attr_t *attr, void
>(*func) (void*), void *arg);
//Returns 0 if OK, positive Exxx value on error
```

- When a program is started, single thread is created (main thread). Create more threads by calling **pthread_create()**
- **pthread_t** is often an unsigned int. returns the new thread ID
- **attr**: is the new thread attributes: priority, initial stack size, daemon thread or not. To get default attributes, pass as NULL
- **func**: address of a function to execute when the thread starts
- **arg**: pointer to argument to function (for multiple arguments, package into a structure and pass address of structure to function)

Basic Thread Functions 2/6

- **pthread_create** function

Example

```
void * func (void *);           //function prototype
pthread_t tid;                  //to hold thread ID
```

```
pthread_create (&tid, NULL, func, NULL);
```

```
void * func (void * arg)
{
}
```

Basic Thread Functions ^{3/6}

- **pthread_join** function

```
#include <pthread.h>
```

```
int pthread_join (pthread_t tid, void ** status);
```

```
//Returns 0 if OK, positive Exxx value on error
```

- Wait for a given thread to terminate (similar to **waitpid()** for Unix processes)
- Must specify thread ID (**tid**) of thread to wait for
- If **status** argument non-null
 - Return value from thread (pointer to some object) is pointed to by **status**

Basic Thread Functions ^{4/6}

- **pthread_self** function

```
#include <pthread.h>
```

```
pthread_t pthread_self (void);
```

```
//Returns thread ID of calling thread
```

- similar to **getpid()** for Unix processes

Basic Thread Functions ^{5/6}

- **pthread_detach** function

```
#include <pthread.h>
```

```
int pthread_detach (pthread_t tid);
```

```
//Returns 0 if OK, positive Exxx value on error
```

- A thread is either *joinable* (default) or *detached*
- When a joinable thread terminates → thread ID and exit status are retained until another thread calls **pthread_join**
- When a detached thread terminates → all resources are released and can not be waited for to terminate
- **Example** : **pthread_detach (pthread_self());**

Basic Thread Functions ^{6/6}

- **pthread_exit** function

```
#include <pthread.h>
```

```
void pthread_exit (void * status);
```

```
//Does not return to caller
```

- If thread not detached, thread ID and exit status are retained for a later **pthread_join** by another thread in the calling process
- Other ways for a thread to terminate
 - ✓ Function that started the thread terminates, with its return value being the exit status of the thread
 - ✓ **main** function of process returns or any thread calls **exit**. In such case, process terminates including any threads

TCP Echo Client using Threads

- Recode `str_cli` function using threads
- Source code in `threads/strclithread.c`
 - Can test using `threads/tcpcli01.c`
 - `tcpcli01.c` uses `tcp_connect` function introduced in section 11.12
 - ✓ Need to pass host name and service
 - Can also test by `threads/tcpcli01_plain.c` → Pass server's IP address
- If server terminates prematurely
 - `Readline` function returns 0 and `str_cli` function terminates
 - `main` function terminates calling `exit` → terminate all threads
- Alternative to using global data for threads to share?
 - See `threads/strclithread_args.c`, test with `threads/tcpcli01_plain_args.c`

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TCP Echo Server using Threads ^{1/2}

- One thread per client instead of one child process per client
- Source code in `threads/tcpserv01.c`
- Uses `tcp_listen` function introduced in section 11.13
- Main processing loop

```
for (;){
    len = addrlen;
    connfd = Accept(listenfd, cliaddr, &len);
    Pthread_create(&tid, NULL, &doit, (void *) connfd);
}
```

 - The casting `(void*) connfd` is OK on most Unix implementations (size of an integer is <= size of a pointer)
 - Is there an alternative approach?

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TCP Echo Server using Threads ^{2/2}

- If we pass the address of `connfd`, what can go wrong?

```
for (;){
    len = addrlen;
    connfd = Accept(listenfd, cliaddr, &len);
    Pthread_create(&tid, NULL, &doit, &connfd);
}
```
- A more correct approach would be to allocate space for the connected descriptor every time before the call to `accept`

```
for (;){
    len = addrlen;
    iptr = Malloc(sizeof(int));
    *iptr = Accept(listenfd, cliaddr, &len);
    Pthread_create(&tid, NULL, &doit, iptr);
} // source code in threads/tcpserv02.c
```

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Thread Synchronization: Mutex

- How can a thread ensure that access/updates to shared variables are atomic?
- How can a thread ensure that it is the only thread executing some critical piece of code?
 - Need a mechanism for thread coordination and synchronization
 - **semaphores** and **mutex** calls
- Mutex: *Mutual Exclusion*
 - Threads can create a **mutex** and initialize it. Before entering a critical region, lock the **mutex**.
 - Unlock the **mutex** after exiting the critical region
- See examples in `threads/example01.c` and `threads/example02.c`

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Thread Synchronization: Semaphores

- A **mutex** allows one thread to enter a critical region
- A **semaphore** can allow some N threads to enter a critical region
 - Used when there is a limited (but more than 1) number of copies of a shared resource
- Can be dynamically initialized
 - Thread calls a semaphore **wait** function before it enters a critical region
- Semaphore is a generalization of a **mutex**

Thread Synchronization: Condition Variables ^{1/2}

- A condition variable is only needed where
 - A set of threads are using a **mutex** to provide mutually exclusive access to some resource
 - Once a thread acquires the resource, it needs to wait for a particular condition to occur
- If no condition variables are available
 - Some form of *busy waiting* in which thread repeatedly acquires the **mutex**, tests the condition, and then releases the **mutex** (wasteful solution)
- A condition variable allows a thread to release a **mutex** and block on a condition atomically

Thread Synchronization: Condition Variables ^{2/2}

- Acquire a **mutex**
- Call **pthread_cond_wait** specifying both a condition variable and the mutex being held
- Thread blocks until some other thread signals the variable
- Two forms of signaling
 - Allow one thread to proceed, even if multiple threads are waiting on the signaled variable
 - ✓ OS simultaneously unblocks the thread and allows the thread to reacquire the **mutex**
 - Allow all threads that are blocked on the variable to proceed
- Blocking on a condition variable does not prevent others from proceeding through the critical section, another thread can acquire the **mutex**