#### Server Design

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### Topics

- Types of servers
- Server algorithms
  - Iterative, connection-oriented servers
  - Iterative, connectionless servers
  - Iterative, connectionless servers
  - Concurrent, connection-oriented servers
- Server design issues

Server examples based on BSD-compatible socket functions and POSIX Threads.

### Need for Concurrency in Servers

#### • A simple server

- Server creates a socket, binds address, and makes it passive
- Server accepts a connection, services the request, the connection is closed, and this is repeated indefinitely
- Simple server is inadequate for most applications since the request may take arbitrarily long to service

Other clients are blocked from service

#### **Concurrent versus Iterative Servers**

- An *iterative* server services one request at a time
- A *concurrent* server services multiple requests at the same time
  - The actual implementation may or may not be concurrent
  - More complex than iterative servers

### Three Dimensions of Server Design

#### Iterative versus concurrent

- Truly a server design issue as it is independent of the application protocol
- Connection-oriented versus connectionless
  - Usually constrained by the application protocol
- Stateless versus stateful
  - Usually constrained by the application protocol

#### Four Classes of Servers



#### Concurrent, connection-oriented is the most common server design

### Iterative, Connection-Oriented (1)

#### 1) Create a socket

- sock = socket( PF\_INET, SOCK\_STREAM, 0 )

#### 2) Bind to well-known address

- bind( sock, localaddr, addrlen )
- For port number, server can use getservbyname( name, protocol )
- For host IP address, "wild card" address is usually used: INADDR\_ANY
- 3) Place socket in passive mode
  - listen( sock, queuelen )
  - Need to establish queue length (maximum is implementation dependent)

# Iterative, Connection-Oriented (2)

#### 4) Accept a connection from a client

- new\_socket = accept( sock, addr, addrlen )
- accept() blocks until there is at least one connection request
- Based on the queue length value in listen(), connection requests may be "accepted" by the operating system and queued to be accepted later by the server with the accept() call
- 5) Interact with client
  - recv( new\_socket, ... )
  - send( new\_socket, ...)

#### Iterative, Connection-Oriented (3)

6) Close connection and return to accept() call (step 4) – close( new\_socket ) new\_sock = accept(...) recv(new\_sock,...) other clients wait send(new\_sock,...) close(new\_sock)

#### Iterative, Connection-Oriented (4)

- Only one connection at a time is serviced by an iterative, connection-oriented server
  - Others wait in queue to be accepted
  - Or, their connection is refused
- TCP provides reliable transport, but there is overhead in making and breaking the connection
  - Simplifies application design
  - At the expense of a performance penalty

### Iterative, Connectionless Server (1)

#### 1) Create socket

- sock = socket( PF\_INET, SOCK\_DGRAM )
- 2) Interact with one or more clients
  - recvfrom(sock, buf, buflen, flags, from\_addr, from\_addrlen)
    - Each subsequent recvfrom() can receive from a different client
    - fromaddr parameter lets server identify the client
  - sendto(sock, buf, buflen, flags, to\_addr, to\_addrlen)
    - to\_addr is usually from\_addr of preceding recvfrom()

# Iterative, Connectionless Server (2) sock=socket(...) recvfrom(sock,...) sendto(sock,...)

- Other clients block while one *request* is processed, not for a full connection time
- UDP is not reliable, but there is no connection overhead

#### Concurrent, Connectionless (1)

- Concurrency is on a per request basis for a connectionless server
- There are two way to achieve concurrency
  - Create a new process, e.g. using fork() or exec()
  - Create a new thread, using pthread\_create()
- "Master" thread uses pthread\_create() to create a "slave" thread for each request

### Concurrent, Connectionless (2)

#### Master

- M1) Create socket
  - sock = socket( PF\_INET, SOCK\_DGRAM )

#### M2) Read request

- recvfrom(sock,...)
- M3) Create thread
  - pthread\_create()
  - Thread knows:
    - IP address and port of client
    - Request information
    - Global data and socket

#### Return to M2

#### Concurrent, Connectionless (3)

Slave

S1) Respond to request

– sendto(sock,...)

S2) Terminate

- pthread\_exit()



### Concurrent, Connectionless (5)

- Requests from multiple clients (or multiple requests from a single client) can be serviced concurrently
  - No long blocking periods
- pthread\_create() does have overhead
  - Thread overhead can dominate if time to respond to request is small
  - Concurrent, connectionless server is a good design choice only if average processing time is long relative to thread overhead
- UDP offers no reliability, has no connection overhead

### Concurrent, Connection-Oriented (1)

- Concurrency is on a per connection basis for a connection-oriented server
  - Depending on application, additional concurrency may also be possible
- There are three ways to achieve concurrency
  - Create a new process -- high overhead
  - Create a new thread -- lower overhead
  - Use apparent concurrency within a single thread
    - Lowest overhead
    - Based on select() call for asynchronous operation

### Concurrent, Connection-Oriented (2)

Master, using thread M1)Create socket - sock = socket( PF INET, SOCK STREAM) M2) Bind address – bind(sock, … ) M3)Put socket in passive mode – listen(sock, …)

### Concurrent, Connection-Oriented (3)

Master, using threads (continued)

#### M4) Accept a new connection

- new\_sock = accept(sock,...)
- M5) Create thread
  - pthread\_create()
  - Thread knows:
    - New socket -- new\_sock
    - Global data

Return to M4

### Concurrent, Connection-Oriented (4)

Slave, using threads S1) Interact with client – recv(new\_sock,...) – send(new\_sock,...) S3) Close socket – close(new\_sock,...) S2) Terminate – pthread\_exit()



### Concurrent, Connection-Oriented (6)

- Clients do not block while other clients are connected
  - One thread per client
  - Could have additional threads per client, but based on particular features of the application
- pthread\_create() has overheads
  - Thread overhead can dominate if connection time is small
  - Concurrent, connection-oriented server is a good design choice only if average client connection time is long relative to thread overhead

### Concurrent, Connection-Oriented (7)

- Except on a true multiprocessor, "concurrency" from threads does not generally increase throughput!
  - Transactions per second do *not* increase
  - Delay for first service and variance for service time do decrease



### Concurrent, Connection-Oriented (8)

- May be able to increase throughput for some applications, e.g. by overlapping disk I/O with processing in the CPU
- TCP provides reliability at the expense of connect/disconnect overhead

### Apparent Concurrency (1)

- 0) Maintain a set of socket descriptors (SOCKETS) using the fd\_set structure
  - Initialize SOCKETS = { } (empty)
- 1) Create socket
  - sock = socket( PF\_INET, SOCK\_STREAM )
  - SOCKETS = { sock }
- 2) Bind address
  - bind(sock, ... )
- 3) Put socket in passive mode
  - listen(sock, ...)

# Apparent Concurrency (2)

- 4) Use select() to determine sockets that have activity (are ready for "service")
   – ret = select(maxfd, rdfds, wrfds, exfds, time)
- 5a) If select() indicates main socket (sock) is ready, accept a new connection
  - new\_sock = accept(sock,...)
  - SOCKETS = SOCKETS È { new\_sock }
- 5b) If select() indicates another socket (ready) is ready
  - recv(ready,...) to read request, and then
  - send(read,...) to send response

Return to step 4



- While another connection is accepted or while one *request* from another client is serviced
- Clients do not wait full connection time

### Apparent Concurrency (4)

- Data can be conveniently (or dangerously) shared between different clients
  - Not easy with multiple threads

# Server Design Factors (1)

#### Time per request

- If high, a multithreaded design is best
- If low, thread overhead may dominate performance and an iterative server or a server using apparent concurrency is best
- Time per connection (connection-oriented)
  - If high, a concurrent (threaded or apparent) server is best
  - If low, an iterative server is best
- Number of active clients
  - If high, concurrent server is best
  - If low, iterative server is best

### Server Design Factors (2)

#### Overhead for thread creation

- Trade-offs for connection time and request response time are relative to thread creation time
- Operating systems with low overhead thread creation increase opportunities to use multithreaded design

Need to share information between clients

- Easier in an iterative server or a server with apparent concurrency
- More complex in a multithreaded server

#### Server Design Factors (3)

- LAN- versus WAN-based application
  - TCP's reliability is more important in a WAN where packet loss and out-oforder delivery is more likely
  - LAN-based applications may be able to provide reliability with less "expense" using UDP than TCP
- Inherent reliability in the application

- May eliminate the need to use TCP

### Simple Deadlock

- Deadlock occurs when
  - Client is blocked waiting on server
  - Server is blocked waiting on client
- Simple example of server deadlock



#### More Subtle Deadlock (1)

#### Deadlock may be much more subtle SERVER CLIENT accept() ← ---> connect() ↓ recv() send(BIG\_BUFFER) ↓ Send() Client blocks at

Server eventually blocks at send() since client never receives 🖄 Client blocks at send() since server is not receiving 送



### Terminating a Connection (1)

- The application protocol determines when a connection should be closed
- Client may know when transaction is done
  - Examples:
    - FTP
    - HTTP 1.1 (persistent connections)
  - A "misbehaving" client can keep connections open, consuming server resources
  - Solutions
    - Time-out for the session (connect, idle, etc.)
    - Trusted clients

### Terminating a Connection (2)

- Even if the server controls connection termination, there may still be problems
  - Operating system maintains connection information for 2<sup>-</sup>MSL (maximum segment life)
    - Allows OS to reject delayed, duplicate packets
    - Uses OS resources
  - Client can make lots of requests and consume resources faster than the server can free them
- Vulnerability to denial of service attacks

# Example: Threaded ECHO Server (1)

 Multiple-threaded concurrent, connection-oriented design



#### Example: Concurrent ECHO Server (2)

#### Operation of concurrent ECHO server

- pthread\_create() called for each new connection
- TCPechod() invoked for each thread
  - recv() and send() repeated until client closes the connection
  - Note that TCPechod() does not call exit() to exit the process if there's an error -- just the thread terminates I.e. the thread calls pthread\_exit.
  - Calling exit will terminate all threads and the process, a bad idea in this case

# Example: Asynch ECHO Server (1)

# • Single-thread concurrent, connection-oriented



# Example: Asynch ECHO Server (2)

- Uses select() call
  - select() indicates which sockets are ready for service
    - Input or connection for ECHO server
  - fd\_set structures record the sets of sockets

```
typedef struct fd_set {
    u_int fd_count;
    SOCKET fd_array[FD_SETSIZE];
}
```

# Example: Asynch ECHO Server (3)

- fd\_set structures manipulated with macros
  - FD\_CLR( fd, set ): remove fd from set
  - FD\_SET( fd, set ): add fd to set
  - FD\_ZERO( set ): empty set
  - FD\_ISSET( fd, set ): test if fd is in set

FD\_ZERO(&afds); // empty afds

FD\_SET(msock, &afds); // add msock

# Example: Asynch ECHO Server (4)

#### select()

- Checks all sockets in sets
  - set for input and connection request
  - set for output
  - set for exceptions
- Blocks until at least one of the sockets is ready or time-out
- Returns with the set changed to contain just the sockets ready for service

select(FD\_SETSIZE, &rfds,
 (fd\_set \*)0, (fd\_set \*)0,
 (struct timeval \*)0)

### Example: Asynch ECHO Server (5)

#### Operation

- Steps through all active sockets and checks to see if socket is ready
- Accepts a new connection and adds to set if master server socket (msock) is ready
- Calls echo() to echo new data if client connection socket is ready
- There may be several sockets ready for service

#### You should now be able to ...

- Identify the three dimensions of server design
- Identify factors and application requirements that affect design choice
- Select server design based on factors application requirements
- Design, implement, and test servers based on the four classes
- Recognize causes of deadlock