Threads, SMP, and Microkernels

Chapter 4
Current View of Process

• Process is a program in execution

• It has
  – Execution environment
    • address space, registers, etc
  – Execution entity
    • Code

• Currently thought of as a singular unit
Current View of a Process: Two Aspects

- *Resource ownership* - process includes a virtual address space to hold the process image

- *Scheduling/execution* - follows an execution path that may be interleaved with other processes

- However, these two characteristics are considered independently by the OS
Rethinking the “Process”

- **Thread** - Unit of dispatching
  - Computational entity +
  - Thread-specific memory

- **Process** – Execution environment
  - Threads
  - Resources available to all threads
    - Memory, files
Multithreading

Multiple threads of execution within a single process

- MS-DOS supports a single thread
- UNIX supports multiple user processes but only supports one thread per process
- Windows, Solaris, Linux, Mach, and OS/2 support multiple threads within a process
Multi-Threading
Process? / Thread?

• Is there a difference in the way we NOW think about them?
  => YES!

• Loosely speaking
  – Thread is the computational unit
  – Process is the resources allocated to the thread, i.e., it’s computational environment,
    • Well… almost
  – Threads execute within, and are considered elements of a process
Process – Earlier Perspective

Process = Computational unit + Computational Environment

Process / Thread – New Perspective
Thread

- Has an execution state (running, ready, etc.)
- Thread context saved when not running
- Has an execution stack
- Has some per-thread static storage for local variables

- Access to the memory and resources of its process
  - all threads of a process share this
Process

• Have a virtual address space which holds the process image
  – Process Control Block
  – User address space
    • Thread accessible
    – Thread + thread components *

• Has protected access to processors, other processes, files, and I/O resources
  – Viz-a-viz the OS
Benefits of Threads

- Takes less time to create a new thread than a process
- Less time to terminate a thread than a process
- Less time to switch between two threads within the same process
- Since threads within the same process share memory and files, they can communicate with each other without invoking the kernel
Uses of Threads in a Single-User Multiprocessing System

- Foreground to background work
- Asynchronous processing
  - Computation + polling
- Speed of execution
  - Computation + I/O
- Modular program structure
  - threads \(\Leftrightarrow\) functions
Process Implications w.r.t Threads

• Suspending a process involves suspending all threads of the process since all threads share the same address space
  – Does blocking a thread stop the process, and subsequently, all other processes?
  • ULT / KLT

• Termination of a process, terminates all threads within the process
Thread States

- States associated with a change in thread state
  - Spawn
    - Spawn another thread
  - Block
  - Unblock
  - Finish
    - Deallocate register context and stacks
Remote Procedure Calls Using a Single Threaded Process

Remote Procedure Calls *Serialized*
Remote Procedure Call Using a Multi-Threaded Process
Multithreading / MultiProcessing
Multithreading / MultiProcessing

Who Should Get The Processor?

Who Should Get The Processor?
User-Level vs. Kernel-Level Threads

• User-Level
  – OS Not aware of their existence

• Kernel-Level
  – OS IS Aware of their existence

• Considerations
  – Who Schedules them for execution?
  – Time Quantum allocation
    • At Process or Thread level?
  – Does Thread block cause Process to block?
User-Level Threads

All thread management is done by the application

The kernel is not aware of the existence of threads
OS: Process B is executing
Application: Thread 2 is executing

Thread 2 requests I/O
OS perceives request from Process
OS Blocks Process B

Note: Thread 2 still in “running” State!
ULTs explicitly issue block or yield to change states
OS: Process B executing
App: Thread 2 executing

Quantum up for Process B
OS: Process B => Ready

Note:
Thread 2 still in running state
OS: Thread B executing
App: Thread 2 executing

Thread 2 intentionally issues block

ULT Lib:
Thread 2 => Blocked State
Thread 1 => Running State

OS: Thread B still running
App: Thread 1 executing
ULKs: The Good, The Bad

• Advantages
  – Thread level switching does not require kernel
    mode privileges (no Mode switching)
  – Scheduling can be application specific
  – ULT’s can run on any OS

• Disadvantages
  – If a thread issues a system-level call that blocks
    thread, then entire Process blocks
  – Cannot take advantage of Multiprocessor
    environment, e.g. SMP
Kernel-Level Threads

Kernel maintains context information for both the process and the threads

Kernel (OS) schedules each thread individually

Windows uses this approach
KLT: The Good, The Bad

• Advantages
  – Thread management done by OS Kernel
  – Scheduling at thread level, not process level
  – In a multiprocessor environment we can have true concurrency
  – If a thread issues a blocking system call, the other threads are not affected

• Disadvantages
  – Transfer of control from one thread to another expensive
    • Two Mode switches (U→K, K→U) : Context switch
User-Level vs. Kernel-Level Threads (Revisited)

- User-Level: OS Not aware of their existence
- Kernel-Level: OS IS Aware of their existence

Considerations
- Who Schedules them for execution?
- Time Quantum allocation
  - At Process or Thread level?
- Does Thread block cause Process to block?
Operational Overhead: ULK vs KLT

Table 4.1  Thread and Process Operation Latencies (μs) [ANDE92]

<table>
<thead>
<tr>
<th>Operation</th>
<th>User-Level Threads</th>
<th>Kernel-Level Threads</th>
<th>Processes</th>
</tr>
</thead>
<tbody>
<tr>
<td>Null Fork</td>
<td>34</td>
<td>948</td>
<td>11,300</td>
</tr>
<tr>
<td>Signal Wait</td>
<td>37</td>
<td>441</td>
<td>1,840</td>
</tr>
</tbody>
</table>

Null Fork: OH of creating a thread
Signal Wait: OH in synchronizing two process/thread together

Implications: KLTs are expensive
Combined Approaches Do Exist

SUN Solaris

Process created with single ULT thread running in user space

Additional ULT threads created in user space

ULTs are then mapped (transformed) into KLT – controlled by application programmer
Categories of Computer Systems

- Single Instruction Single Data (SISD) stream
  - Single processor executes a single instruction stream to operate on data stored in a single memory
- Single Instruction Multiple Data (SIMD) stream
  - Each instruction is executed on a different set of data by the different processors
Categories of Computer Systems

• Multiple Instruction Single Data (MISD) stream
  – A sequence of data is transmitted to a set of processors, each of which executes a different instruction sequence. Never implemented

• Multiple Instruction Multiple Data (MIMD)
  – A set of processors simultaneously execute different instruction sequences on different data sets
Parallel Processors: SIMD / MIMD

- SIMD (single instruction, multiple data stream)
- MIMD (multiple instruction, multiple data stream)

  - Shared-Memory (tightly coupled)
  - Distributed-Memory (loosely coupled)
    - Master/Slave
    - Symmetric Multiprocessors (SMP)
    - Clusters
Symmetric Multiprocessing

- Kernel can execute on any processor
- Kernel can be constructed as multiple processes/threads and execute concurrently
- Typically each processor does self-scheduling from the pool of available process or threads
Memory & Cache Organization

On Processor Chip (fastest)

On Motherboard (Faster than accessing memory)

Concurrent Access (Multiported/Partitioned Memories)
Multiprocessor Operating System Design Considerations

- Kernel processes need to be re-entrant
  - Simultaneous concurrent processes or threads
- Scheduling can be performed by more than one processor
  - Need to avoid conflicts
- Synchronization
  - Facility for mutual exclusion & event sequencing
- Memory management
  - Concurrent access
- Reliability and fault tolerance
  - Graceful degradation if one processor fails
OS “Kernels”

• Monolithic
  – Lacked structure
  – Any procedure could call any other
  – OS/360 1Mill SLOC, Multics 20 Mill Slocs

• Layered
  – Structured, but everything still ran in Kernel mode

• Microkernels
  – Only essential run in Kernel mode
  – Remainder ran as services
Layered Kernel

- Hierarchically organized
- Interaction between adjacent layers
- Most layers executed in Kernel mode
- Modifying code still a problem
- Security difficult (so many interfaces)
Microkernels

- Small operating system core
- Contains only essential core OS functions
- Many traditional OS services now external subsystems
  - Device drivers
  - File systems
- Services implemented as server processes
  - Message passing
Benefits of a Microkernel Organization

- **Uniform interface on request made by a process**
  - Don’t distinguish between kernel-level and user-level services
  - All services are provided by means of message passing
- **Extensibility**
  - Allows the addition of new services
- **Flexibility**
  - New features easily added
  - Existing features can be subtracted
Benefits of a Microkernel Organization

• Portability
  – Changes needed to port the system to a new processor is changed in the microkernel - not in the other services

• Reliability
  – Modular design
  – Small microkernel can be rigorously tested
Benefits of Microkernel Organization

• Distributed system support
  – Message are sent without knowing what the target machine is

• Object-oriented operating system
  – Components are objects with clearly defined interfaces that can be interconnected to form software
Microkernel Design

• Low-level memory management
  – Mapping each virtual page to a physical page frame
Microkernel Components

• Low-level memory management
  – Page fault initiates MK interrupt

• Interprocess communication
  – Port-based communication
  – (sender, message)

• I/O and interrupt management
Windows Processes

- Process & Thread separate concepts
- Threads are kernel-based
- ULT's achieved through library calls
- An executable process may contain one or more threads
- Both processes and thread objects have built-in synchronization capabilities
### Windows Process Object

<table>
<thead>
<tr>
<th>Object Type</th>
<th>Process</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Process ID</td>
</tr>
<tr>
<td></td>
<td>Security Descriptor</td>
</tr>
<tr>
<td></td>
<td>Base priority</td>
</tr>
<tr>
<td></td>
<td>Default processor affinity</td>
</tr>
<tr>
<td></td>
<td>Quota limits</td>
</tr>
<tr>
<td></td>
<td>Execution time</td>
</tr>
<tr>
<td></td>
<td>I/O counters</td>
</tr>
<tr>
<td></td>
<td>VM operation counters</td>
</tr>
<tr>
<td></td>
<td>Exception/debugging ports</td>
</tr>
<tr>
<td></td>
<td>Exit status</td>
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### Windows Thread Object

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<td>Thread context</td>
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<td>Dynamic priority</td>
</tr>
<tr>
<td></td>
<td>Base priority</td>
</tr>
<tr>
<td></td>
<td>Thread processor affinity</td>
</tr>
<tr>
<td></td>
<td>Thread execution time</td>
</tr>
<tr>
<td></td>
<td>Alert status</td>
</tr>
<tr>
<td></td>
<td>Suspension count</td>
</tr>
<tr>
<td></td>
<td>Impersonation token</td>
</tr>
<tr>
<td></td>
<td>Termination port</td>
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<tr>
<td>Set thread information</td>
</tr>
<tr>
<td>Current thread</td>
</tr>
<tr>
<td>Terminate thread</td>
</tr>
</tbody>
</table>
Windows Thread States
Solaris (SUN)

- Process includes the user’s address space, stack, and process control block

- User-level threads
  - Library supported

- Lightweight processes (LWP)
  - Associates ULT with KLT

- Kernel threads
<table>
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<tr>
<th>Traditional Unix</th>
<th>Pure ULT</th>
<th>Multiplexed ULTs</th>
<th>Pure “KLT”s</th>
<th>Combo</th>
</tr>
</thead>
</table>

![Diagram showing the relationship between user, kernel, and hardware layers for different types of Unix systems.](image_url)
Figure 4.16  Process Structure in Traditional UNIX and Solaris [LEWI96]
ULT can be in active state even if LWP is blocked – no computation occurs

Managed through application by calls to library routines

ULT can be in active state even if LWP is blocked – no computation occurs

Managed by OS Kernel

**Figure 4.17** Solaris User-Level Thread and LWP States
Linux Process/Thread

• Classical view
  – Process and Thread viewed as one entity
  – Fork()
    • creates “copy” of parent process
    • Separate address space

• Modern view
  – Multithreading
  – Clone()
    • Shares address space, resources, code
    • Individual thread stack, PSW
Block state - waiting directly on hardware event

Process terminated, task structure still in process table

Block state - waiting on event signaled through interrupt

Linux Process/Thread Model